

Chapter 9 - 12 review

Center of Mass $m_{com} = \dots$, $ma = F$

Momentum: $p = mv$, $dp = Fdt$, *conservation*

Collisions: using momentum and kinetic energy conservation

Rotational kinematics

Moment of inertia $I = \dots$, parallel axis theorem $I = I_{com} + mh^2$

Torque $\tau = r \times F$, $\tau = I\alpha$

Rolling: ω wrt center = ω wrt touching point

Angular momentum: $L = r \times p$, $dL = \tau dt$, *conservation*

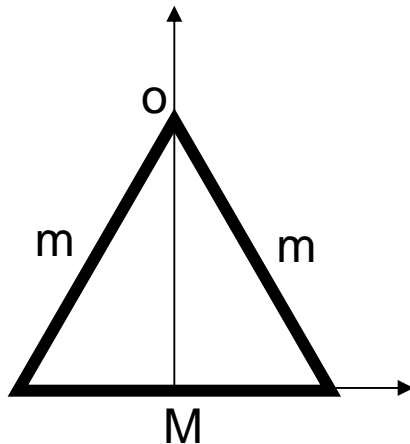
Using angular momentum conservation

Gyroscope precession

Equilibrium

Finding COM, Moment of Inertia

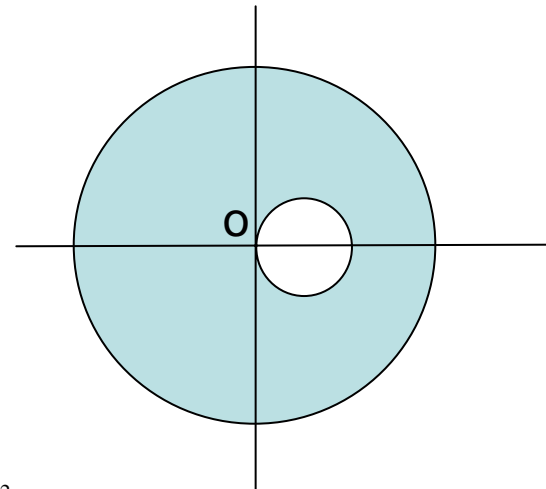
- COM: $\vec{r}_{com} = \frac{1}{m_{TOT}} \sum m_i \vec{r}_i$
- Use symmetry
- Break up object in simpler parts



$$y_{com} = \frac{2m}{M+2m} \frac{\sqrt{3}L}{4}$$

$$I_0 = 2 \left(\frac{1}{12} mL^2 + m \left(\frac{L}{2} \right)^2 \right) + \left(\frac{1}{12} ML^2 + M \left(\frac{\sqrt{3}L}{2} \right)^2 \right)$$

- Moment of Inertia: $I = \sum m_i r_i^2$
- Use parallel axis theorem
- Break up object in simpler parts



$$x_{com} = -\frac{r^2}{R^2 - r^2} r$$

$$I_0 = \frac{1}{2} MR^2 - \left(\frac{1}{2} mr^2 + mr^2 \right) = \frac{1}{2} (\pi R^2 \rho - \pi r^2 \rho) R^2 - \frac{3}{2} (\pi r^2 \rho) r^2$$

Momentum

Gun of mass **M** fires a bullet of mass **m** with velocity **v**.

Find recoiling velocity of gun **u**.

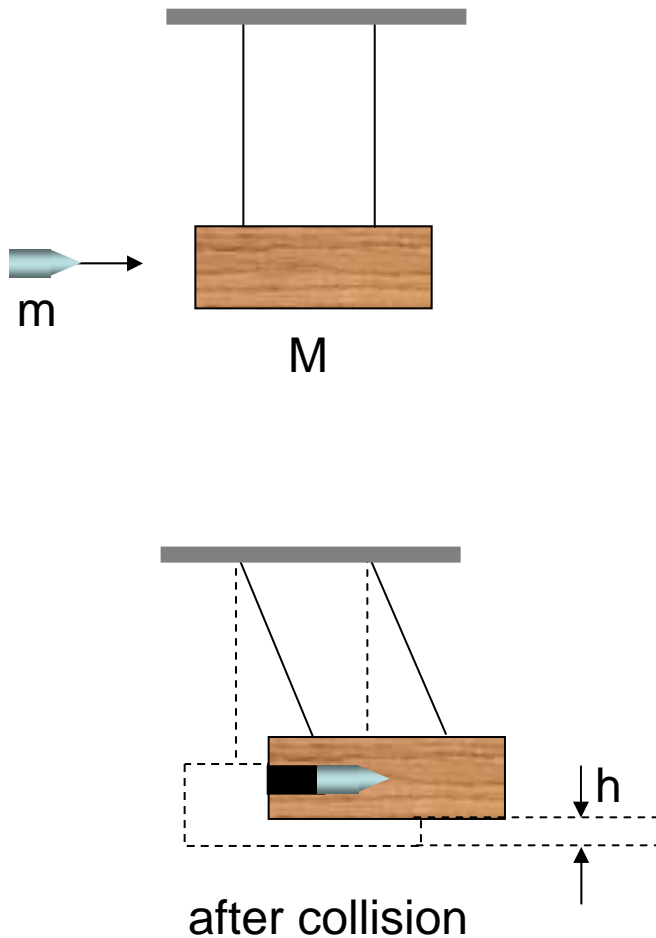
Find the force **F** on your shoulder, if your shoulder deforms by distance **d** as it stops the recoil. Assume that the force, while it acts, is constant.

$$u = \frac{m}{M} v$$

$$F = \left(\frac{mv^2}{2} \right) \frac{1}{d} \frac{m}{M}$$

Inelastic collision

Ballistic pendulum



Given you know the **maximum height** of the block as it swings to the right, find initial **velocity** of a bullet.

Elastic collisions

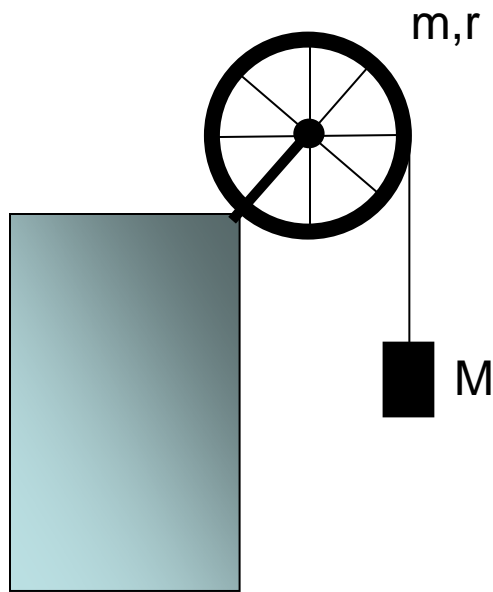
A large ball (#1) of mass **M** and moving with velocity **v** along an x-axis collides elastically with a small ball (#2) of mass **m** at rest.

Find velocities of the two balls after the collision.

$$u_1 = \frac{M - m}{M + m} v$$

$$u_2 = \frac{2M}{M + m} v$$

Rotation

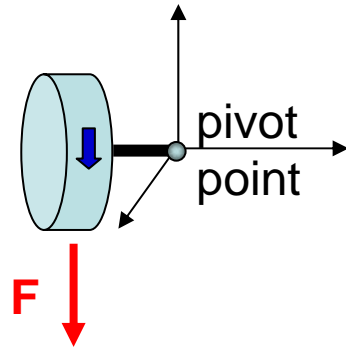


Find tension in the rope T , as the rope wound on the wheel of mass m and radius r unwinds under the weight M

$$T = \frac{Mg}{1 + \frac{Mr^2}{I}} = \frac{Mm}{M + m} g$$

Gyroscope

$$\Omega = \frac{\tau}{L} = \frac{rF_{\perp}}{I\omega}$$



The gyroscope (disk) spins around its axis and is free to rotate around the pivot point.

Direction of **spinning** is shown with **→**
Force is applied downward in plane of the screen

Which way will the gyroscope start precessing?

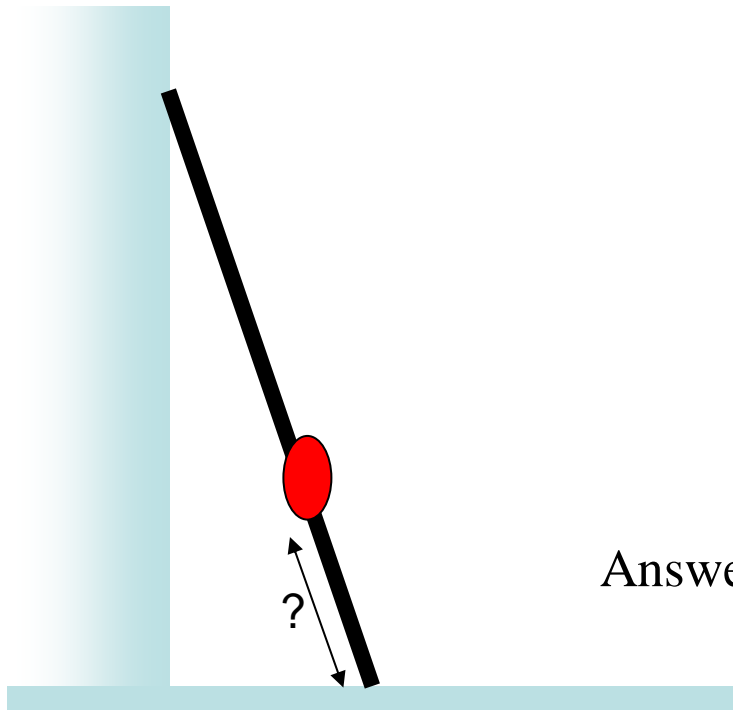
Away from you into the screen (around z-axis)

Equilibrium

A ladder of length L makes an angle 30° with a wall.

Max static friction coefficient between the ladder and the floor $\mu_{\max}=0.25$ and there is no friction between the ladder and the wall.

How far can you climb the ladder before it starts sliding along the floor?



Answer: $l_{\max} = \mu_{\max} \frac{\cos \alpha}{\sin \alpha} L = 0.25\sqrt{3}L \approx 0.4L$