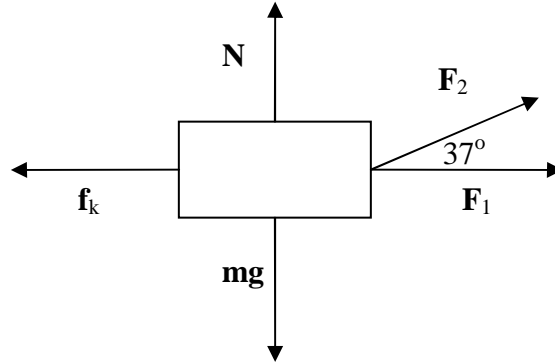


PHY2053 Summer 2012
Exam 2
Solutions

1. The free-body diagram for the block is



Using Newton's second law for the x -components

$$\begin{aligned}\sum F_x &= ma_x \\ F_1 + F_2 \cos 37^\circ - f_k &= 0 \\ f_k &= F_1 + F_2 \cos 37^\circ = (10 \text{ N}) + (15 \text{ N}) \cos 37^\circ = 22 \text{ N}\end{aligned}$$

The work done by kinetic friction

$$W = f_k \Delta r \cos \theta = (22 \text{ N})(6 \text{ m}) \cos 180^\circ = -130 \text{ N}$$

2. Mechanical energy is conserved

$$\begin{aligned}U_1 + K_1 &= U_2 + K_2 \\ mgy_1 + \frac{1}{2}mv_1^2 &= mgy_2 + \frac{1}{2}mv_2^2 \\ gy_1 + \frac{1}{2}v_1^2 &= gy_2 + \frac{1}{2}v_2^2 \\ v_2 &= \sqrt{v_1^2 + 2g(y_1 - y_2)} = \sqrt{(3 \text{ m/s})^2 + 2(9.8 \text{ m/s}^2)(60 \text{ m} - 30 \text{ m})} = 24 \text{ m/s}\end{aligned}$$

3. Mechanical energy is not conserved since the sled stops moving.

$$\begin{aligned}W_{nc} &= \Delta K + \Delta U \\ &= (K_f - K_i) + (U_f - U_i) \\ &= (0 - 0) + (0 - mgy_i) \\ &= -mgy_i = -(45 \text{ kg} + 15 \text{ kg})(9.8 \text{ m/s}^2)(15 \text{ m}) = -8800 \text{ J}\end{aligned}$$

Friction does the dissipative work

$$W_{nc} = f_k \Delta r \cos \theta$$

$$f_k = \frac{W_{nc}}{\Delta r \cos 180^\circ} = \frac{-8800 \text{ J}}{(44 \text{ m})(-1)} = 200 \text{ N}$$

4. The force information gives the force constant for the spring

$$F = kx$$

$$k = \frac{F}{x} = \frac{80 \text{ N}}{0.20 \text{ m}} = 400 \text{ N/m}$$

Mechanical energy is conserved as the ball exits the gun

$$U_1 + K_1 = U_2 + K_2$$

$$\frac{1}{2} kx_1^2 + \frac{1}{2} mv_1^2 = \frac{1}{2} kx_2^2 + \frac{1}{2} mv_2^2$$

$$\frac{1}{2} kx_1^2 + 0 = 0 + \frac{1}{2} mv_2^2$$

$$v_2 = x_1 \sqrt{\frac{k}{m}} = (0.20 \text{ m}) \sqrt{\frac{400 \text{ N/m}}{0.018 \text{ kg}}} = 30 \text{ m/s}$$

5. The work done by the engine increases the car's kinetic energy.

$$W = \Delta K$$

$$= K_f - K_i$$

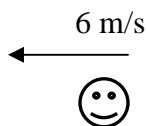
$$= \frac{1}{2} mv_f^2 - \frac{1}{2} mv_i^2$$

$$= \frac{1}{2} (1000 \text{ kg})(40 \text{ m/s})^2 - \frac{1}{2} (1000 \text{ kg})(10 \text{ m/s})^2 = 7.5 \times 10^5 \text{ J}$$

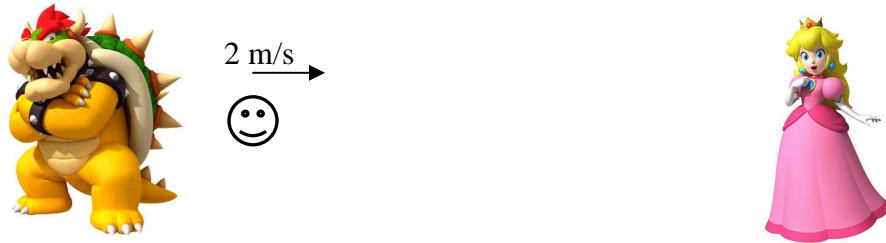
The power output by the engine rate of the work done by the engine

$$P = \frac{W}{t} = \frac{7.5 \times 10^5 \text{ J}}{10 \text{ s}} = 7.5 \times 10^4 \text{ W}$$

6. The force is found from the impulse-momentum theorem. Before the collision



After the collision



The impulse-momentum theorem is

$$\Delta \vec{p} = \vec{F}_{av} \Delta t$$

Since this is a vector equation, we must take components. Since the motion is only along the x -axis, only the x -component is needed.

$$\Delta p_x = F_{av,x} \Delta t$$

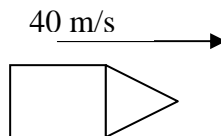
The change in momentum is

$$\Delta p_x = mv_{fx} - mv_{ix} = (1.5 \text{ kg})(2 \text{ m/s}) - (1.5 \text{ kg})(-6 \text{ m/s}) = 12 \text{ kg} \cdot \text{m/s}$$

The average force is

$$F_{av,x} = \frac{\Delta p_x}{\Delta t} = \frac{12 \text{ kg} \cdot \text{m/s}}{0.20 \text{ s}} = 60 \text{ N}$$

7. Linear momentum is conserved since the explosion is an internal force. Before the explosion



$$p_i = mv_i = (15 \text{ kg})(40 \text{ m/s}) = 600 \text{ kg} \cdot \text{m/s}$$

After the explosion



$$p_f = m_1 v_{1f} + m_2 v_{2f}$$

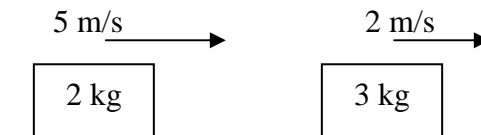
Since linear momentum is conserved,

$$p_i = p_f$$

$$p_i = m_1 v_{1f} + m_2 v_{2f}$$

$$v_{1f} = \frac{p_i - m_2 v_{2f}}{m_1} = \frac{(600 \text{ kg} \cdot \text{m/s}) - (5 \text{ kg})(60 \text{ kg} \cdot \text{m/s})}{10 \text{ kg}} = 30 \text{ m/s}$$

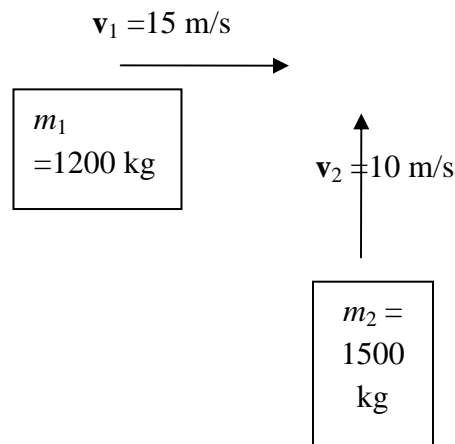
8. Use the equations for a one dimensional elastic collision derived in lecture



$$v_{2f} = \left(\frac{2m_1}{m_1 + m_2} \right) v_{1i} + \left(\frac{m_2 - m_1}{m_1 + m_2} \right) v_{2i}$$

$$= \left(\frac{2(2 \text{ kg})}{2 \text{ kg} + 3 \text{ kg}} \right) (5 \text{ m/s}) + \left(\frac{3 \text{ kg} - 2 \text{ kg}}{2 \text{ kg} + 3 \text{ kg}} \right) (2 \text{ m/s}) = 4.4 \text{ m/s}$$

9. Momentum is conserved in the collision. Before the collision



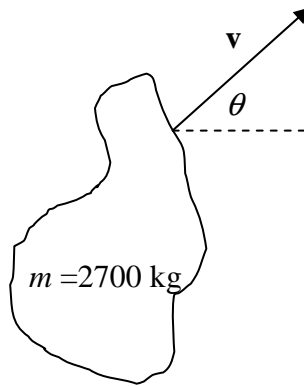
For the x -component

$$p_{ix} = m_1 v_1 = (1200 \text{ kg})(15 \text{ m/s}) = 1.8 \times 10^4 \text{ kg} \cdot \text{m/s}$$

For the y -component

$$p_{iy} = m_2 v_2 = (1500 \text{ kg})(10 \text{ m/s}) = 1.5 \times 10^4 \text{ kg} \cdot \text{m/s}$$

After the collision



For the x -component

$$p_{fx} = mv \cos \theta$$

And the y -component

$$p_{fy} = mv \sin \theta$$

Using the conservation of linear momentum

$$p_{ix} = p_{fx}$$

$$1.8 \times 10^4 \text{ kg} \cdot \text{m/s} = mv \cos \theta$$

And

$$p_{iy} = p_{fy}$$

$$1.5 \times 10^4 \text{ kg} \cdot \text{m/s} = mv \sin \theta$$

There are two equations

$$1.8 \times 10^4 \text{ kg} \cdot \text{m/s} = mv \cos \theta$$

$$1.5 \times 10^4 \text{ kg} \cdot \text{m/s} = mv \sin \theta$$

To solve for v directly, square the equations and add them together.

$$(mv \cos \theta)^2 + (mv \sin \theta)^2 = (1.8 \times 10^4 \text{ kg} \cdot \text{m/s})^2 + (1.5 \times 10^4 \text{ kg} \cdot \text{m/s})^2$$

$$(mv)^2 (\cos^2 \theta + \sin^2 \theta) = 5.49 \times 10^8 \text{ kg}^2 \cdot \text{m}^2/\text{s}^2$$

$$v = \sqrt{\frac{5.49 \times 10^8 \text{ kg}^2 \cdot \text{m}^2/\text{s}^2}{m^2}} = \sqrt{\frac{5.49 \times 10^8 \text{ kg}^2 \cdot \text{m}^2/\text{s}^2}{(2700 \text{ kg})^2}} = 8.7 \text{ m/s}$$

10. The object looks like



The definition of the center of mass is

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$

The 1 subscript refers to the rod and the 2 subscript refers to the additional mass. Solving for m_2 :

$$x_{cm} = \frac{m_1 + m_2}{m_1 + m_2}$$

$$x_{cm} (m_1 + m_2) = m_1 x_1 + m_2 x_2$$

$$m_1 x_{cm} + m_2 x_{cm} = m_1 x_1 + m_2 x_2$$

$$m_2 (x_{cm} - x_2) = m_1 (x_1 - x_{cm})$$

$$m_2 = m_1 \frac{(x_1 - x_{cm})}{(x_{cm} - x_2)}$$

Measuring the locations from the left end of the rod, the location of the rod is $x_1 = 1 \text{ m}$, the location of the added mass is $x_2 = 0$, and the location of the center of mass is $x_{cm} = 0.75 \text{ m}$. So

$$m_2 = m_1 \frac{(x_1 - x_{cm})}{(x_{cm} - x_2)} = (3 \text{ kg}) \frac{(1 \text{ m} - 0.75 \text{ m})}{(0.75 \text{ m} - 0)} = 1.0 \text{ kg}$$

11. The object consists of two parts. The rotational inertia can be decomposed into

$$I = I_{disk} + I_{mass}$$

The rotational inertia of the disk is

$$I_{disk} = \frac{1}{2} m_{disk} R^2 = \frac{1}{2} (3 \text{ kg})(0.6 \text{ m})^2 = 0.54 \text{ kg} \cdot \text{m}^2$$

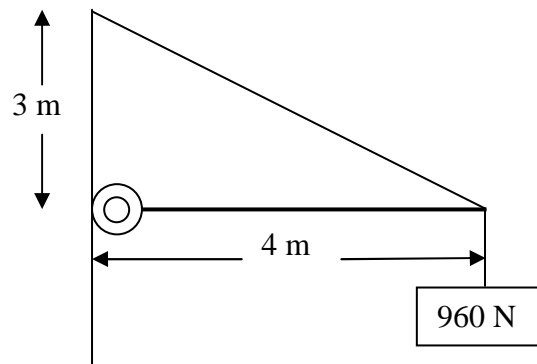
The rotational inertia of the extra mass is

$$I_{disk} = mr^2 = (1 \text{ kg})(0.6 \text{ m})^2 = 0.36 \text{ kg} \cdot \text{m}^2$$

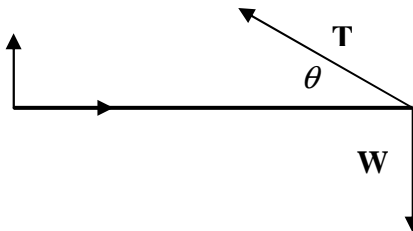
Finally,

$$I = I_{disk} + I_{mass} = 0.54 \text{ kg} \cdot \text{m}^2 + 0.36 \text{ kg} \cdot \text{m}^2 = 0.90 \text{ kg} \cdot \text{m}^2$$

12.



The forces on the beam are



The condition for equilibrium is

$$\sum \tau = 0$$

Taking torques about the left end (the hinge)

$$\sum \tau = 0$$
$$\tau_W + \tau_T = 0$$

The torque due to the weight is clockwise. Its value is

$$\tau_W = -Wr_{\perp W} = -(960 \text{ N})(4 \text{ m}) = 3840 \text{ N} \cdot \text{m}$$

To find the torque due to the tension, we need the angle θ

$$\theta = \tan^{-1}\left(\frac{3 \text{ m}}{4 \text{ m}}\right) = 37^\circ$$

The torque is counterclockwise,

$$\tau_T = +Tr_{\perp T} = T((4 \text{ m}) \sin 37^\circ) = (2.4 \text{ m})T$$

The tension can be found

$$\begin{aligned}\tau_W + \tau_T &= 0 \\ -3840 \text{ N} \cdot \text{m} + (2.4 \text{ m})T &= 0 \\ T &= \frac{3840 \text{ N} \cdot \text{m}}{2.4 \text{ m}} = 1600 \text{ N}\end{aligned}$$

13. The rotational inertia of the hoop is

$$I = MR^2 = (100 \text{ kg})(2 \text{ m})^2 = 400 \text{ kg} \cdot \text{m}^2$$

Its angular acceleration

$$\alpha = \frac{\Delta\omega}{\Delta t} = \frac{(0 - 20 \text{ rad/s})}{200 \text{ s}} = -0.10 \text{ rad/s}^2$$

We don't care about the direction of the acceleration. Drop the minus sign. The torque is

$$\begin{aligned}\sum \tau &= I\alpha \\ \tau &= I\alpha = (400 \text{ kg} \cdot \text{m}^2)(0.10 \text{ rad/s}^2) = 40 \text{ N} \cdot \text{m}\end{aligned}$$

14. The fastest object reaches the bottom first. Use energy to find the fastest. Take position 1 at the top of the ramp and position 2 at the bottom of the ramp.

$$\begin{aligned}K_1 + U_1 &= K_2 + U_2 \\ 0 + mgy &= \left(\frac{1}{2}mv^2 + \frac{1}{2}I\omega^2\right) + 0\end{aligned}$$

The rotational inertia for the shapes can be summarized (like our text does) by

$$I = \beta m R^2$$

For the sphere $\beta = 2/5$, the cylinder $\beta = 1/2$, and the ring $\beta = 1$. Also use $\omega = v/R$ in the energy relation:

$$mgy = \frac{1}{2}mv^2 + \frac{1}{2}\beta mR^2\left(\frac{v}{R}\right)^2$$

$$gy = \frac{1}{2}v^2(1 + \beta)$$

$$v = \sqrt{\frac{2gy}{1 + \beta}}$$

The largest β will be the slowest. The order will be sphere, cylinder, and ring.

15. Angular momentum will be conserved.

$$L_i = L_f$$

$$I_i\omega_i = I_f\omega_f$$

The time for one rotation (T) is related to the angular speed (ω)

$$\omega T = 2\pi$$

$$\omega = \frac{2\pi}{T}$$

Substituting

$$I_i\omega_i = I_f\omega_f$$

$$I_i \frac{2\pi}{T_i} = I_f \frac{2\pi}{T_f}$$

$$T_f = T_i \frac{I_f}{I_i} = (1.8 \text{ s}) \left(\frac{\frac{1}{2}I_i}{I_i} \right) = 0.90 \text{ s}$$

16. No.

17. At the depth of 2 m

$$P_2 = P_1 + \rho g d = (1.01 \times 10^5 \text{ Pa}) + (1000 \text{ kg/m}^3)(9.8 \text{ m/s}^2)(2 \text{ m}) = 1.21 \times 10^5 \text{ Pa}$$

Double that number and find the depth

$$P_2 = P_1 + \rho g d$$

$$d = \frac{P_2 - P_1}{\rho g} = \frac{2(1.21 \times 10^5 \text{ Pa}) - 1.01 \times 10^5 \text{ Pa}}{(1000 \text{ kg/m}^3)(9.8 \text{ m/s}^2)} = 14 \text{ m}$$

18. From the density and the mass the volume is found

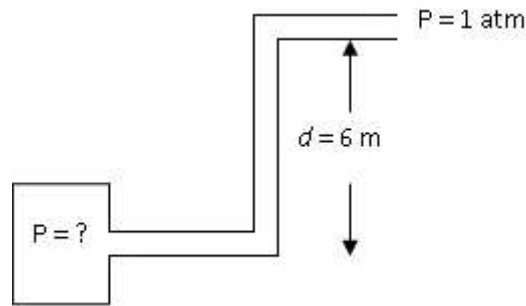
$$\rho = \frac{m}{V}$$

$$V = \frac{m}{\rho} = \frac{15 \text{ kg}}{3000 \text{ kg/m}^3} = 5.0 \times 10^{-3} \text{ m}^3$$

Use Archimedes' principle to find the buoyant force

$$F_b = \rho_f g V = (1000 \text{ kg/m}^3)(9.8 \text{ m/s}^2)(5.0 \times 10^{-3} \text{ m}^3) = 49 \text{ N}$$

19. Call the position at the bottom of the pipe 1 and the position at the top of the pipe 2. Applying Bernoulli's equation



$$P_1 + \rho g y_1 + \frac{1}{2} \rho v_1^2 = P_2 + \rho g y_2 + \frac{1}{2} \rho v_2^2$$

The pipe's diameter does not change so

$$A_1 = A_2$$

By the continuity equation

$$A_1 v_1 = A_2 v_2$$

$$v_1 = v_2$$

Since the end of the pipe is exposed to the atmosphere $P_2 = P_{atm}$. Heights are measured from the lowest point so $y_1 = 0$. Making these substitutions

$$P_1 + \rho g y_1 + \frac{1}{2} \rho v_1^2 = P_2 + \rho g y_2 + \frac{1}{2} \rho v_2^2$$

$$P_1 + 0 + \frac{1}{2} \rho v_1^2 = P_{atm} + \rho g y_2 + \frac{1}{2} \rho v_1^2$$

$$P_1 = P_{atm} + \rho g y_2 = 1.01 \times 10^5 \text{ Pa} + (1000 \text{ kg/m}^3)(9.8 \text{ m/s}^2)(6 \text{ m}) = 1.60 \times 10^5 \text{ Pa}$$

20. Poiseuille's law is

$$\frac{\Delta V}{\Delta t} = \frac{\pi \Delta P / L}{8 \eta} r^4$$

$$\Delta P / L = \left(\frac{\Delta V}{\Delta t} \right) \frac{8\eta}{\pi r^4} = (2.30 \times 10^{-2} \text{ m}^3/\text{s}) \left(\frac{(8)(1.0 \times 10^{-3} \text{ Pa} \cdot \text{s})}{\pi (0.025 \text{ m})^4} \right) = 150 \text{ Pa/m}$$