

4/4/2018 Lorentz Transformation

$$x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$$

$$(ct)' = \gamma \left(ct + \frac{v}{c} x \right)$$

$$x' = \gamma \left(x + \frac{v}{c} ct \right)$$

Properties

$$\eta_{\alpha\beta} \Lambda^{\alpha}_{\mu} \Lambda^{\beta}_{\nu} = \eta_{\mu\nu}$$

$$\Rightarrow (\Lambda^T) \eta \Lambda = \eta$$

$$\Rightarrow \left(\det \Lambda \right)^2 = 1$$

$$\det \Lambda = \pm 1$$

$$\eta_{\alpha\beta} \Lambda^{\alpha}_{\mu} \Lambda^{\beta}_{\nu} = \eta_{\mu\nu} \quad \text{Take } \mu = \nu = 0$$

$$\eta_{\alpha\beta} \Lambda^{\alpha}_{0} \Lambda^{\beta}_{0} = \eta_{00} (\Lambda^0_0)^2 + \sum_i \eta_{ii} (\Lambda^i_0)^2$$

$$\left(\Lambda^0_0 \right)^2 = 1 + \sum_i (\Lambda^i_0)^2$$

$$\Lambda^0_0 \geq 1$$
$$\Lambda^0_0 \leq -1$$

2

$$A = \exp(\vec{\theta} \cdot \vec{J} + \vec{r} \cdot \vec{K})$$

$$\det M = \lambda_1 \dots \lambda_n \quad \log \det M = \log \lambda_1 + \dots + \log \lambda_n = \text{Tr}(\ln M)$$

$$\boxed{\det M = \exp(\text{Tr}(\ln M))}$$

$$\det A = \exp[\text{Tr}(\vec{\theta} \cdot \vec{J} + \vec{r} \cdot \vec{K})] = e^0 = 1$$

$\exp(\vec{\theta} \cdot \vec{J} + \vec{r} \cdot \vec{K})$ continuously connected to $\mathbb{1}$
 $\rightarrow A^0$ can't change sign $\rightarrow \lambda^0 \geq 1$
 $(\cos \theta \geq 1)$ (works for det. also)

$$T = \begin{pmatrix} -1 & & \\ & 1 & \\ & & 1 \end{pmatrix} \quad P = \begin{pmatrix} 1 & & \\ & -1 & \\ & & -1 \end{pmatrix} \quad PT = TP = \begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix}$$

$$\det T = -1 \quad \det P = -1 \quad \det(PT) = 1$$

$$T^0 = -1 \quad P^0 = +1 \quad (PT)^0 = -1$$

Four disconnected components:

Proper A

(Proper) x T

(-) x P

(-) x (PT)

$\begin{pmatrix} 1 & & \\ & -1 & \\ & & -1 \end{pmatrix}$ = rotation 180° z-axis. $\begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix}$ T x rotation

$$\Lambda^T \eta \Lambda = 1 \quad \eta^{-1} \Lambda^T \eta \Lambda = 1 \quad \left[\eta^{-1} \Lambda^T \eta = \Lambda^{-1} \right]$$

$$\begin{aligned} (\Lambda^{-1})^\alpha_\beta &= \eta^{\sigma\mu} (\Lambda^T)_\mu^\nu \cdot \eta_{\nu\beta} \\ &= \eta^{\sigma\mu} \Lambda^\nu_\mu \eta_{\nu\beta} \\ &= \eta_{\beta\nu} \Lambda^\nu_\mu \cdot \eta^{\mu\sigma} = \Lambda^\sigma_\beta \end{aligned}$$

Rotation lives in (\mathbb{R}^3) $\Lambda = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$ $\Lambda^2 = 1$.

$$\boxed{R^{-1} = R^T} \quad \checkmark \quad \boxed{\theta \rightarrow -\theta}$$

Boost. $\Lambda^T = \Lambda$, $\eta \Lambda \eta \rightarrow \begin{pmatrix} + & - \\ - & \cancel{+} \end{pmatrix} \rightarrow \begin{matrix} v \rightarrow -v \\ \cancel{y} \rightarrow -\cancel{y} \end{matrix}$

$$\begin{aligned} x^\mu &= \Lambda^\mu_\nu x^\nu \\ x_\mu &= \Lambda^\nu_\mu x_\nu \end{aligned} \quad \begin{aligned} y^\mu &= \Lambda^\mu_\rho y^\rho \end{aligned}$$

~~$$x_\mu y^\mu = (\Lambda^\nu_\mu x_\nu) (\Lambda^\mu_\rho y^\rho)$$~~

$$\begin{aligned} x_\mu y^\mu &= (\Lambda^\nu_\mu x_\nu) (\Lambda^\mu_\rho y^\rho) \\ &= x_\nu (\Lambda^\nu_\mu \Lambda^\mu_\rho) y^\rho \\ &= \delta^\nu_\rho x_\nu y^\rho \end{aligned}$$

4

Tensors. $\left\{ \begin{matrix} \text{1d} \\ x^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu} \end{matrix} \right\} = \text{vector}$

$$T'^{\alpha\beta} = \Lambda^{\alpha}_{\mu} \Lambda^{\beta}_{\nu} \Lambda^{\rho}_{\gamma} \Lambda^{\sigma}_{\delta} T^{\mu\nu}_{\rho\sigma}$$

(m, n) tensor: m superscript, n subscript.
order matters.

Since η can raise, lower any index.

$T^{\alpha\beta\gamma\delta}$ rank = 4

Special Tensors:

$$\eta^{\alpha\beta} = \Lambda^{\alpha}_{\mu} \Lambda^{\nu}_{\beta} \eta^{\mu\nu} = \eta^{\alpha\beta}$$

$\epsilon^{0123} = +1$ (Minkowski)

$\epsilon_{0123} = \eta_{00} \eta_{11} \eta_{22} \eta_{33} \epsilon^{0123} = -1$

$$\epsilon'^{\alpha\beta\gamma\delta} = \Lambda^{\alpha}_{\mu} \Lambda^{\beta}_{\nu} \Lambda^{\rho}_{\gamma} \Lambda^{\sigma}_{\delta} \epsilon^{\mu\nu\rho\sigma}$$

$$= (\det \Lambda) (\epsilon^{\alpha\beta\gamma\delta}) = \epsilon^{\alpha\beta\gamma\delta} \quad (\text{proper})$$

Traces

$$T^{\mu}_{\nu} = T^{\mu\alpha}_{\alpha\nu}$$

$$T^I = \Lambda M T$$

$$\text{Tr } T^I = \text{Tr}(\Lambda M T) = \Lambda \text{Tr } T$$

before or after

⑤

$$T_{(dB)} = \frac{1}{2} (T_{dB} + T_{Bd})$$

$$T_{(dB)} = \frac{(n+s-1)!}{n!(s-1)!} \left| \begin{matrix} \infty & \infty \\ \infty & \infty \end{matrix} \right|$$

$$T_{[dB]} = \frac{1}{2} (T_{dB} - T_{Bd})$$

$$T_{[dB]} = \binom{n}{a} = \frac{n!}{a!(n-a)!}$$

$$T_{(dB)} + T_{[dB]} = T_{dB}$$

$$T_{(dB)} + T_{[dB]} \neq T_{dB}$$

$$\frac{4.5}{4} = 20$$

$$\frac{4.7.2}{6} = 4$$

$$4^3 = 64$$

Dual

$$(*V)_{dB} = \epsilon_{dB\mu\nu} V^{\mu\nu}$$

$$(*V)_d = \frac{1}{3!} \epsilon_{d\mu\nu\rho} V^{\mu\nu\rho}$$

$$(*T)_{dB} = \frac{1}{2} \epsilon_{dB\mu\nu} T^{\mu\nu}$$

E, m. field

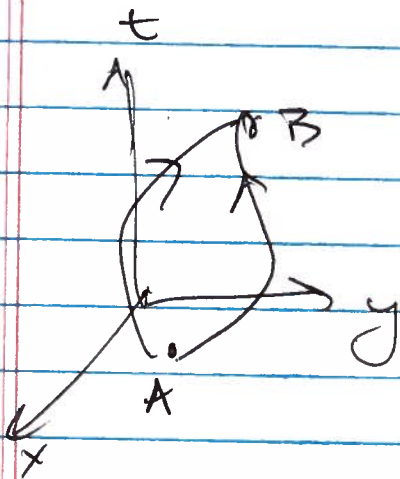
$$x^\mu = \begin{pmatrix} ct \\ \vec{x} \end{pmatrix} \text{ is a vector}$$

$$\vec{v} = \frac{d\vec{x}}{dt} \quad v^\mu = \frac{dx^\mu}{dt} \quad \text{with a vector.}$$

$$\frac{d\vec{x}'}{dt'} = \frac{\cancel{v} (d\vec{x} + \vec{v} dt)}{\cancel{v} (dt + \vec{v} \cdot \frac{d\vec{x}}{c^2})} = \left(\frac{\frac{d\vec{x}}{dt} + \vec{v}}{1 + \frac{\vec{v} \cdot \frac{d\vec{x}}{dt}}{c^2}} \right)$$

$$dt'^2 - \frac{1}{c^2} (d\vec{x}')^2 = \frac{1}{c^2} dx \cdot dx = (1 - \frac{v^2}{c^2}) dt^2 = d\tau^2$$

is a scalar. $\tau = \int \frac{1}{\gamma} dt$



$$\tau_{AB} = \int_A^B d\tau$$

is path-dependent,

(twin paradox)