

Laboratory for Enabling Technologies

Experimental investigations of an inertial reference sensor with spherical test mass and optical read out

Harald Kögel^{1,2}, Ewan Fitzsimons¹, Domenico Gerardi¹, Ulrich Johann¹, Claus Braxmaier^{1,2,3} and Dennis Weise¹

¹Airbus Defense and Space, Friedrichshafen, Germany ²University of Bremen, Center of Applied Space Technology and Microgravity, Bremen, Germany ³DLR German Aerospace Center, Institute of Space Systems, Bremen, Germany

Motivation	Inertial Sensor Setup
An alternative eLISA payload concept with In-Field Pointing (IFP) was proposed which aligns the line of sight of each telescope by an actuated mirror, the IFP- Mechanism, compensating for orbital driven geometrical changes of the satellite formation:	As a first step Airbus is developing a setup to characterize the surface of the spherical test mass and to gain experience with the optical read out. Therefore the test mass will be mounted on a rotation table while its surface is measured interferometrically.
 In-Field Pointing replaces Telescope Pointing Single active test mass concept with reduced guiding Single optical bench without back-link fibers 	 Principal tests with non levitated test mass Test mass mounted on a highly precise rotation table Optical read out using two heterodyne interferometers

Potential performance improvements could be achieved by combining the IFP concept with a spherical test mass:

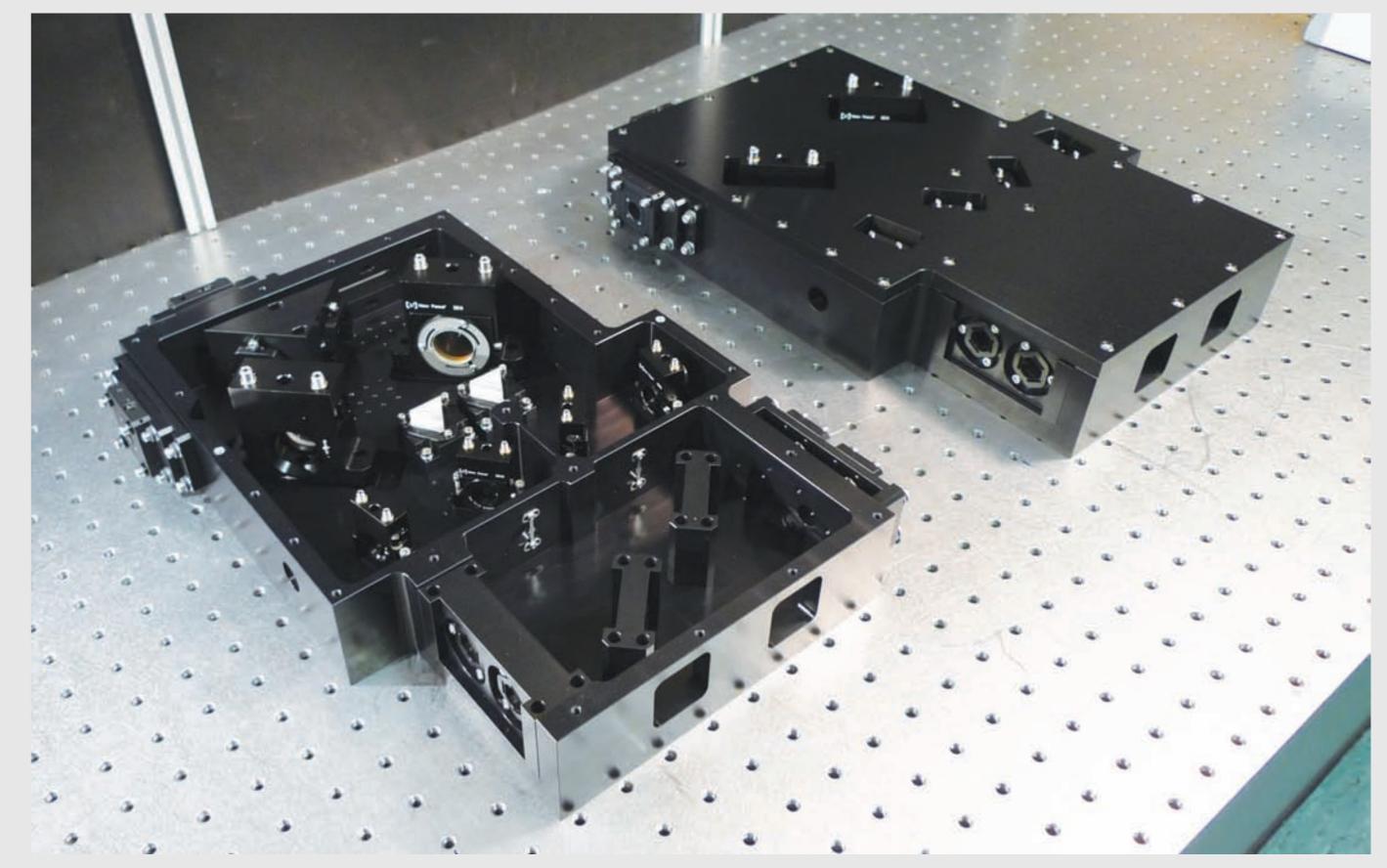
- ► No test mass guiding during science runs
- Larger gap between test mass and housing
- Enabling an all optical read out of test mass

Levitation Test Bed

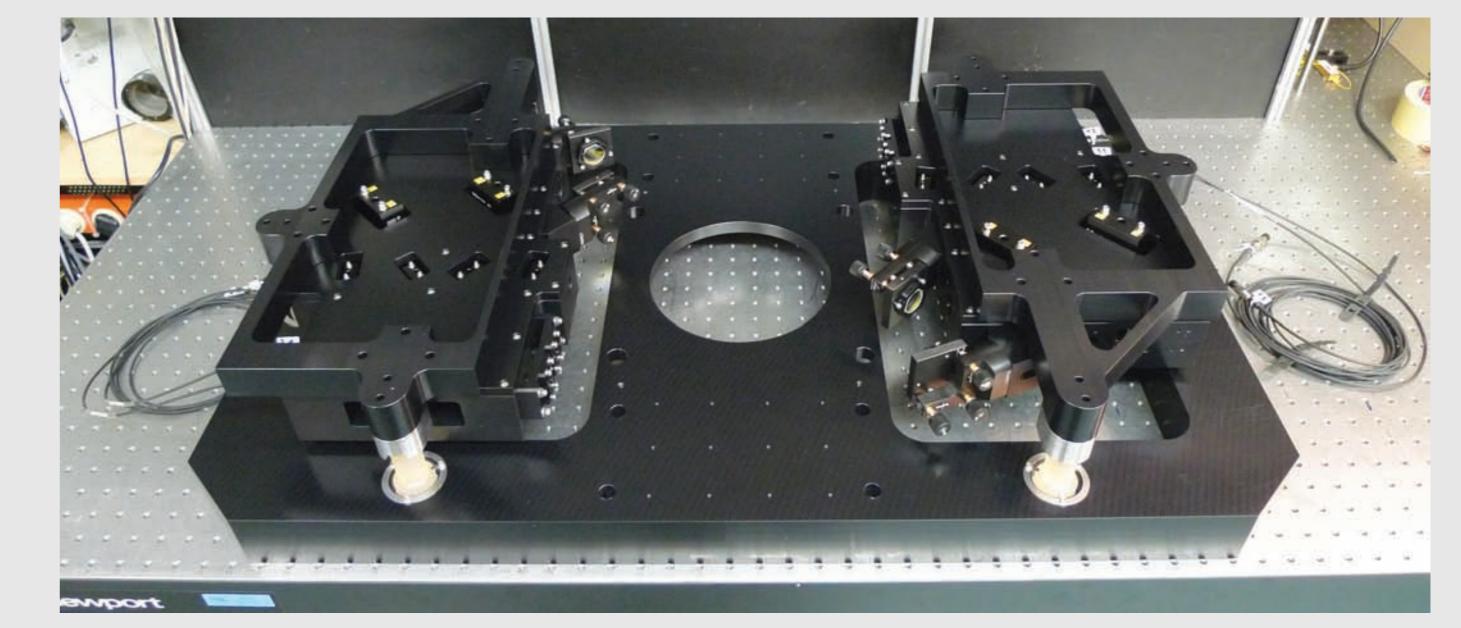
A levitation test bed is currently under construction to get some experience of levitating a spherical test mass. An electro-magnetic system is the chosen principle using a controlled electro-magnet and a magnetizable test mass. Starting point is a levitation system with 1 DoF guidance:

- Spherical test mass:
- ▷ Diameter: ⊘40 mm
- Surface quality (before coating): 60 nm (rms)
- Levitation of test mass via two level electro-magnet:
 - Dual-coil with 500 and 6000 windings for test mass height control
 - Controlling via FPGA based cascade control loop system
- Optical height sensing system by light barrier principle:

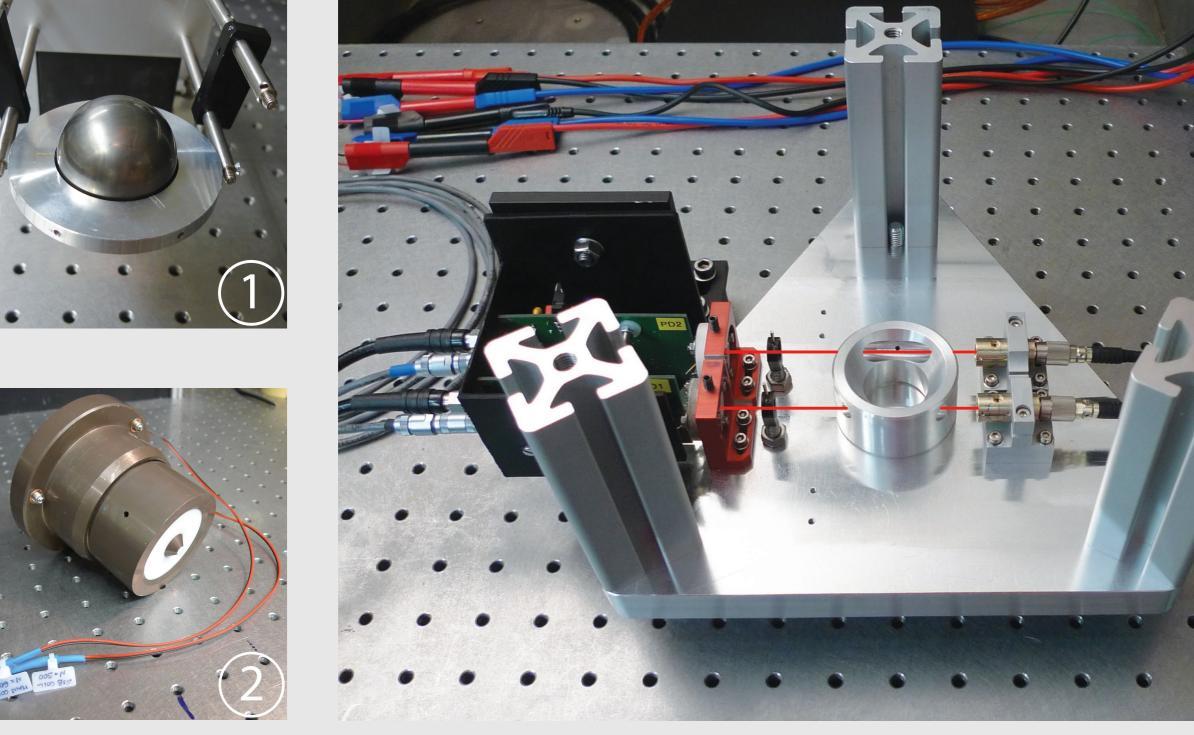
Mode match of output laser beams onto test mass



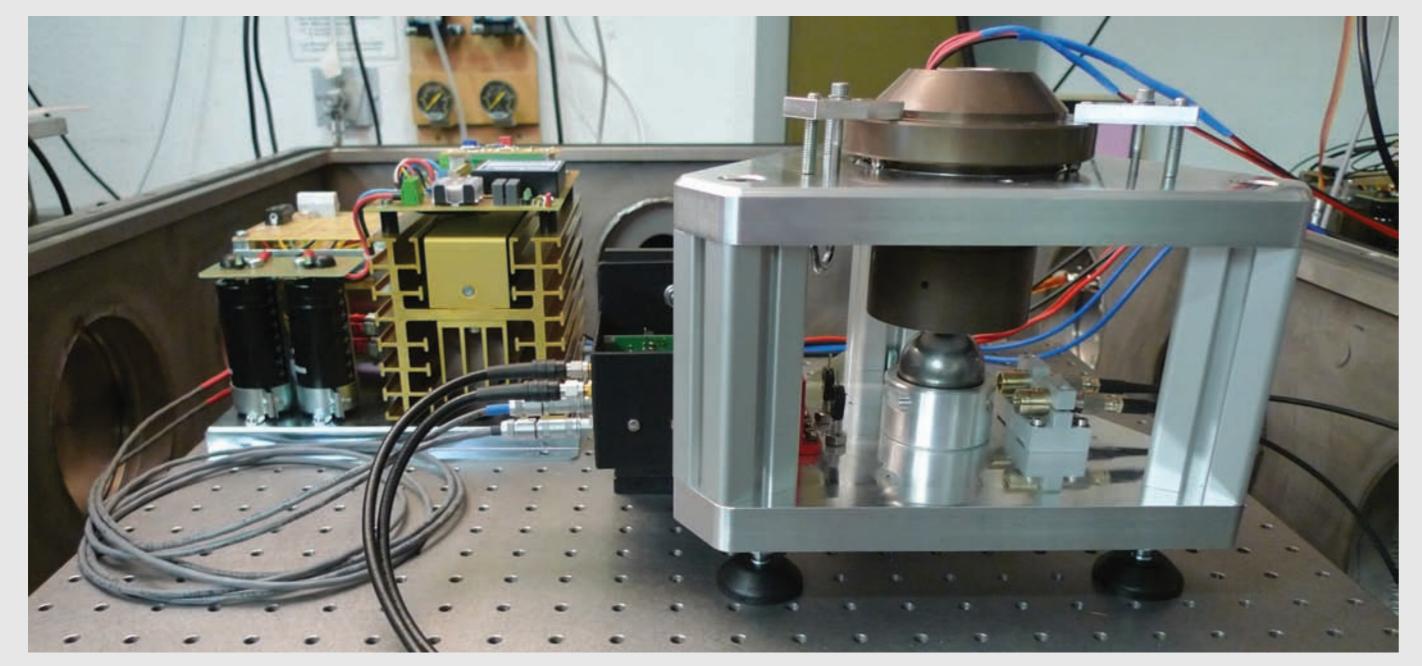
Heterodyne interferometers for the optical read out (currently under construction).



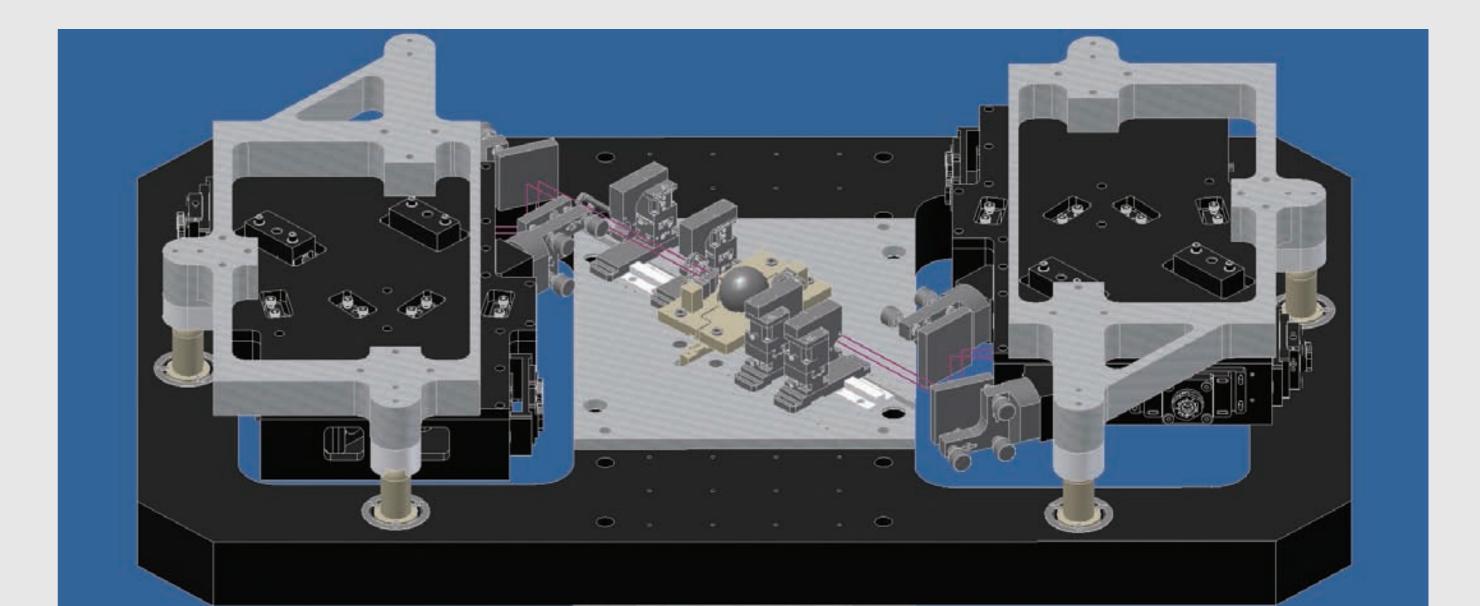
Two beam system for detection of lateral test mass movements



Spherical test mass (1), two level electro-magnet (2) and height sensing system (3).



Setup for characterizing test mass surface (currently under construction).



Levitation system test bed (currently under construction).

► Next steps:

Extension of height sensing by tilt signal (DWS) of the optical read out
 Implementing additional electro-magnets for 3 DoF guidance
 Implementing a system to apply a defined torque onto test mass

CAD rendering of the final setup for characterizing test mass surface.

Next steps: Tests with levitated test mass

- Setup shown above is also designed for future measurements with a levitation system
- Implementation of levitation system into setup
 Measurement of the test mass's center of mass
 Compensation of surface error by calibration
 Compensation of surface error by spin of test mass
 Implementation of two additional interferometers

Airbus Defense and Space

harald.koegel@astrium.eads.net