

①

8/22/16

$$x = x^\mu = \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$$

4-vector

$\mu = 0, 1, 2, 3$

$$x = x^i$$

$i = 1, 2, 3$

~~x^μ~~

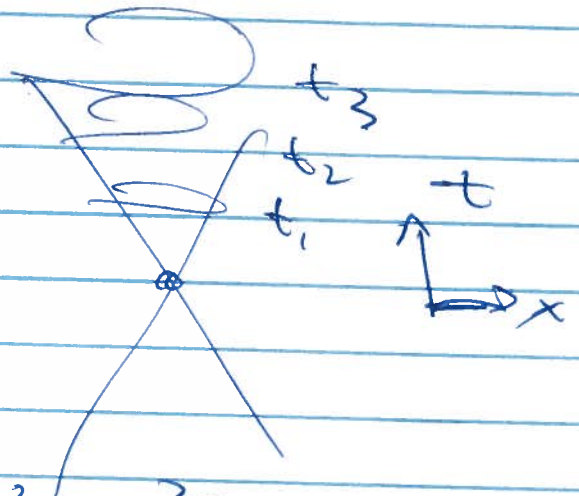
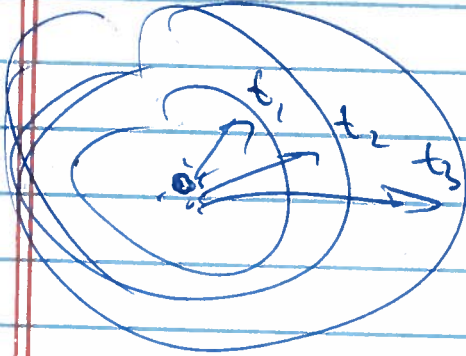
x^μ

(AE, P&EP, J&J)

$i \leftrightarrow j$

$$c = 1$$

$$(\hbar = 1)$$



Observer 0: $(\Delta x)^2 = c^2(\Delta t)^2 = \Delta s^2$

Observer 0': $(\Delta x')^2 = (\Delta t')^2$

$$\Delta s^2 = -(\Delta t)^2 + (\Delta x)^2 \quad \text{invariant}$$

$$x \cdot y = -(x^0 y^0) + (x^1 y^1) + (x^2 y^2) + (x^3 y^3)$$

$$= -x^0 y^0 + x^i y^i = \eta_{\mu\nu} x^\mu y^\nu$$

$$\eta = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

1 superscript / 1 subscript $\sum_{\mu, \nu}$

opposite signature (different)

2

$g = 980 \text{ cm s}^{-2} \rightarrow \text{Temperature}$

$h\nu = (10^{-27} \text{ erg s}) (10^3 \text{ cm s}^{-2}) = 10^{-24} \text{ erg cm s}^{-1}$

$\frac{h\nu}{e} = 3 \times 10^{-35} \text{ erg} = 2 \times 10^{-23} \text{ eV} = 2 \cdot 10^{-19} \text{ K}$

$(1 \text{ eV} = 1.602 \times 10^{-12} \text{ erg}, 1 \text{ eV} = 11,604.5 \text{ K})$

$[K] = [cm s^{-2}] [e]^a [h]^b [G]^c [K]^d$

$= [cm s^{-2}] [cm s^{-1}]^a [erg s]^b [cm^{-3} erg^{-1} s^{-2}]^c [erg K^{-1}]^d$

- (cm)
- (s)
- (erg)
- (K)

$0 = 1 + a + 3c$

$0 = -2 - a + b - 2c$

$0 = 0 + b - c + d$

$1 = -d$

$d = -1$

$$\left. \begin{aligned} 1 + a + 3c &= 0 \\ -2 - a + b - 2c &= 0 \\ -b + c - d &= 0 \end{aligned} \right\}$$

$2c = 0$

$c = 0$

$a = -1$

$b = 1$

$\frac{h\nu}{k} = 2.5 \times 10^{-19} \text{ K}$

3

$\vec{F} = m\vec{a}$

$ds^2 = g_{\mu\nu} dx^\mu dx^\nu$

$\frac{d^2 \vec{x}}{dt^2} = -\vec{\nabla}\phi$

$\frac{d^2 x^\mu}{dt^2} = -\Gamma^{\mu}_{\alpha\beta} \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt}$ (1.6)

$\frac{d^2 x^i}{dt^2} = -\frac{\partial\phi}{\partial x_i} = \phi_{,i}$

$\Gamma^{\mu}_{\alpha\beta} = \frac{1}{2} g^{\mu\sigma} (g_{\sigma\alpha, \beta} + g_{\sigma\beta, \alpha} - g_{\sigma\alpha\beta, \gamma})$

(3.27)

$d\tau^2 = -ds^2 = dt^2 - dx^2$

(Coordinate basis)

"geodesic equation" $\nabla_u u = 0$

Newton

$\nabla^2 \phi = 4\pi G \rho$

$T = \begin{pmatrix} \rho \\ \rho v \\ \rho v^2 \end{pmatrix}$

$G_{\mu\nu} = 8\pi G T_{\mu\nu}$

$G = \partial P + P P$

Einstein

$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R$ (1.5)

$R^{\alpha}_{\beta\mu\nu} = \Gamma^{\alpha}_{\nu\beta, \mu} - \Gamma^{\alpha}_{\mu\beta, \nu} + \Gamma^{\alpha}_{\mu\lambda} \Gamma^{\lambda}_{\nu\beta} - \Gamma^{\alpha}_{\nu\lambda} \Gamma^{\lambda}_{\mu\beta}$

(3.113)



"world line" $x^\mu(\lambda)$

λ arbitrary parameter ($\frac{dt}{d\lambda} > 0$)

$$d\tau^2 = -dx \cdot dx = dt^2 - d\vec{x}^2$$

$$= dt^2 \left(1 - \left(\frac{d\vec{x}}{dt} \right)^2 \right) = dt^2 (1 - v^2)$$

$d\tau$ is time interval in frame $d\vec{x} = 0$
 = frame comoving with (observer) = proper frame

$d\tau$ = "proper time"

$$d\tau \leq dt$$

"moving clocks run slow"

$$\gamma = \frac{1}{\sqrt{1-v^2}}$$

$$d\tau = (1-v^2) dt$$

$$d\tau = \frac{dt}{\gamma}$$

parameterize with τ , $x^\mu(\tau)$

tangent: $u^\mu = \frac{dx^\mu}{d\tau}$

$$u \cdot u = \frac{dx}{d\tau} \cdot \frac{dx}{d\tau} = - \left(\frac{dt}{d\tau} \right)^2 + \left(\frac{d\vec{x}}{d\tau} \right)^2$$

$$= - \frac{(dt^2 - d\vec{x}^2)}{d\tau^2} = - \frac{d\tau^2}{d\tau^2} = -1$$