

Post-Newtonian limit of general relativity

$$g_{00} = -1 + \frac{2}{c^2}U + \frac{2}{c^4} \left(\psi + \frac{1}{2}\partial_{tt}X - U^2 \right) + O(c^{-6}),$$

$$g_{0j} = -\frac{4}{c^3}U_j + O(c^{-5}),$$

$$g_{jk} = \delta_{jk} \left(1 + \frac{2}{c^2}U \right) + O(c^{-4}),$$

$$U(t, \mathbf{x}) := G \int \frac{\rho^{*'}}{|\mathbf{x} - \mathbf{x}'|} d^3x',$$

$$\psi(t, \mathbf{x}) := G \int \frac{\rho^{*'} \left(\frac{3}{2}v'^2 - U' + \Pi' + 3p'/\rho^{*'} \right)}{|\mathbf{x} - \mathbf{x}'|} d^3x',$$

$$X(t, \mathbf{x}) := G \int \rho^{*'} |\mathbf{x} - \mathbf{x}'| d^3x',$$

$$U^j(t, \mathbf{x}) := G \int \frac{\rho^{*'} v'^j}{|\mathbf{x} - \mathbf{x}'|} d^3x'$$



Post-Newtonian Hydrodynamics

From $\nabla_{\beta} T^{\alpha\beta} = 0$

Post-Newtonian equation of hydrodynamics

$$\begin{aligned} \rho^* \frac{dv^j}{dt} = & -\partial_j p + \rho^* \partial_j U \\ & + \frac{1}{c^2} \left[\left(\frac{1}{2} v^2 + U + \Pi + \frac{p}{\rho^*} \right) \partial_j p - v^j \partial_t p \right] \\ & + \frac{1}{c^2} \rho^* \left[(v^2 - 4U) \partial_j U - v^j (3\partial_t U + 4v^k \partial_k U) \right. \\ & \quad \left. + 4\partial_t U_j + 4v^k (\partial_k U_j - \partial_j U_k) + \partial_j \Psi \right] \\ & + O(c^{-4}) \end{aligned}$$

$$\Psi = \psi + \frac{1}{2} \partial_{tt} X$$



N-body equations of motion

Main assumptions:

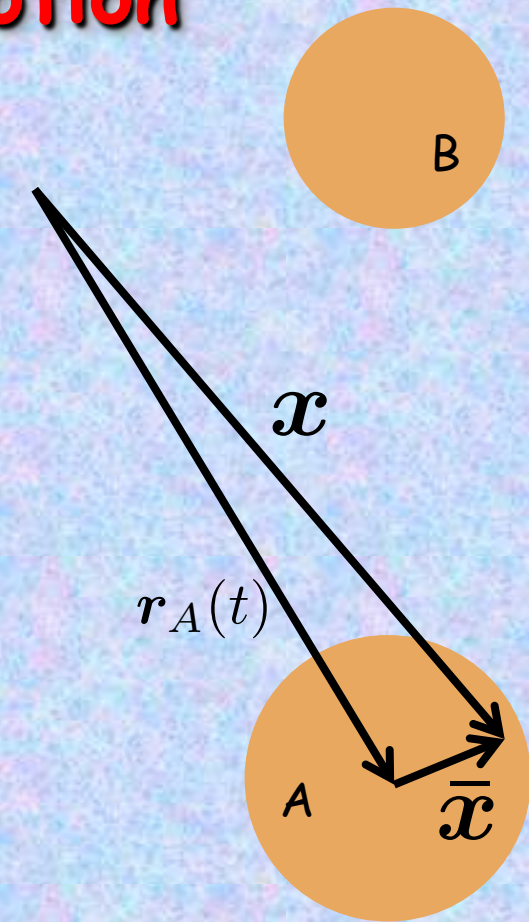
- Bodies small compared to typical separation ($R \ll r$)
- “isolated” -- no mass flow
- ignore contributions that scale as R^n
- assume bodies are reflection symmetric

$$\text{mass : } m_A \equiv \int_A \rho^* d^3x$$

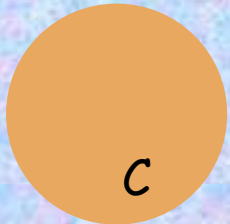
$$\text{position : } \mathbf{r}_A(t) \equiv \frac{1}{m_A} \int_A \rho^* \mathbf{x} d^3x$$

$$\text{velocity : } \mathbf{v}_A(t) \equiv \frac{1}{m_A} \int_A \rho^* \mathbf{v} d^3x = \frac{d\mathbf{r}_A}{dt}$$

$$\text{acceleration : } \mathbf{a}_A(t) \equiv \frac{1}{m_A} \int_A \rho^* \mathbf{a} d^3x = \frac{d\mathbf{v}_A}{dt}$$



$$\mathbf{x} \equiv \mathbf{r}_A(t) + \bar{\mathbf{x}}$$



N-body equations of motion

$$\begin{aligned}\int_A \rho^* v^2 \partial_j U d^3 x &= \int_A \rho^* (v_A^2 + 2\mathbf{v}_A \cdot \bar{\mathbf{v}} + \bar{v}^2) \partial_j U_A d^3 x \\ &\quad + \sum_B \int_A \rho^* (v_A^2 + 2\mathbf{v}_A \cdot \bar{\mathbf{v}} + \bar{v}^2) \partial_j U_B d^3 x \\ &= 2H_A^{jk} v_A^k + \sum_B m_A v_A^2 \partial_j U_B + 2\mathcal{T}_A \sum_B \partial_j U_B\end{aligned}$$



N-body equations of motion

Dependence on internal structure?

$$\mathcal{T}_A \equiv \frac{1}{2} \int_A \rho^* \bar{v}^2 d^3 \bar{x}, \quad P_A \equiv \int_A p d^3 \bar{x},$$
$$\Omega_A \equiv -\frac{1}{2} G \int_A \frac{\rho^* \rho^{*'}}{|\bar{x} - \bar{x}'|} d^3 \bar{x}' d^3 \bar{x}, \quad E_A^{\text{int}} \equiv \int_A \rho^* \Pi d^3 \bar{x}$$

Use the virial theorem:

$$2\mathcal{T}_A + \Omega_A + 3P_A = 0$$

Then all structure integrals for body A disappear and those for the external bodies can be absorbed into a single "total" mass:

$$M_B \equiv m_B + \frac{1}{c^2} (\mathcal{T}_B + \Omega_B + E_B^{\text{int}}) + O(c^{-4})$$

This is a manifestation of the **Strong Equivalence Principle**, satisfied by GR, but not by most alternative theories.

The motions of all bodies, including NS and BH, are independent of their internal structure - in GR!



N-body equations of motion

$$\begin{aligned}
 \mathbf{a}_A = & - \sum_{B \neq A} \frac{GM_B}{r_{AB}^2} \mathbf{n}_{AB} \\
 & + \frac{1}{c^2} \left(- \sum_{B \neq A} \frac{GM_B}{r_{AB}^2} \left[v_A^2 - 4(\mathbf{v}_A \cdot \mathbf{v}_B) + 2v_B^2 - \frac{3}{2}(\mathbf{n}_{AB} \cdot \mathbf{v}_B)^2 \right. \right. \\
 & \qquad \qquad \qquad \left. \left. - \frac{5GM_A}{r_{AB}} - \frac{4GM_B}{r_{AB}} \right] \mathbf{n}_{AB} \right. \\
 & + \sum_{B \neq A} \frac{GM_B}{r_{AB}^2} \left[\mathbf{n}_{AB} \cdot (4\mathbf{v}_A - 3\mathbf{v}_B) \right] (\mathbf{v}_A - \mathbf{v}_B) \\
 & + \sum_{B \neq A} \sum_{C \neq A, B} \frac{G^2 M_B M_C}{r_{AB}^2} \left[\frac{4}{r_{AC}} + \frac{1}{r_{BC}} - \frac{r_{AB}}{2r_{BC}^2} (\mathbf{n}_{AB} \cdot \mathbf{n}_{BC}) \right] \mathbf{n}_{AB} \\
 & \left. - \frac{7}{2} \sum_{B \neq A} \sum_{C \neq A, B} \frac{G^2 M_B M_C}{r_{AB} r_{BC}^2} \mathbf{n}_{BC} \right) + O(c^{-4}).
 \end{aligned}$$



Post-Newtonian limit of general relativity

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$$g_{0j} = -\frac{4}{c^3}U_j + O(c^{-5}),$$

$$g_{jk} = \delta_{jk} \left(1 + \frac{2}{c^2}U\right) + O(c^{-4}),$$

$$\Psi = \psi + \frac{1}{2}\partial_{tt}X$$

$$U(t, \mathbf{x}) := G \int \frac{\rho^{*'}}{|\mathbf{x} - \mathbf{x}'|} d^3x',$$

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$$X(t, \mathbf{x}) := G \int \rho^{*'} |\mathbf{x} - \mathbf{x}'| d^3x',$$

$$U^j(t, \mathbf{x}) := G \int \frac{\rho^{*'} v'^j}{|\mathbf{x} - \mathbf{x}'|} d^3x'$$



Post-Newtonian geodesic equation

$$\frac{d^2 r^\alpha}{d\lambda^2} + \Gamma_{\beta\gamma}^\alpha \frac{dr^\beta}{d\lambda} \frac{dr^\gamma}{d\lambda} = 0 \quad \begin{array}{l} \lambda = \text{proper time (timelike)} \\ = \text{affine parameter (null)} \end{array}$$

Use 0 component $d^2t/d\lambda^2$ to change from λ to t

$$\frac{dv^\alpha}{dt} = - \left(\Gamma_{\beta\gamma}^\alpha - \frac{v^\alpha}{c} \Gamma_{\beta\gamma}^0 \right) v^\beta v^\gamma \quad v^\alpha = (c, \mathbf{v})$$

Timelike test body $v^2 \sim U$

$$\frac{dv^j}{dt} = \partial_j U + \frac{1}{c^2} \left[(v^2 - 4U) \partial_j U - (4v^k \partial_k U + 3\partial_t U) v^j - 4v^k (\partial_j U_k - \partial_k U_j) + 4\partial_t U_j + \partial_j \Psi \right] + O(c^{-4})$$



Post-Newtonian geodesic equation

Lightlike test body $v^2 \sim c^2$

$$ds^2 = 0 = - \left(1 - \frac{2}{c^2} U + O(c^{-4}) \right) c^2 dt^2 + \left(1 + \frac{2}{c^2} U + O(c^{-4}) \right) v^2 dt^2 - \frac{8}{c^2} U^j v_j dt^2$$

$$v^2 = c^2 \left(1 - \frac{4}{c^2} U + O(c^{-3}) \right) \Rightarrow \mathbf{v} = c \left(1 - \frac{2}{c^2} U \right) \mathbf{n}$$

Geodesic equation with $v \sim c$

$$\frac{dv^j}{dt} = \left(1 + \frac{v^2}{c^2} \right) \partial_j U - \frac{4}{c^2} v^j v^k \partial_k U + O(c^{-3})$$

$$\frac{dn^j}{dt} = \frac{2}{c} (\delta^{jk} - n^j n^k) \partial_k U + O(c^{-2})$$

These will be used for the deflection of light, Shapiro time delay and gravitational lenses



N-body equations of motion

$$\begin{aligned}
 \mathbf{a}_A = & - \sum_{B \neq A} \frac{GM_B}{r_{AB}^2} \mathbf{n}_{AB} \\
 & + \frac{1}{c^2} \left(- \sum_{B \neq A} \frac{GM_B}{r_{AB}^2} \left[v_A^2 - 4(\mathbf{v}_A \cdot \mathbf{v}_B) + 2v_B^2 - \frac{3}{2}(\mathbf{n}_{AB} \cdot \mathbf{v}_B)^2 \right. \right. \\
 & \qquad \qquad \qquad \left. \left. - \frac{5GM_A}{r_{AB}} - \frac{4GM_B}{r_{AB}} \right] \mathbf{n}_{AB} \right. \\
 & + \sum_{B \neq A} \frac{GM_B}{r_{AB}^2} \left[\mathbf{n}_{AB} \cdot (4\mathbf{v}_A - 3\mathbf{v}_B) \right] (\mathbf{v}_A - \mathbf{v}_B) \\
 & + \sum_{B \neq A} \sum_{C \neq A, B} \frac{G^2 M_B M_C}{r_{AB}^2} \left[\frac{4}{r_{AC}} + \frac{1}{r_{BC}} - \frac{r_{AB}}{2r_{BC}^2} (\mathbf{n}_{AB} \cdot \mathbf{n}_{BC}) \right] \mathbf{n}_{AB} \\
 & \left. - \frac{7}{2} \sum_{B \neq A} \sum_{C \neq A, B} \frac{G^2 M_B M_C}{r_{AB} r_{BC}^2} \mathbf{n}_{BC} \right) + O(c^{-4}).
 \end{aligned}$$



PN 2-body equations of motion

Define:

$$\begin{aligned} \mathbf{r} &\equiv \mathbf{r}_1 - \mathbf{r}_2 & m &\equiv M_1 + M_2 \\ \mathbf{v} &\equiv \mathbf{v}_1 - \mathbf{v}_2 & \eta &\equiv \frac{M_1 M_2}{(M_1 + M_2)^2} \\ \mathbf{a} &\equiv \mathbf{a}_1 - \mathbf{a}_2 & \mathbf{n} &\equiv \mathbf{r}/r \\ & & \dot{r} &\equiv dr/dt = \mathbf{n} \cdot \mathbf{v} \end{aligned}$$

$$\mathbf{a} = -\frac{Gm}{r^2} \mathbf{n} - \frac{Gm}{c^2 r^2} \left\{ \left[(1 + 3\eta)v^2 - \frac{3}{2}\eta\dot{r}^2 - 2(2 + \eta)\frac{Gm}{r} \right] \mathbf{n} - 2(2 - \eta)\dot{r}\mathbf{v} \right\} + O(c^{-4}),$$

- Geodesic equation: $\eta = 0$, more general potentials U, ψ, X
- PN 2-body equation: general masses, ignore moments



PN 2-body equations of motion: conserved quantities

Conserved energy: dot v into the equation of motion

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} v^2 &= -\frac{Gm}{r^2} \dot{r} + \frac{Gm}{c^2 r^2} \dot{r} \left[(3 - 5\eta)v^2 + \frac{3}{2} \eta \dot{r}^2 + 2(2 + \eta) \frac{Gm}{r} \right] \\ &= \frac{d}{dt} \left(\frac{Gm}{r} \right) - \frac{d}{dt} \left\{ \frac{Gm}{c^2 r} \left[(3 - 4\eta)v^2 - \left(1 - \frac{9}{2} \eta \right) \frac{Gm}{r} + \frac{1}{2} \eta \dot{r}^2 \right] \right\} \end{aligned}$$

$$\frac{(Gm)^2}{r^3} \dot{r} = -\frac{1}{2} \frac{d}{dt} \left(\frac{Gm}{r} \right)^2$$

$$\frac{Gm}{r^2} \dot{r} v^2 = \frac{d}{dt} \left[\frac{Gm}{r} \left(\frac{Gm}{r} - v^2 \right) \right]$$

$$\frac{Gm}{r^2} \dot{r}^3 = \frac{1}{3} \frac{d}{dt} \left[\frac{Gm}{r} \left(3 \frac{Gm}{r} - 2v^2 - \dot{r}^2 \right) \right]$$



PN 2-body equations of motion: conserved quantities

Conserved energy: dot v into the equation of motion

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} v^2 &= -\frac{Gm}{r^2} \dot{r} + \frac{Gm}{c^2 r^2} \dot{r} \left[(3 - 5\eta)v^2 + \frac{3}{2} \eta \dot{r}^2 + 2(2 + \eta) \frac{Gm}{r} \right] \\ &= \frac{d}{dt} \left(\frac{Gm}{r} \right) - \frac{d}{dt} \left\{ \frac{Gm}{c^2 r} \left[(3 - 4\eta)v^2 - \left(1 - \frac{9}{2} \eta \right) \frac{Gm}{r} + \frac{1}{2} \eta \dot{r}^2 \right] \right\} \\ &\quad - \frac{3}{2c^2} (1 - 3\eta) \frac{d}{dt} \left(\frac{1}{2} v^2 - \frac{Gm}{r} \right)^2 \end{aligned}$$

$$\varepsilon := \frac{1}{2} v^2 - \frac{Gm}{r} + \frac{1}{c^2} \left\{ \frac{3}{8} (1 - 3\eta) v^4 + \frac{Gm}{2r} \left[(3 + \eta)v^2 + \eta \dot{r}^2 + \frac{Gm}{r} \right] \right\} + O(c^{-4})$$

$$E_{\text{SR}} = \gamma_1 m_1 c^2 + \gamma_2 m_2 c^2$$



PN 2-body equations of motion: conserved quantities

Conserved angular momentum: cross \times with the equation of motion

$$\begin{aligned} \frac{d}{dt}(\mathbf{r} \times \mathbf{v}) &= (4 - 2\eta) \frac{Gm}{c^2 r^2} \dot{r} (\mathbf{r} \times \mathbf{v}) \\ &= -\frac{d}{dt} \left[(4 - 2\eta) \frac{Gm}{c^2 r} (\mathbf{r} \times \mathbf{v}) \right] \\ &\quad - \frac{d}{dt} \left[\frac{1 - 3\eta}{c^2} \left(\frac{1}{2} v^2 - \frac{Gm}{c^2 r} \right) (\mathbf{r} \times \mathbf{v}) \right] \end{aligned}$$

$$\mathbf{h} = \left\{ 1 + \frac{1}{c^2} \left[\frac{1}{2} (1 - 3\eta) v^2 + (3 + \eta) \frac{Gm}{r} \right] \right\} (\mathbf{r} \times \mathbf{v}) + O(c^{-4})$$

$$\mathbf{L}_{\text{SR}} = \gamma_1 m_1 (\mathbf{x}_1 \times \mathbf{v}_1) + \gamma_2 m_2 (\mathbf{x}_2 \times \mathbf{v}_2)$$



PN circular orbits

$$\mathbf{a} = -\frac{Gm}{r^2}\mathbf{n} - \frac{Gm}{c^2 r^2} \left\{ \left[(1 + 3\eta)v^2 - \frac{3}{2}\eta\dot{r}^2 - 2(2 + \eta)\frac{Gm}{r} \right] \mathbf{n} - 2(2 - \eta)\dot{r}\mathbf{v} \right\} + O(c^{-4}),$$

$$d\mathbf{n}/dt = \dot{\phi}\boldsymbol{\lambda}$$

$$d\boldsymbol{\lambda}/dt = -\dot{\phi}\mathbf{n}$$

$$\mathbf{v} = \dot{r}\mathbf{n} + r\dot{\phi}\boldsymbol{\lambda}$$

$$\mathbf{a} = (\ddot{r} - r\dot{\phi}^2)\mathbf{n} + (2\dot{r}\dot{\phi} + r\ddot{\phi})\boldsymbol{\lambda}$$

$$\dot{r} = 0 \implies \begin{cases} \ddot{r} = 0 \\ \dot{\phi} = \Omega = \text{const} \end{cases}$$

$$\Omega^2 = \frac{Gm}{r^3} \left[1 - (3 - \eta)\frac{Gm}{c^2 r} + O(c^{-4}) \right]$$

$$\varepsilon = -\frac{Gm}{2r} \left[1 - \frac{1}{4}(7 - \eta)\frac{Gm}{c^2 r} + O(c^{-4}) \right]$$

$$h = \sqrt{Gmr} \left[1 + 2\frac{Gm}{c^2 r} + O(c^{-4}) \right]$$

Remark: test body in Schwarzschild coords
($\eta = 0, r = r_S - Gm/c^2$)

$$\Omega^2 = \frac{Gm}{r_S^3}$$



N-body equations of motion: Worked example: 2 bodies and the perihelion shift

Components of the disturbing force

$$\mathcal{R} = \frac{Gm}{c^2 r^2} \left[-(1 + 3\eta)v^2 + \frac{1}{2}(8 - \eta)\dot{r}^2 + 2(2 + \eta)\frac{Gm}{r} \right],$$

$$\mathcal{S} = \frac{Gm}{c^2 r^2} \left[2(2 - \eta)\dot{r}(r\dot{\phi}) \right],$$

$$\mathcal{W} = 0$$

Integrate the Lagrange planetary equations:

$$\Delta e = \Delta a = 0$$

$$\Delta \Omega = \Delta \iota = 0$$

$$\Delta \omega = \frac{6\pi G(M_1 + M_2)}{a(1 - e^2)c^2}$$

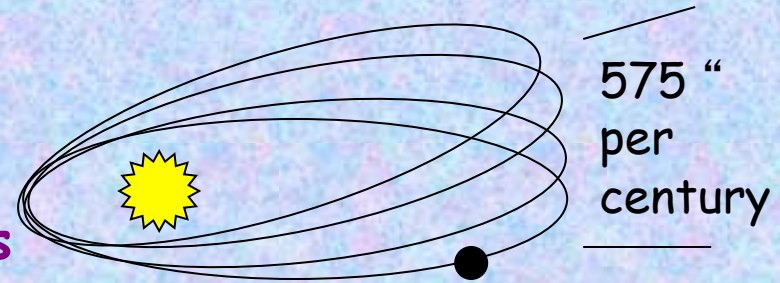
42.98 "/c for
Mercury

4.226598 °/yr
for PSR 1913+16



Mercury's Perihelion: Trouble to Triumph

- 1687 Newtonian triumph
- 1859 Leverrier's conundrum
- 1900 A turn-of-the century crisis



Planet	Advance
Venus	277.8
Earth	90.0
Mars	2.5
Jupiter	153.6
Saturn	7.3
Total	531.2
Discrepancy	42.9
Modern measured value	42.982 ± 0.001
General relativity prediction	42.98



Deflection of light

$$\mathbf{v} = c \left(1 - \frac{2}{c^2} U \right) \mathbf{n} \quad \frac{dn^j}{dt} = \frac{2}{c} (\delta^{jk} - n^j n^k) \partial_k U \quad U = G \int \frac{\rho'}{|\mathbf{r}(t) - \mathbf{x}'|} d^3 x'$$

Zeroth order trajectory:

$$\mathbf{r}(t) = \mathbf{r}_e + c\mathbf{k}(t - t_e) + O(c^{-2})$$

$$\mathbf{s}_e = \mathbf{r}_e - \mathbf{x}'$$

$$\mathbf{s} = \mathbf{r}(t) - \mathbf{x}'$$

To PN order, let

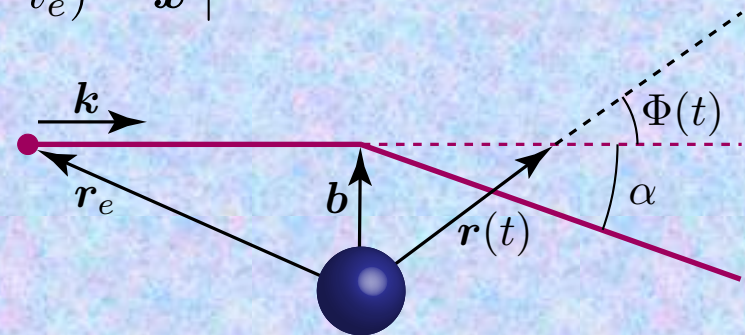
$$\mathbf{n} = \mathbf{k} + \boldsymbol{\alpha} + O(c^{-4})$$

$$\mathbf{b} = \mathbf{s}_e - \mathbf{k}(\mathbf{s}_e \cdot \mathbf{k})$$

$$\frac{d\alpha^j}{dt} = -\frac{2G}{c} (\delta^{jk} - k^j k^k) \int \rho' \frac{r_e^k + c k^k (t - t_e) - x'^k}{|\mathbf{r}_e + c\mathbf{k}(t - t_e) - \mathbf{x}'|^3} d^3 x'$$

$$= -\frac{2G}{c} \int \rho' \frac{\mathbf{b}}{s^3} d^3 x'$$

$$= -\frac{2G}{c^2} \int \rho' \frac{\mathbf{b}}{b^2} \frac{d}{dt} \left(\frac{\mathbf{s} \cdot \mathbf{k}}{s} \right) d^3 x'$$



$$\boldsymbol{\alpha}(t) = -\frac{2G}{c^2} \int \rho(t, \mathbf{x}') \frac{\mathbf{b}}{b^2} \left(\frac{\mathbf{s} \cdot \mathbf{k}}{s} - \frac{\mathbf{s}_e \cdot \mathbf{k}}{s_e} \right) d^3 x'$$



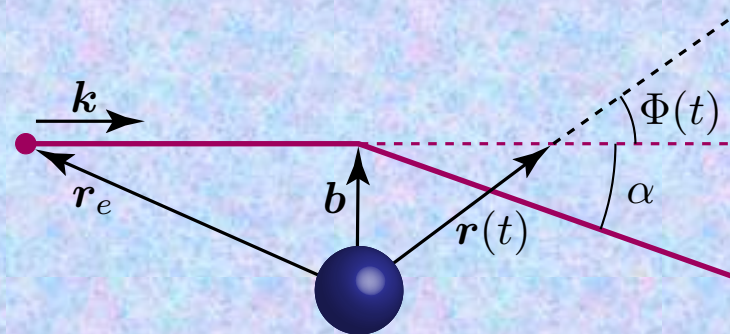
Deflection of light

For a point mass at the origin

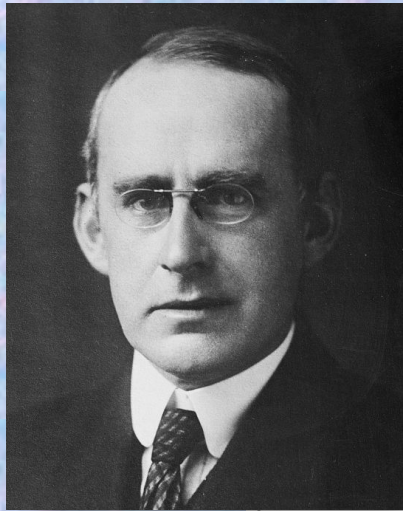
$$\alpha(t) = -\frac{2GM}{c^2} \frac{\mathbf{b}}{b^2} \left[\frac{\mathbf{r}(t) \cdot \mathbf{k}}{r(t)} - \frac{\mathbf{r}_e \cdot \mathbf{k}}{r_e} \right]$$
$$\approx -\frac{4GM}{c^2 b} \hat{\mathbf{b}} \left[\frac{\cos \Phi(t) + 1}{2} \right]$$

For $\Phi \approx 0$

$$\Delta\theta \approx |\alpha|$$
$$= \frac{4GM}{c^2 b}$$
$$= 1'' .7505 \left(\frac{M/M_\odot}{b/R_\odot} \right)$$



Deflection of light: The 1919 Eclipse



A. S. Eddington

LIGHTS ALL ASKEW IN THE HEAVENS

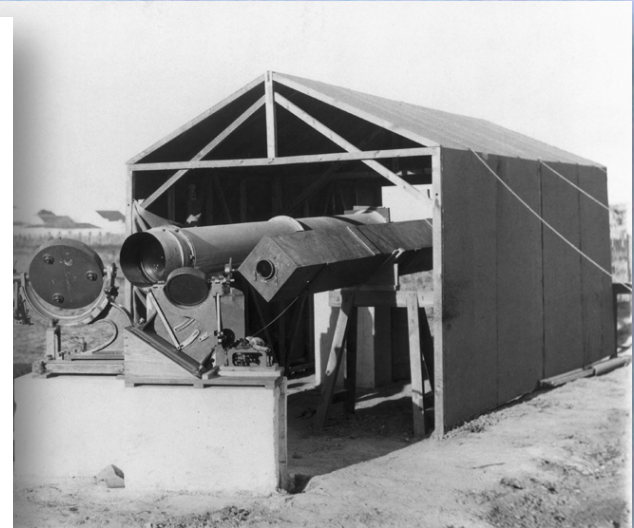
Men of Science More or Less
Agog Over Results of Eclipse
Observations.

EINSTEIN THEORY TRIUMPHS

Stars Not Where They Seemed
or Were Calculated to be,
but Nobody Need Worry.

A BOOK FOR 12 WISE MEN

No More in All the World Could
Comprehend It, Said Einstein When
His Daring Publishers Accepted It.



Sobral site

Photo from Principe

Deflection of light: Results

