

PHY2048 Exam 1 Formula Sheet

Vectors

$$\vec{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k} \quad \vec{b} = b_x \hat{i} + b_y \hat{j} + b_z \hat{k} \quad \text{Magnitudes: } |\vec{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2} \quad |\vec{b}| = \sqrt{b_x^2 + b_y^2 + b_z^2}$$

$$\text{Scalar Product: } \vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z \quad \vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta \quad (\theta = \text{angle between } \vec{a} \text{ and } \vec{b})$$

$$\text{Vector Product: } \vec{a} \times \vec{b} = (a_y b_z - a_z b_y) \hat{i} + (a_z b_x - a_x b_z) \hat{j} + (a_x b_y - a_y b_x) \hat{k}$$

$$\text{Magnitude: } |\vec{a} \times \vec{b}| = |\vec{a}| |\vec{b}| \sin \theta \quad (\theta = \text{smallest angle between } \vec{a} \text{ and } \vec{b})$$

Motion

$$\text{Displacement: } \Delta x = x(t_2) - x(t_1) \text{ (1 dimension)} \quad \Delta \vec{r} = \vec{r}(t_2) - \vec{r}(t_1) \text{ (3 dimensions)}$$

$$\text{Average Velocity: } v_{ave} = \frac{\Delta x}{\Delta t} = \frac{x(t_2) - x(t_1)}{t_2 - t_1} \text{ (1 dim)} \quad \vec{v}_{ave} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}(t_2) - \vec{r}(t_1)}{t_2 - t_1} \text{ (3 dim)}$$

$$\text{Average Speed: } s_{ave} = (\text{total distance})/\Delta t$$

$$\text{Instantaneous Velocity: } v(t) = \frac{dx(t)}{dt} \text{ (1 dim)} \quad \vec{v}(t) = \frac{d\vec{r}(t)}{dt} \text{ (3 dim)}$$

$$\text{Relative Velocity: } \vec{v}_{AC} = \vec{v}_{AB} + \vec{v}_{BC} \text{ (3 dim)}$$

$$\text{Average Acceleration: } a_{ave} = \frac{\Delta v}{\Delta t} = \frac{v(t_2) - v(t_1)}{t_2 - t_1} \text{ (1 dim)} \quad \vec{a}_{ave} = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}(t_2) - \vec{v}(t_1)}{t_2 - t_1} \text{ (3 dim)}$$

$$\text{Instantaneous Acceleration: } a(t) = \frac{dv(t)}{dt} = \frac{d^2 x(t)}{dt^2} \text{ (1 dim)} \quad \vec{a}(t) = \frac{d\vec{v}(t)}{dt} = \frac{d^2 \vec{r}(t)}{dt^2} \text{ (3 dim)}$$

Equations of Motion (Constant Acceleration)

$$\begin{aligned} v_x(t) &= v_{x0} + a_x t & v_y(t) &= v_{y0} + a_y t & v_z(t) &= v_{z0} + a_z t \\ x(t) &= x_0 + v_{x0} t + \frac{1}{2} a_x t^2 & y(t) &= y_0 + v_{y0} t + \frac{1}{2} a_y t^2 & z(t) &= z_0 + v_{z0} t + \frac{1}{2} a_z t^2 \\ v_x^2(t) &= v_{x0}^2 + 2a_x(x(t) - x_0) & v_y^2(t) &= v_{y0}^2 + 2a_y(y(t) - y_0) & v_z^2(t) &= v_{z0}^2 + 2a_z(z(t) - z_0) \end{aligned}$$

Newton's Law and Weight

$$\vec{F}_{net} = m\vec{a} \quad (m = \text{mass}) \quad \text{Weight (near the surface of the Earth)} = W = mg \quad (\text{use } g = 9.8 \text{ m/s}^2)$$

Magnitude of the Frictional Force

(μ_s = static coefficient of friction, μ_k = kinetic coefficient of friction)

$$\text{Static: } (f_s)_{\max} = \mu_s F_N \quad \text{Kinetic: } f_k = \mu_k F_N \quad (F_N \text{ is the magnitude of the normal force})$$

Uniform Circular Motion (Radius R, Tangential Speed $v = R\omega$, Angular Velocity ω)

$$\text{Centripetal Acceleration \& Force: } a = \frac{v^2}{R} = R\omega^2 \quad F = \frac{mv^2}{R} = mR\omega^2 \quad \text{Period: } T = \frac{2\pi R}{v} = \frac{2\pi}{\omega}$$

Projectile Motion

(horizontal surface near Earth, v_0 = initial speed, θ_0 = initial angle with horizontal)

$$\text{Range: } R = \frac{v_0^2 \sin(2\theta_0)}{g} \quad \text{Max Height: } H = \frac{v_0^2 \sin^2 \theta_0}{2g} \quad \text{Time (of flight): } t_f = \frac{2v_0 \sin \theta_0}{g}$$

Quadratic Formula

$$\text{If: } ax^2 + bx + c = 0 \quad \text{Then: } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$