

Continuum Mechanics

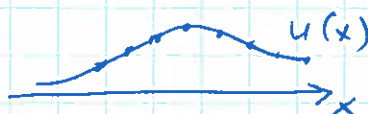
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- a) mechanics of point masses
- b) mechanics of rigid bodies
- c) Continuum mechanics.

discrete to continuum mechanics
diff. equations to partial diff. eq.

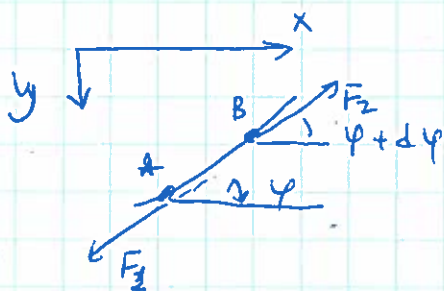
→ WAVES.

Motion of a string:



can approximate first with a discrete system.

masses m_1, \dots, m_n at displacements u_1, \dots, u_n
for $n \rightarrow \infty$ $m \rightarrow \mu(x)$ density $u \rightarrow u(x)$ or $u(x, t)$ displacement.



$$\vec{F}_{net} = \vec{F}_1 + \vec{F}_2$$

↑ tension forces.

$$F_{1x} = T \cos \varphi \quad F_{2x} = T \cos(\varphi + d\varphi)$$

$$F_{xnet} = T \cos(\varphi + d\varphi) - T \cos \varphi \rightarrow 0$$

for small φ .

all motion is in y direction

$$F_{ynet} = T \sin(\varphi + d\varphi) - T \sin \varphi \approx T \cos \varphi d\varphi = T \cos \varphi \frac{\partial \varphi}{\partial x} dx$$

$$F_{ynet} = T \frac{\partial \varphi}{\partial x} dx \rightarrow T \frac{\partial^2 u}{\partial x^2} dx \quad \text{use } \varphi = \frac{\partial u}{\partial x} \text{ - slope.}$$

$\frac{\partial u}{\partial t}$ - velocity $\frac{\partial^2 u}{\partial t^2}$ - acceleration of

a segment of string with mass $\Delta m = \mu dx$

$$\text{So } F_{ynet} = \mu \frac{\partial^2 u}{\partial t^2} dx = T \frac{\partial^2 u}{\partial x^2} dx \quad \text{or.}$$

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad c^2 = T/\mu$$

1D wave equation.

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The Wave Equation the general solution

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \rightarrow -4c^2 \frac{\partial}{\partial \xi} \frac{\partial u}{\partial \eta} \quad \begin{array}{l} \xi = x - ct \\ \eta = x + ct \end{array}$$

$$u(\xi, \eta); \text{ use } \frac{\partial u}{\partial t} = \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial t} + \frac{\partial u}{\partial \eta} \frac{\partial \eta}{\partial t} = -c \left(\frac{\partial u}{\partial \xi} - \frac{\partial u}{\partial \eta} \right)$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial u}{\partial \eta} \frac{\partial \eta}{\partial x} = \frac{\partial u}{\partial \xi} + \frac{\partial u}{\partial \eta}$$

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial \xi} - \frac{\partial u}{\partial \eta} \right) (-c) = c^2 \left[\frac{\partial^2 u}{\partial \xi^2} + \frac{\partial^2 u}{\partial \eta^2} - 2 \frac{\partial^2 u}{\partial \xi \partial \eta} \right]$$

$$c^2 \frac{\partial^2 u}{\partial x^2} = c^2 \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial \xi} + \frac{\partial u}{\partial \eta} \right) = c^2 \left[\frac{\partial^2 u}{\partial \xi^2} + \frac{\partial^2 u}{\partial \eta^2} + 2 \frac{\partial^2 u}{\partial \xi \partial \eta} \right]$$

$$\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = -4c^2 \frac{\partial^2 u}{\partial \xi \partial \eta} = 0 = \frac{\partial}{\partial \xi} \left(\frac{\partial u}{\partial \eta} \right)$$

$$\frac{\partial u}{\partial \eta} = h(\eta) \quad u = \int h(\eta) d\eta + f(\xi)$$

"g(\eta)" "constant" of \eta

$$u = g(\eta) + f(\xi) \quad \text{— general solution.}$$

$$u(x, t) = g(x+ct) + f(x-ct)$$

first consider $u(x, t) = f(x-ct)$

$$t=0: \quad u(x, 0) = f(x) \quad f(x) \text{ shifted by } x_0.$$

$$t=t_0; \quad u(x, t_0) = u(x') = f(x') \quad x = x' + x_0 \quad x_0 = ct$$

$f(x)$ travels to the left with velocity c

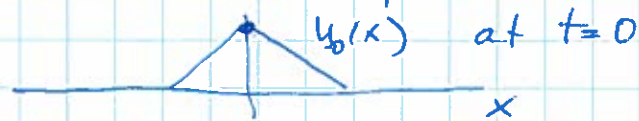
$u = g(x+ct) \rightarrow$ wave that travels to the right.

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Triangular Waves

textbook.
Example 16.1

initial condition

release string at $t=0$ $u(x,0) = u_0(x)$

$$u(x,t) = f(x-ct) + g(x+ct)$$

$$\frac{\partial u}{\partial t} = -c \frac{\partial f}{\partial z} + c \frac{\partial g}{\partial y} = 0 \text{ at } t=0$$

$$\left. \frac{\partial f}{\partial z} \right|_{t=0} = \left. \frac{\partial g}{\partial y} \right|_{t=0} \rightarrow f'(z)_{t=0} = g'(y)_{t=0} = f'(x) = g'(x)$$

$$\text{but } u_0(x) = f(x) + g(x) \rightarrow f(x) = g(x) = \frac{1}{2} u_0(x)$$

at any time t

$$u(x,t) = f(x-ct) + g(x+ct) = \frac{1}{2} u_0(x-ct) + \frac{1}{2} u_0(x+ct)$$

The initial disturbance falls into
2 triangular waves traveling left & right.

Harmonic waves: $f, g = \sin$ & \cos for example $u(x,t) = A \sin(k(x-ct))$ A, k arbitrary constants.

$$u(x,t) = A \sin(kx - \omega t)$$

$$k - \text{wave number} = 2\pi/\lambda \quad \omega = kc \quad \begin{array}{l} \swarrow \\ \text{angular} \\ \text{frequency} \end{array}$$

 λ - wavelength

Superposition of 2 waves:

$$u(x,t) = A \sin(kx - \omega t) + A \sin(kx + \omega t) =$$

$$= 2A \sin(kx) \cos \omega t \quad - \text{standing wave.}$$