

Eigenvectors of Angular Momentum:

We know that $J_+ |j, m\rangle \propto |j, m+1\rangle$
 $J_- |j, m\rangle \propto |j, m-1\rangle$

$$\begin{aligned} \text{and } \langle j, m | J_- J_+ |j, m\rangle &= \hbar^2 (\lambda - \lambda_z^2 - \lambda_z) \\ &= \hbar^2 (j(j+1) - m(m+1)) \\ \langle j, m | J_+ J_- |j, m\rangle &= \hbar^2 (\lambda - \lambda_z^2 + \lambda_z) \\ &= \hbar^2 (j(j+1) - m(m-1)) \end{aligned}$$

Thus, the prefactor is taken to be

$$\begin{aligned} J_+ |j, m\rangle &= \hbar \sqrt{j(j+1) - m(m+1)} |j, m+1\rangle \\ J_- |j, m\rangle &= \hbar \sqrt{j(j+1) - m(m-1)} |j, m-1\rangle \end{aligned}$$

\Rightarrow If we know one of the $|j, m\rangle$ we can find the others for the same j using J_+ and J_- .

For orbital angular momentum

$$L_{\pm} = \pm \hbar e^{\pm i\varphi} \left(\frac{\partial}{\partial \theta} \pm i \cot \theta \frac{\partial}{\partial \varphi} \right)$$

$$L_z = \frac{\hbar}{i} \frac{\partial}{\partial \varphi}$$

Look for solutions

$$L_z Y_{lm} = \hbar m Y_{lm}$$

$$L^2 Y_{lm} = \hbar^2 l(l+1) Y_{lm}$$

$$\frac{\hbar}{i} \frac{\partial}{\partial \varphi} Y_{lm} = \hbar m Y_{lm} \rightarrow Y_{lm}(\theta, \varphi) = f(\theta) e^{im\varphi}$$

Rather than solve using L^2 , use

$$\begin{aligned} L_+ Y_{l, l} = 0 &= \hbar e^{i\varphi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right) f(\theta) e^{il\varphi} \\ &= \hbar e^{i\varphi} \left(\frac{df}{d\theta} + i \cot \theta (il) f \right) e^{il\varphi} \end{aligned}$$

$$\rightarrow \frac{df}{d\theta} = l \cot \theta f = l \frac{\cos \theta}{\sin \theta} f$$

$$\rightarrow f(\theta) \propto \sin^l(\theta)$$

$$\begin{aligned} \text{check: } \frac{d}{d\theta} \sin^l(\theta) &= l \sin^{l-1}(\theta) \cos \theta \\ &= l \frac{\cos \theta}{\sin \theta} \sin^l(\theta). \end{aligned}$$

$$\text{Thus, } Y_{ll}(\theta, \varphi) = C \sin^l(\theta) e^{il\varphi}$$

To get the normalization constant C :

$$\begin{aligned} 1 &= |C|^2 \int d\Omega \sin^{2l}(\theta) \\ &= |C|^2 \int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin \theta \sin^{2l}(\theta) \\ &= |C|^2 2\pi \int_{-1}^1 du (1-u^2)^l, \quad \text{where } u = \cos \theta \\ &\qquad\qquad\qquad \sin^2 \theta = 1 - u^2 \\ &= |C|^2 4\pi \int_0^1 du (1-u^2)^l \\ &= |C|^2 4\pi \frac{2^{2l} (l!)^2}{(2l+1)!} \quad (\text{see next page for details}) \end{aligned}$$

$$\rightarrow |C| = \frac{1}{2^l l!} \sqrt{\frac{(2l+1)!}{4\pi}}$$

The sign or phase convention is

$$Y_{ll}(\theta, \varphi) = \frac{(-1)^l}{2^l l!} \sqrt{\frac{(2l+1)!}{4\pi}} (\sin \theta)^l e^{il\varphi}.$$

Details on evaluating integral:

Integrate by parts:

$$\begin{aligned}
 I_l &= \int_0^1 \underbrace{(1-u^2)^l}_v = \underbrace{u(1-u^2)^l}_{u \cdot v} \Big|_0^1 - \int_0^1 du \, u \cdot l(1-u^2)^{l-1} \cdot (-2u) \\
 &= 2l \int_0^1 du \, u^2 (1-u^2)^{l-1} \\
 &= 2l \int_0^1 du (u^2 - 1 + 1)(1-u^2)^{l-1} \\
 &= 2l (I_{l-1} - I_l)
 \end{aligned}$$

$$\rightarrow I_l (2l+1) = 2l I_{l-1}$$

$$I_l = \frac{2l}{2l+1} I_{l-1}$$

$$\text{Using } I_0 = 1, I_1 = \frac{2}{3}, I_2 = \frac{2^2 \cdot 2 \cdot 1}{5 \cdot 3},$$

$$I_3 = \frac{2^3 \cdot 3 \cdot 2 \cdot 1}{7 \cdot 5 \cdot 3 \cdot 1} = \frac{2^3 3! 2^3 3!}{7!}$$

$$\text{and hence } I_l = \frac{2^{2l} (l!)^2}{(2l+1)!}$$