

Divergence theorem: A corollary.

$$\int (\nabla \cdot \vec{U}) d\tau = \oint \vec{U} \cdot d\vec{a} \rightarrow \textcircled{1}$$

Let $\vec{U} \Rightarrow \vec{U} \times \vec{c}$ which is of course a vector
and \vec{c} is a constant vector.

$$\Rightarrow \int (\nabla \cdot \vec{U}) d\tau \rightarrow \int \nabla \cdot (\vec{U} \times \vec{c}) d\tau \rightarrow \textcircled{2}$$

$$\nabla \cdot (\vec{U} \times \vec{c}) = \vec{c} \cdot (\nabla \times \vec{U}) - \underbrace{\vec{U} \cdot (\nabla \times \vec{c})}_{=0 \because \vec{c} \text{ is constant.}} \rightarrow \textcircled{3}$$

$$\textcircled{1}, \textcircled{2}, \textcircled{3} \Rightarrow \int \vec{c} \cdot (\nabla \times \vec{U}) d\tau = \oint (\vec{U} \times \vec{c}) \cdot d\vec{a} \rightarrow \textcircled{4}$$

$$\boxed{\text{Recall: } (\vec{A} \times \vec{B}) \cdot \vec{E} = (\vec{B} \times \vec{E}) \cdot \vec{A} = \vec{B} \cdot (\vec{E} \times \vec{A})}$$

$$\textcircled{4} \Rightarrow \int \vec{c} \cdot (\nabla \times \vec{U}) d\tau = \oint \vec{c} \cdot d\vec{a} \times \vec{U} \rightarrow \textcircled{5}$$

Taking \vec{c} out of the integrals since \vec{c} is constant

$$\textcircled{5} \Rightarrow \vec{c} \cdot \int (\nabla \times \vec{U}) d\tau = \vec{c} \cdot \oint d\vec{a} \times \vec{U}$$

$$\Rightarrow \int (\nabla \times \vec{U}) d\tau = \oint d\vec{a} \times \vec{U}$$

$$\boxed{\Rightarrow \int (\nabla \times \vec{U}) d\tau = - \oint \vec{U} \times d\vec{a}}$$