

8/29/22

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## Announcements

HW 1 due Sept. 7 (pub ok?)  
Ofc. hrs PH TW 4PM Chao Zhang M 5pm

Last time: review of Lagrange's eqns

$$\frac{\partial \mathcal{L}}{\partial q_i} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i}; \quad \mathcal{L} = T - U \text{ for conservative holonomic systems}$$

Examples: a) simple pendulum, b) bead on rotating circular wire.

N.B. For b) we found eqn. of motion for bead:

$$\ddot{\theta} = \left( \omega^2 \cos \theta - \frac{g}{R} \right) \sin \theta$$

=> Eq. solns:  $\sin \theta = 0$  or  $\cos \theta = \frac{g}{R\omega^2}$  if  $\omega^2 > \frac{g}{R}$

Q: why isn't  $\sin \theta = 0$  a soln. for  $\omega^2 > \frac{g}{R}$ ?

A: it is, but we have for small  $\theta$

$$\ddot{\theta} = \left( \omega^2 \left( 1 - \frac{\theta^2}{2} + \dots \right) - \frac{g}{R} \right) \left( \theta - \frac{\theta^3}{3} + \dots \right)$$

$$\approx \underbrace{\left( \omega^2 - \frac{g}{R} \right)}_{\text{if } \omega^2 > g/R \Rightarrow \text{no restoring force!}} \theta$$

Q: what about  $\theta = \pi$  → always unstable  
Hint:  $\sin \theta \approx -(\theta - \pi) + \dots$

# LAGRANGIAN REVIEW CONT'D

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(1)

## Symmetries and Conservation Laws

Emmy Noether (1882-1935)

b. Erlangen, Germany, studied math  
Invited by D. Hilbert and F. Klein to  
join faculty at U Göttingen,

Rest of faculty refused  $\rightarrow$  Privatdozent,  
1933  $\rightarrow$  Bryn Mawr, Princeton I.A.S.

\* Noether's Theorem (1918) For every continuous symmetry of a mechanical system  $\exists$  a conservation law.

\* major contribution to abstract algebra

Examples: transl. sym.  $\Rightarrow$  momentum cons.  
time transl. sym.  $\Rightarrow$  energy cons.

Method of proof: transform Lagrangian under some symm. operation, show that  $\delta\mathcal{L} = 0 \Rightarrow \frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{q}} \right) = 0$

$\hookrightarrow$  conserved

Momentum: shift coordinates by const  $\vec{\epsilon}$

$$x_i \rightarrow x_i + \epsilon_i \quad \dot{x}_i \rightarrow \dot{x}_i \quad \Rightarrow T \rightarrow T$$

$$\text{Transl. inv.} \Rightarrow U(\vec{r} + \vec{\epsilon}) = U(\vec{r})$$

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example - grav. forces among  $N$  particles

$$U = - \sum_{i \neq j} \frac{G m_i m_j}{|\vec{r}_i - \vec{r}_j|} \quad \vec{r}_i \rightarrow \vec{r}_i + \delta \vec{r} \quad \text{same}$$

$$\text{So } \delta T = 0, \delta U = 0 \Rightarrow \delta \mathcal{L} = 0$$

Let  $x$ -coord. of all  $N$  particles change by  $\delta x_i$  !

$$\delta \mathcal{L} = \sum_i \frac{\partial \mathcal{L}}{\partial x_i} \delta x_i = 0$$

$$= \sum_i \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}_i} \delta x_i = \frac{d}{dt} \sum_i \frac{\partial \mathcal{L}}{\partial \dot{x}_i} \delta x_i$$

$\Rightarrow$  total momentum  $\vec{P} = (P_x, P_y, P_z)$  conserved.  $P_x$

Other remarks on Lagrangian method

1) Dissipative forces must be included explicitly:  $\frac{\partial \mathcal{L}}{\partial x} + \vec{F}_{\text{fric}} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}}$  (7.12)

2) Method of Lagrange multipliers to include constraints

a) express  $\mathcal{L}$  in terms of all coordinates

b) constraint equation  $f(x_1, x_2, \dots) = 0$

# Lagrange multipliers cont'd

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Then solve modified eqns

$$\frac{\partial \mathcal{L}}{\partial x} + \lambda \frac{\partial F}{\partial x} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}}, \text{ etc.}$$

$N+1$  eqns with  $N+1$  unknowns  $\rightarrow$  solve

3) Lagrangian for charge  $q$  in  $\vec{E}, \vec{B}$  fields

$$\mathcal{L}(\vec{r}, \dot{\vec{r}}, t) = \frac{1}{2} m \dot{\vec{r}}^2 - q (V - \dot{\vec{r}} \cdot \vec{A})$$

$$\Rightarrow \ddot{\vec{r}} = q (\vec{E} + \dot{\vec{r}} \times \vec{B})$$

$$\begin{aligned} \vec{E} &= -\nabla V - \frac{\partial \vec{A}}{\partial t} \\ \vec{B} &= \nabla \times \vec{A} \end{aligned}$$

# Chapter 13. Hamiltonian Mechanics

Consider Lagrangians that do not depend explicitly on time, and consider total t-derivative

$$\frac{d}{dt} \mathcal{L}(q_1, \dots, q_N, \dot{q}_1, \dots, \dot{q}_N) = \sum_i \frac{\partial \mathcal{L}}{\partial q_i} \dot{q}_i + \sum_i \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \ddot{q}_i + \frac{\partial \mathcal{L}}{\partial t}$$

① use  $\frac{\partial \mathcal{L}}{\partial q_i} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} = \dot{p}_i$

where  $p_i \equiv \frac{\partial \mathcal{L}}{\partial \dot{q}_i}$

"canonical momentum conjugate to  $q_i$ "  
 "generalized momentum" (same things)

②  $\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \ddot{q}_i = p_i \ddot{q}_i$

$$\Rightarrow \frac{d}{dt} \mathcal{L} = \sum_i (\dot{p}_i \dot{q}_i + p_i \ddot{q}_i)$$

$$= \frac{d}{dt} \sum_i (p_i \dot{q}_i)$$

$$\Rightarrow \frac{d}{dt} (p_i \dot{q}_i - \mathcal{L}) = 0$$

H "Hamiltonian" = T + V

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Restatement:

\* "time translational invariance" of  $\mathcal{L}$   
( $t \rightarrow t + \epsilon$   $\epsilon = \text{const}$  leaves  $\mathcal{L}$  invariant)

$$\Rightarrow \boxed{\frac{d}{dt} H = 0}$$

i.e. Total energy conserved

(2nd example of Noether's theorem!)

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$\mathcal{L} \rightarrow H$  is an example of Legendre transformation

$$\mathcal{L} = \mathcal{L}(q, \dot{q}) \quad H = H(q, p)$$

$p$  is momentum "conjugate to"  $q$

Math: function of 2 vars.  $f(x, y)$

$$df = \underbrace{\left(\frac{\partial f}{\partial x}\right)_y}_u dx + \underbrace{\left(\frac{\partial f}{\partial y}\right)_x}_v dy$$

$$= u dx + v dy \quad (*)$$

$u, x$  conjugate to each other  
 $v, y$  " " " " " "

Now notice  $d(yv) = ydv + vdy$   
Subtract from (\*) to get

$$d(\underbrace{f - yv}_g) = udx - ydv$$

$g$  is Legendre transform of  $f$   
we switched from  $f(x, y)$  to  $g(x, v)$   
where  $v$  is conjugate of  $y$ .

Aside

Familiar example from thermodynamics:

Fixed quantity of gas, independent variables  $S, V$

$u = u(S, V)$  Internal energy  $du = Tds - PdV$   
 $T, P$  conjugate to  $S, V$  respectively

Legendre transform to quantity w/  
independent variables  $S, P$

$H = H(S, P)$  Enthalpy  $dH = TdS + VdP$

where  $\left. \frac{\partial u}{\partial S} \right|_V = T$        $\left. \frac{\partial u}{\partial V} \right|_S = -P$