

3/28/2016.

$$x' = \gamma(x + vt)$$
$$t' = \gamma(t + \frac{v}{c^2}x)$$

v <<< c

$$x' = x + vt$$
$$t' = t$$

$$\Lambda^\alpha_\mu \Lambda^\beta_\nu g_{\alpha\beta} = g_{\mu\nu}$$

$$(\Lambda^T) \eta \Lambda = \eta$$

$$\eta^{-1} \Lambda^T \eta \Lambda = 1 \quad \eta^{-1} \Lambda^T \eta = \Lambda^{-1}$$

$$(\Lambda^{-1})^\alpha_\beta = (\eta^{-1})^{\alpha\mu} (\Lambda^T)_{\mu\nu} (\eta)_{\nu\beta}$$
$$= \eta^{\alpha\mu} \Lambda^T_{\mu\nu} \eta_{\nu\beta} = \underline{\underline{\Lambda^T_{\beta\alpha}}}$$

$$\underline{\underline{\Lambda^{-1} = \eta^{-1} \Lambda^T \eta}}$$

(rotation)

(rotation)

$$\eta^2 = 1$$

$$R^T = R^{-1}$$

$$|\theta \rightarrow -\theta$$

(Boost)

$$\Lambda^T = \Lambda$$

$$\eta \Lambda \eta^{-1}$$

$$\left(\begin{array}{c|c} + & - \\ \hline - & + \end{array} \right)$$

↑
-j²

$$v \rightarrow -v$$
$$t \rightarrow -t$$

$$\left(\begin{array}{c|c} \alpha & \beta \\ \hline \gamma & \delta \end{array} \right)$$

$$\underline{\underline{\Lambda = \exp(\vec{\theta} \cdot \vec{J} + \vec{\beta} \cdot \vec{K})}}$$

(2)

Tensors . $x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$ vector

$$T'^{\alpha\beta\gamma\delta} = \Lambda^{\alpha}_{\mu} \Lambda^{\beta}_{\nu} \Lambda^{\gamma}_{\rho} \Lambda^{\delta}_{\sigma} T^{\mu\nu\rho\sigma}$$

since η can raise/lower any index, $T^{\alpha\beta\gamma\delta}$

Special Tensors

$$\eta'_{\alpha\beta} = \Lambda^{\mu}_{\alpha} \Lambda^{\nu}_{\beta} \eta_{\mu\nu} = \eta_{\alpha\beta}$$

$$\left(\epsilon^{0123} = +1 \right)$$

$$\epsilon'^{\alpha\beta\gamma\delta} = \Lambda^{\alpha}_{\mu} \Lambda^{\beta}_{\nu} \Lambda^{\gamma}_{\rho} \Lambda^{\delta}_{\sigma} \epsilon^{\mu\nu\rho\sigma}$$

$$= (\det \Lambda) (\epsilon^{\alpha\beta\gamma\delta}) = \epsilon^{\alpha\beta\gamma\delta}$$

proper

$$\underline{T^{\mu}_{\nu} = T^{\mu\alpha} \delta_{\alpha\nu}}$$

$$T' = \Lambda \Lambda T$$

$$\text{Tr} T' = \text{Tr}(\Lambda \Lambda T) = \Lambda \Lambda (\text{Tr} T)$$

~~before~~ \rightsquigarrow ~~after~~

$$T(\alpha\beta) = \frac{1}{2} (T_{\alpha\beta} + T_{\beta\alpha})$$

$$T(\alpha\beta\gamma) \left[\begin{matrix} (n-1)! \\ (n-1)! \end{matrix} \right] \dots$$

$$T[\alpha\beta] = \frac{1}{2} (T_{\alpha\beta} - T_{\beta\alpha})$$

$$T[\alpha\beta\gamma] \frac{n(n-1)(n-2)}{3!}$$

$$\left[\frac{n!}{a!(n-a)!} \right]$$

(3)

$$\underline{x^M = \begin{pmatrix} ct \\ \vec{x} \end{pmatrix}}$$

$\vec{v} = \frac{d\vec{x}}{dt}$ is not a vector. (will see how it transforms)

$$d\tau^2 = dt^2 - \frac{1}{c^2} (d\vec{x})^2 = \frac{1}{c^2} dx^\mu dx_\mu \quad \text{scalar}$$

along a path where $d\vec{x} = \vec{v} dt$ $d\tau^2 = dt^2 - \left(\frac{\vec{v} dt}{c}\right)^2$

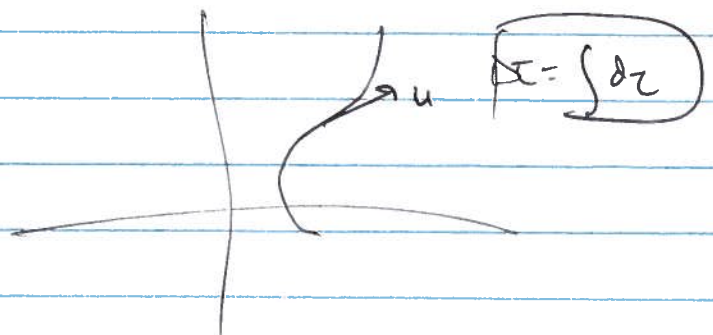
$$\boxed{d\tau = \frac{dt}{\gamma}} \qquad \qquad \qquad = \frac{dt^2}{\gamma^2}$$

$$u^M \equiv \frac{dx^M}{d\tau} = \begin{pmatrix} c \frac{dt}{d\tau} \\ \frac{d\vec{x}}{d\tau} \end{pmatrix} = \begin{pmatrix} c \cdot \gamma \cdot \frac{dt}{dt} \\ \gamma \cdot \frac{d\vec{v}}{dt} \end{pmatrix} = \begin{pmatrix} \gamma c \\ \gamma \vec{v} \end{pmatrix}$$

4-vector velocity 4-velocity

$$u \cdot u = (\gamma c)^2 - (\gamma \vec{v})^2 = \gamma^2 c^2 \left(1 - \frac{v^2}{c^2}\right) = \frac{c^2 (1 - v^2/c^2)}{1 - v^2/c^2}$$

$$\boxed{u \cdot u = c^2}$$



2

$$a^\mu = \frac{du^\mu}{dz}$$

$$u \cdot u = c^2$$

$$\frac{d}{dz}(u \cdot u) = 2u \cdot a = 0$$

$$u \cdot a = 0$$

at rest

(proper) $\vec{v} = 0$

$$u = \begin{pmatrix} c \\ 0 \end{pmatrix}$$

$$a = \begin{pmatrix} 0 \\ a \end{pmatrix}$$

$$a \cdot a = -|\vec{a}|_{\text{proper}}^2$$

constant proper acceleration $|\vec{a}|_{\text{proper}} = g$

$$u \cdot u = (u^t)^2 - (u^x)^2 = c^2$$

$$a \cdot a = (a^t)^2 - (a^x)^2 = -g^2$$

$$u \cdot a = (u^t)(a^t) - (u^x)(a^x) = 0$$

remove x-components

$$(a^x)^2 = (a^t)^2 + g^2 = a^2 + g^2$$

$$(u^x)^2 = (u^t)^2 - c^2 = u^2 - c^2$$

$$u^2 a^2 = (u^t)^2 (a^t)^2 - (u^x)^2 (a^x)^2 = (u^t)^2 (a^t)^2 - (u^2 - c^2)(a^2 + g^2)$$

$$u^2 a^2 = u^2 a^2 + u^2 g^2 - a^2 c^2 - g^2 c^2$$

$$\frac{u^2}{c^2} - \frac{a^2}{g^2} = 1$$

$$\left(\frac{du}{dz} \right)^2 = g^2 \left(\frac{u^2}{c^2} - 1 \right)$$

$$\int_c^u \frac{du'}{\sqrt{\frac{u'^2}{c^2} - 1}} = c \cdot \cosh^{-1} \left(\frac{u}{c} \right) \Big|_c^u = c \cdot \cosh^{-1} \frac{u}{c} = g\tau$$

$$u = c \cdot \cosh \left(\frac{g\tau}{c} \right) = c \frac{dt}{d\tau}$$

$$ct = \frac{c^2}{g} \sinh \left(\frac{g\tau}{c} \right)$$

$$ct \approx \frac{ct}{g} \frac{g\tau}{c} = c\tau$$

$$\left(\frac{dx}{dz} \right)^2 = \cancel{c^2} - \left(\frac{dt}{d\tau} \right)^2 = u^2 - c^2 = c^2 (1 - \cosh^2 \frac{g\tau}{c})$$

$$= c^2 \cdot \sinh^2 \frac{g\tau}{c}$$

$$\frac{dx}{d\tau} = c \cdot \sinh \frac{g\tau}{c}$$

$$x = \frac{c^2}{g} \left[\cosh \left(\frac{g\tau}{c} \right) - 1 \right]$$

$$x \approx \frac{c^2}{g} \left(1 + \frac{1}{2} \left(\frac{g\tau}{c} \right)^2 - 1 \right)$$

$$= \frac{1}{2} g\tau^2$$

$$\left(x + \frac{c^2}{g} \right)^2 - c^2 t^2 = \frac{c^2}{g} \left(\cosh^2 \frac{g\tau}{c} - \sinh^2 \frac{g\tau}{c} \right) = \frac{c^2}{g}$$

hyperbolic motion