

All on final:

## Chapter 8

Linear  $\rightarrow$  Rotation

$x$	$\theta$
$m$	$I$
$v$	$\omega$
$a$	$\alpha$
$F$	$\tau$

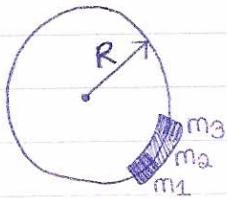
vectors

## Torque &amp; Angular Acceleration

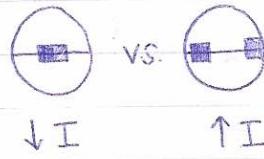
$$\sum \tau = I\alpha, I = \text{moment of inertia}$$

Demo: 2 people twist rods of equal mass - the rod with mass at end is harder to twist because it has a higher moment of inertia

$$\text{For uniform ring: } I = \sum m_i r_i^2 = MR^2$$



Demo:



Depends on distribution  
of the mass and axis  
of rotation.

Other moments of inertia: given on the exam

Look at axis:  
 $m \rightarrow 0$  or  $\infty$   
 $M \rightarrow 0$  or  $\infty$

## Newton's Second Law for Rotation

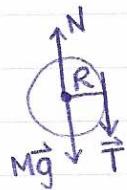
$$\sum \tau = I\alpha$$

$$\sum F = ma$$

$$a = \alpha r = \frac{-mg}{(M/2) + m}$$



and



Accelerating?

$$T - mg = ma \quad -\frac{1}{2}Ma - mg = ma$$

$$RT = \frac{1}{2}MR^2\alpha \quad -RT = \frac{1}{2}MRA$$

CQ2: Torque applied?

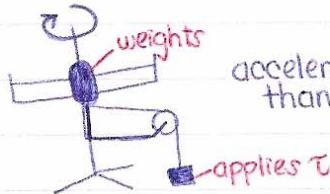
$$\tau = -mgR \quad (= -TR)$$

right hand rule: negative

## Angular Momentum

$$\vec{L} = I\vec{\omega}$$

Demo:



accelerates faster when mass is in the center than when masses are at the ends

$\vec{L}$  conserved no matter what!

$$\text{Impulse: } \sum \tau = \Delta L / \Delta t$$

$$\text{If } \sum \tau = 0, \quad L_i = L_f \quad \text{or} \quad I_i \omega_i = I_f \omega_f$$

Demo: Spin some wheel, give to person sitting in a chair, and as he turns the wheel, the chair will also rotate

Demo: Give weights to person in chair, spin chair - when he's holding weights in close, he'll spin faster than when he's holding his arms out (ie: the ice skater)

$\uparrow \omega, \downarrow I$

In an isolated system, what's conserved?

ME

L

Linear momentum

## Rotational Kinetic Energy

$$KE = \frac{1}{2} I \omega^2$$

$$W_{nc} = \Delta KE_t + \Delta KE_r + \Delta PE$$