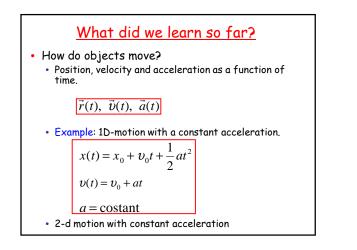
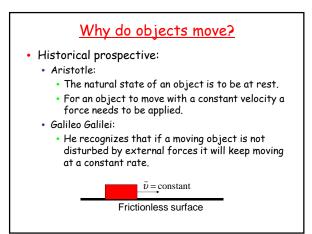
<u>Chapter 4</u>

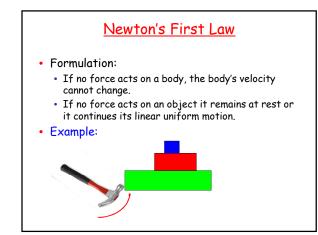
Force and Newton's Laws of Motion

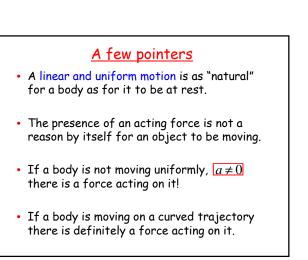
Ch 4 Force and Motion

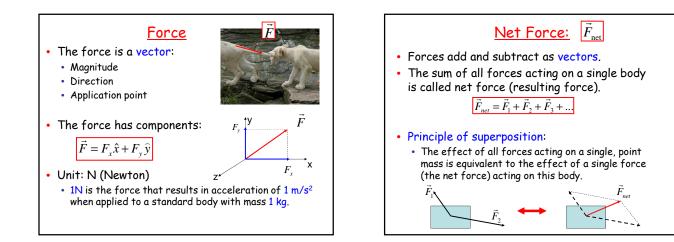
- Summery of Motion
- Force
- Newton's 1st Law
- Reference Frames
- Newton's 2nd Law
- Mass
- Free Body Diagram

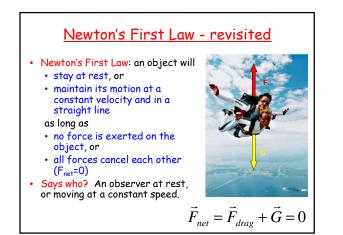


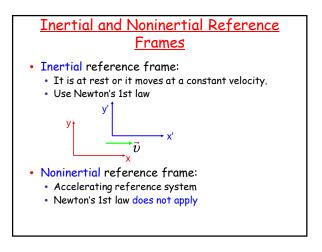










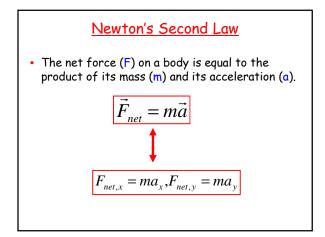


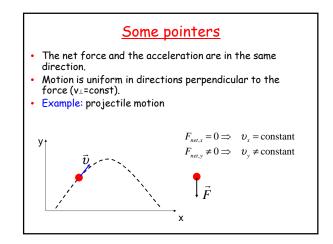
What about the Earth?

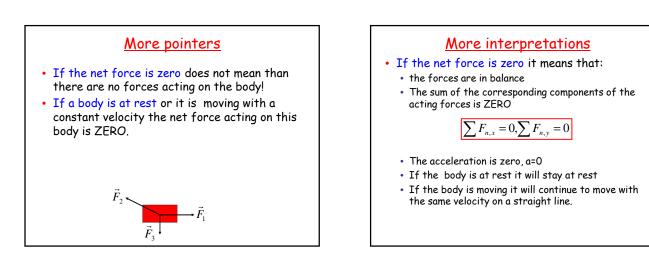
- The Earth is rotating and it is not an inertial reference frame.
- The effect is noticeable only for long range motions (air travel, missile trajectories, winds in the atmosphere)
- For the purpose of this class we will consider the Earth as an inertial reference frame, unless stated otherwise.

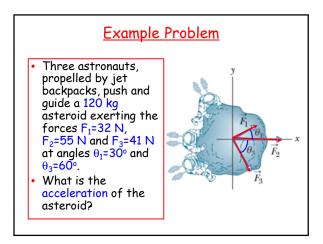
<u>Mass m, M</u>

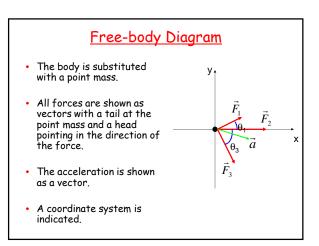
- Experiment: same force acting on different bodies results in different accelerations.
 Definition: an intrinsic characteristic of a body
- that relates the magnitude of a force acting on the body to the resulting acceleration.
- Properties:
 - Scalar
 - Nonnegative
- Additive (example-snowman)
 m,T
 <lim,T
 <lim,T</











$m = 120 kg$ $\vec{E} - m\vec{a}$ y	Γ		<u>Solution</u>
$ \begin{array}{c} F_1 = 32 N \\ F_2 = 55 N \\ F_3 = 41 N \end{array} \qquad \begin{array}{c} F_{net,x} = ma_x \\ F_{net,y} = ma_y \end{array} \qquad \begin{array}{c} \vec{F_1} \\ \vec{F_2} \end{array} $		$F_2 = 55 N$ $F_3 = 41 N$ $\theta_1 = 30^{\circ}$ $\theta_3 = -60^{\circ}$	$\vec{F}_{net,x} = m\vec{a}_{x}$ $F_{net,x} = ma_{x}$ $F_{net,y} = ma_{y}$ $F_{net,y} = F_{1x} + F_{2x} + F_{3x}$ $F_{net,y} = F_{1y} + F_{2y} + F_{3y}$ \vec{F}_{3} $a_{x} = \frac{1}{m}(F_{1}\cos\theta_{1} + F_{2} + F_{3}\cos\theta_{3}) = 0.86m/s^{2}$ $a_{y} = \frac{1}{m}(F_{1}\sin\theta_{1} + 0 + F_{3}\sin\theta_{3}) = -0.16m/s^{2}$