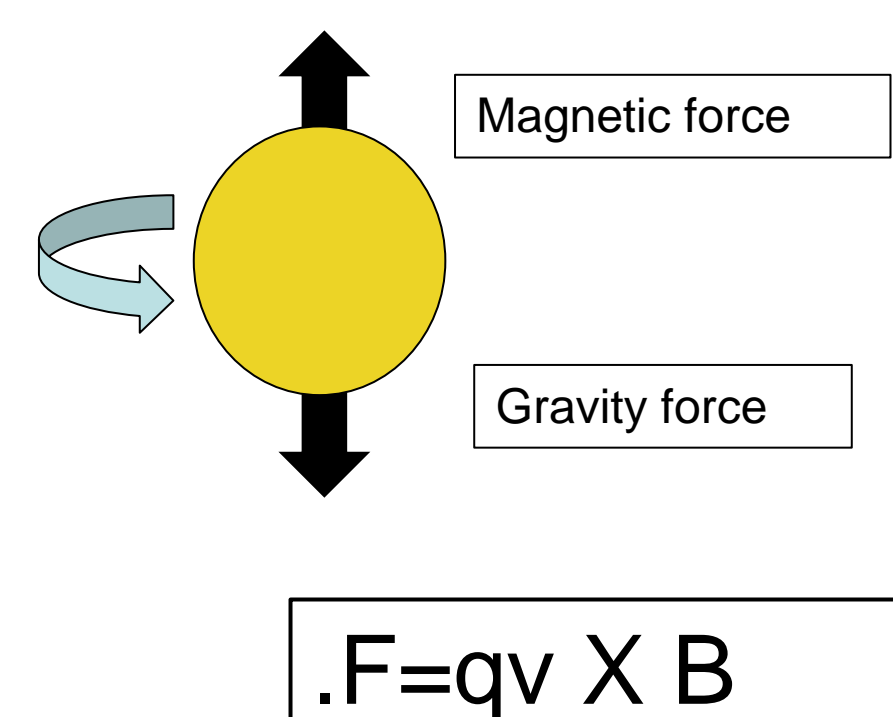


## Introduction

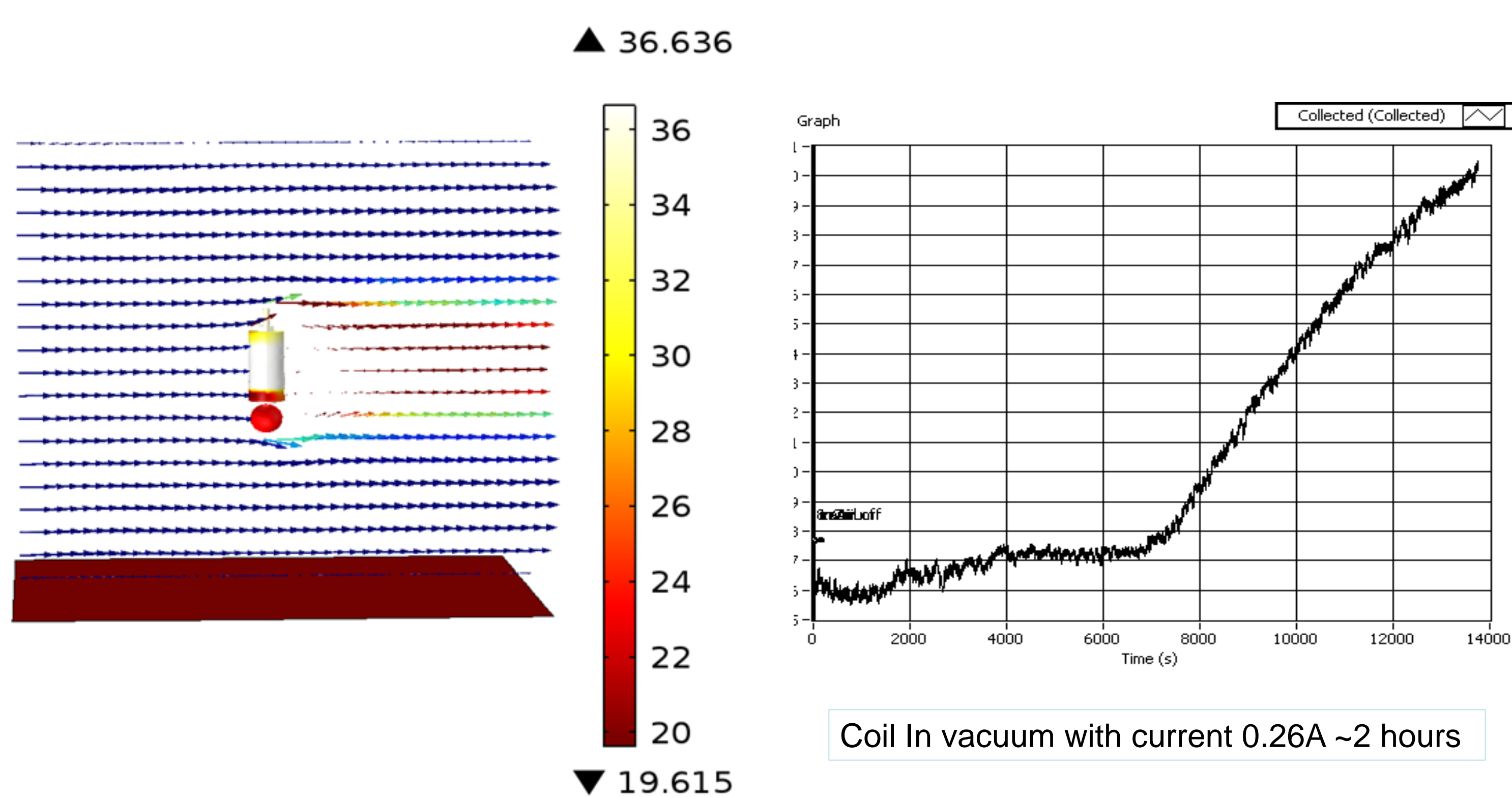


- Design and build a system that can levitate and hold a hollow sphere in vacuum, “simulating zero-g operation”
- Spin the TM by using 4 coils to produce a rotating magnetic field around the equator of the sphere.

## Thermal

### Coil Power Dissipation

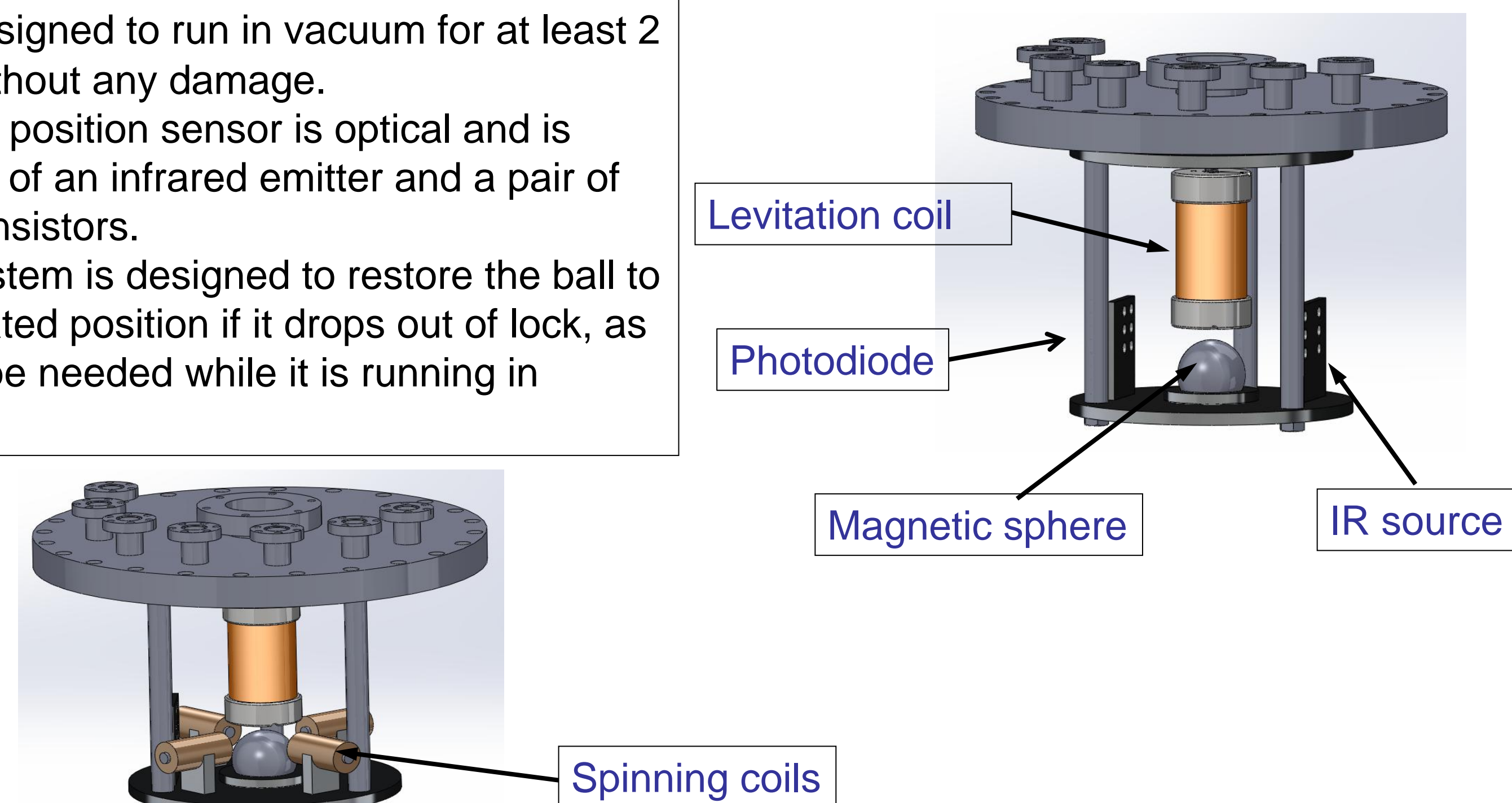
- Used COMSOL to simulate thermal simulation in air and vacuum.
- Install 2 temperature sensor in the coil
- Run the coil in vacuum for about 3 hours.



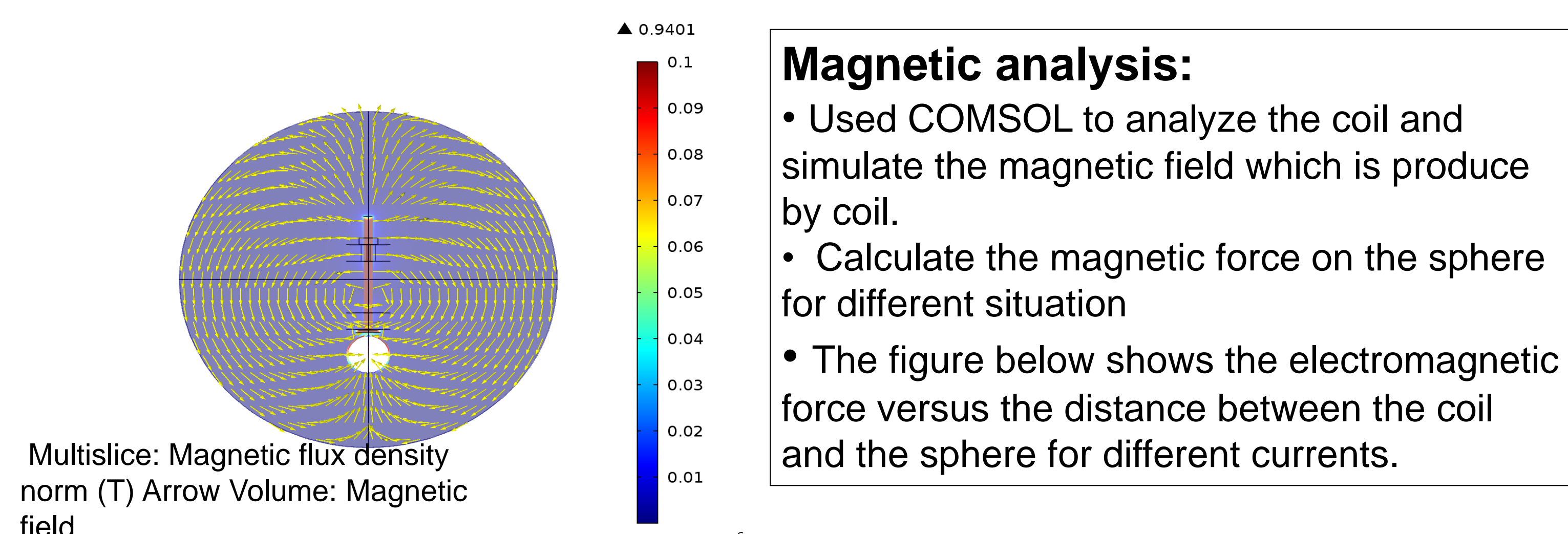
## Design

### System features:

- Coil designed to run in vacuum for at least 2 hours without any damage.
- The ball position sensor is optical and is made up of an infrared emitter and a pair of phototransistors.
- The system is designed to restore the ball to the levitated position if it drops out of lock, as it might be needed while it is running in vacuum.

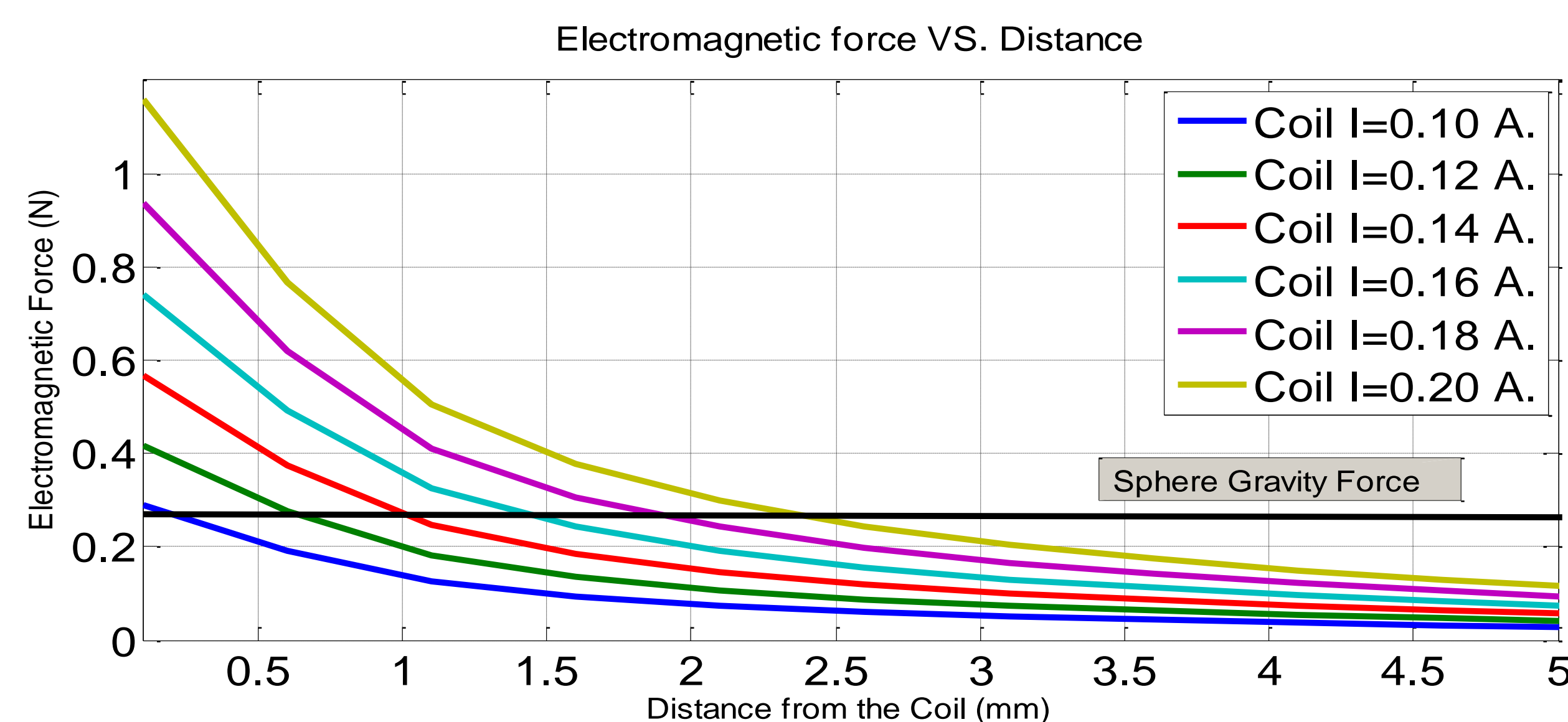


## Simulation



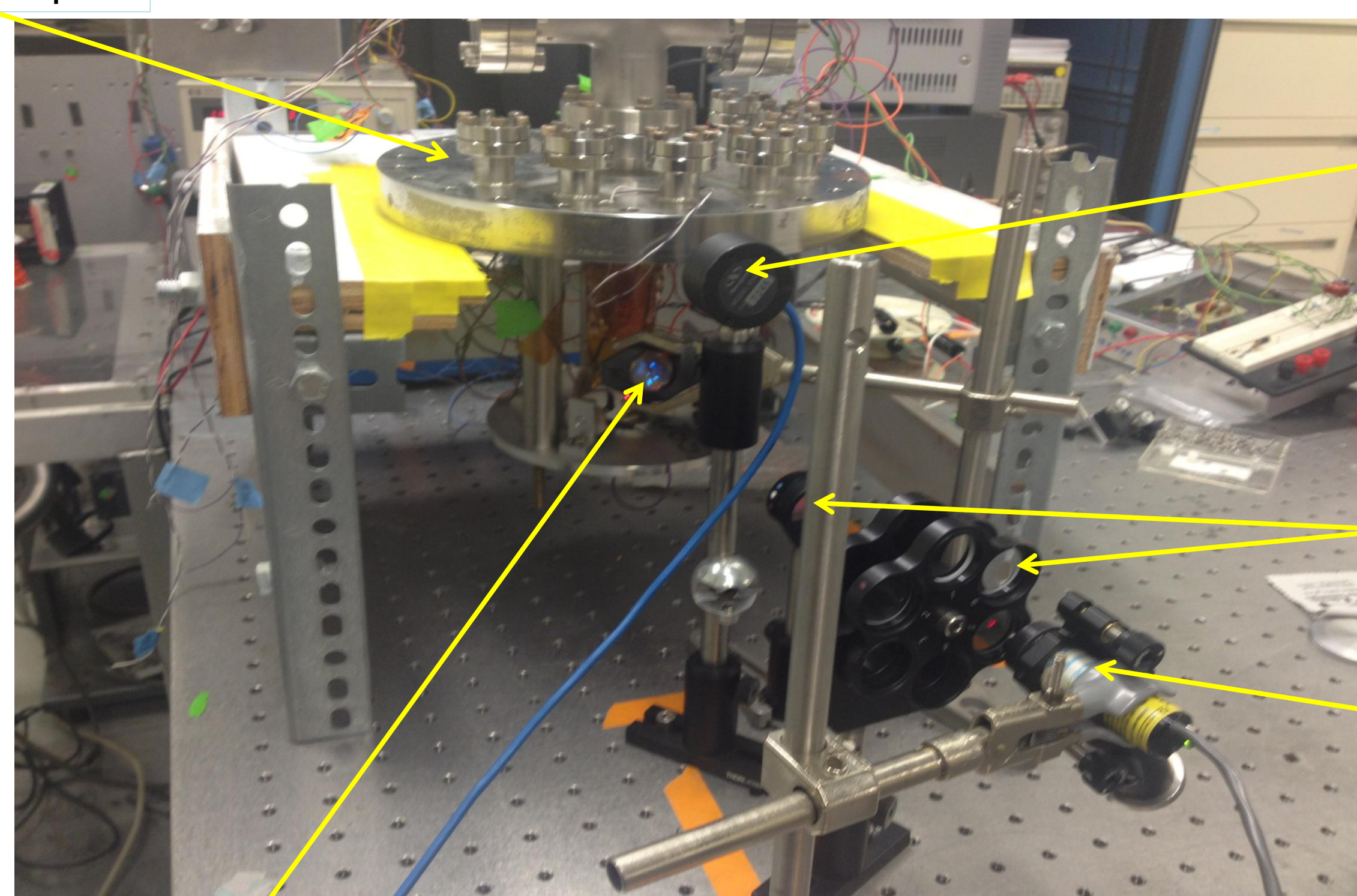
### Magnetic analysis:

- Used COMSOL to analyze the coil and simulate the magnetic field which is produced by coil.
- Calculate the magnetic force on the sphere for different situations
- The figure below shows the electromagnetic force versus the distance between the coil and the sphere for different currents.



## Experiment Levitation

Vacuum top lid



Detector

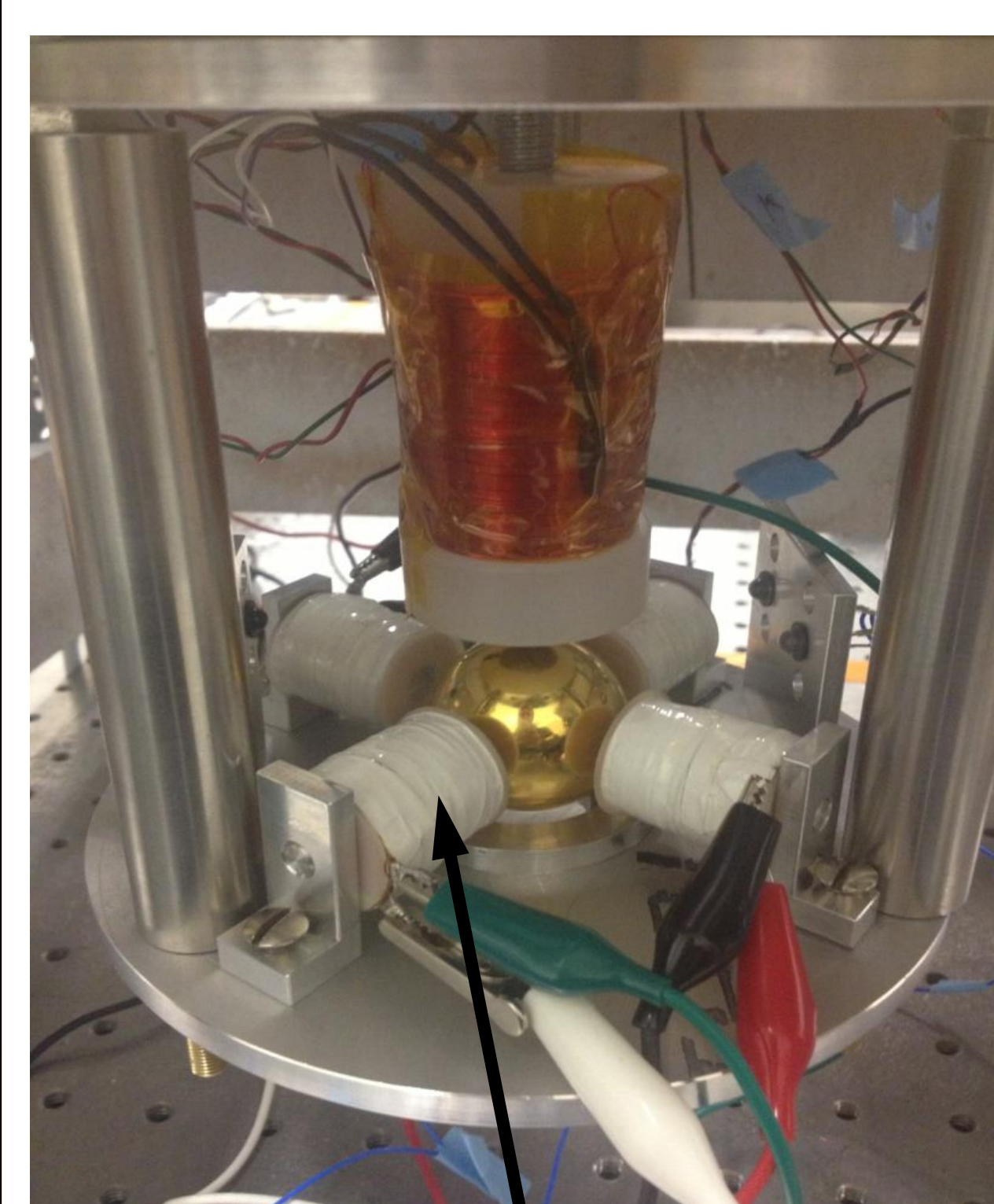
Lens between sphere and laser source

Laser source

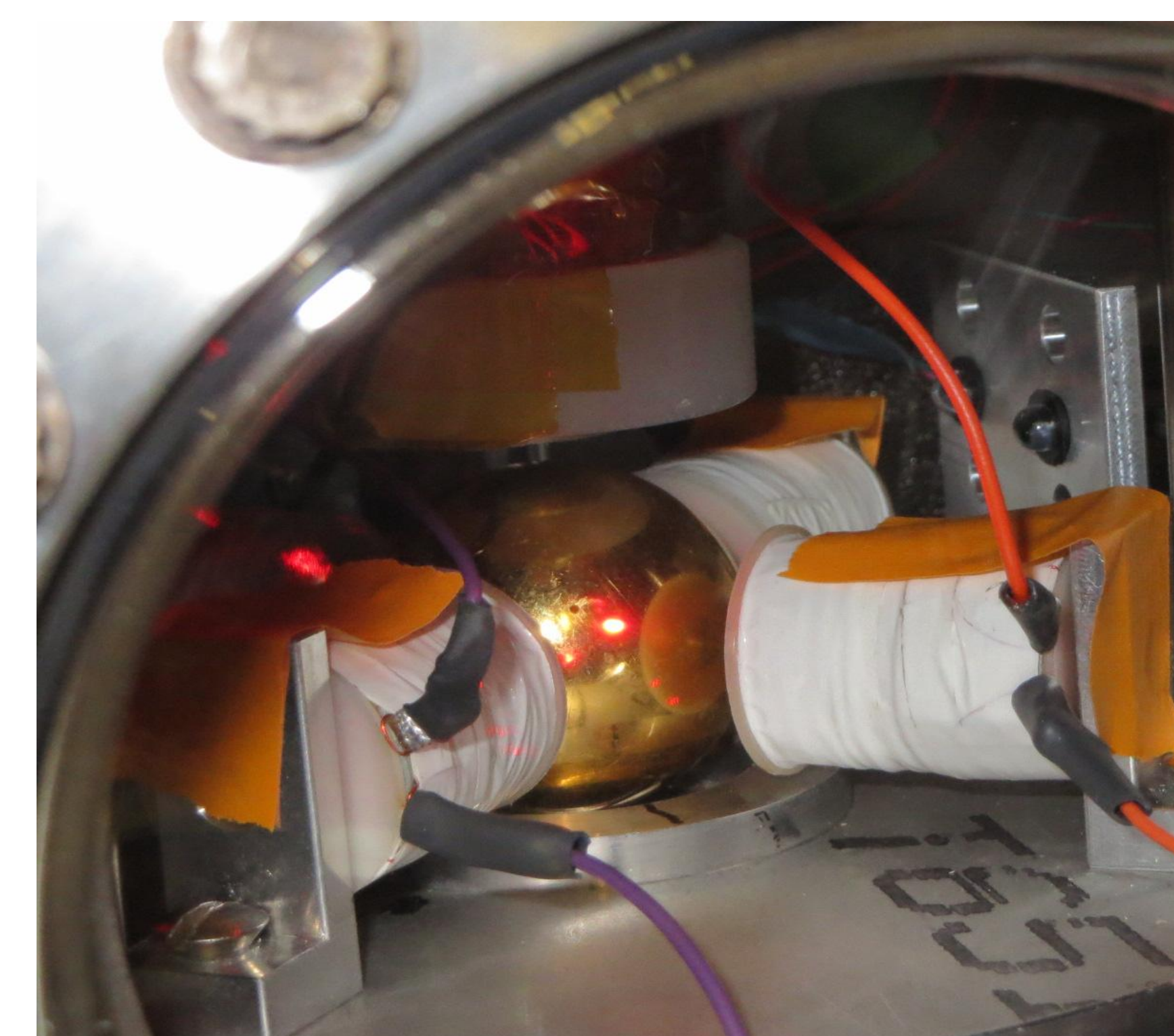
Lens between sphere and detector

Experiment running in air before it is moved to vacuum.

## Experiment Spinning



4 coils



Sphere is spinning in vacuum

Was able to spin the sphere up to 11Hz in vacuum.

## Future Work

- The system will be used to test the three-axis optical sensor system, DOSS, that is being developed separately, by rapidly switching to the DOSS sensor while the ball is levitated.
- Small magnetic pulses will be used to simulate thruster perturbations in the plane orthogonal to the support axis

## Acknowledgements

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