

9/12/22

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Announcements

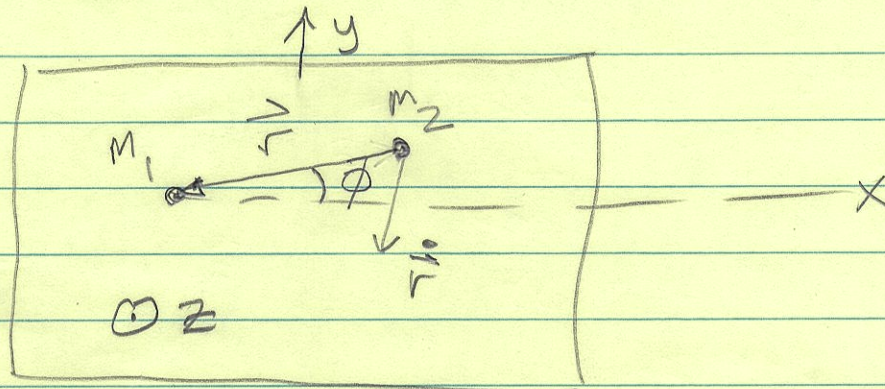
HW 2 due Sept. 19 Lectures recorded, link on web.
 Quiz 2 on Wednesday Sept. 14
 Discussion of quiz, test dates

Last time central force problems

$\mathcal{L} = \mathcal{L}(\phi) \Rightarrow \mathcal{L}$ conserved \Rightarrow motion in a plane

$$l = \mu r^2 \dot{\phi}$$

$$l = L_z = \mu \vec{r} \times \dot{\vec{r}}$$



$$\mathcal{L} = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2) - U(r)$$

ϕ

A.M. cons. : $\frac{\partial \mathcal{L}}{\partial \phi} = 0 = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\phi}} = \frac{d}{dt} (\underbrace{\mu r^2 \dot{\phi}}_{l = L_z})$
 (ϕ ignorable)

check that $\mu r^2 \dot{\phi}$ corresponds to L_z :

$$\vec{r} = r (\cos \phi, \sin \phi)$$

$$\dot{\vec{r}} = \dot{r} (\cos \phi, \sin \phi) + r (-\sin \phi, \cos \phi) \dot{\phi}$$

$$\vec{r} \times \dot{\vec{r}} = r^2 \dot{\phi} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \end{vmatrix} = r^2 \dot{\phi} \hat{z} \quad \checkmark$$

(1)

So l is constant of motion, $\dot{\phi} = \frac{l}{\mu r^2}$

$$\boxed{r} \quad \frac{\partial \mathcal{L}}{\partial r} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r}} \Rightarrow$$

$$\mu \ddot{r} = -\frac{dU}{dr} + \mu r \dot{\phi}^2$$

$$\boxed{\mu \ddot{r} = -\frac{dU}{dr} + \frac{l^2}{\mu r^3}}$$

1D, 1-body eqn. from 3D, 2-body eqn.
when l is specified ∇

* NB: $\frac{l^2}{\mu r^3} > 0$ has dimensions of a force F_{cf}

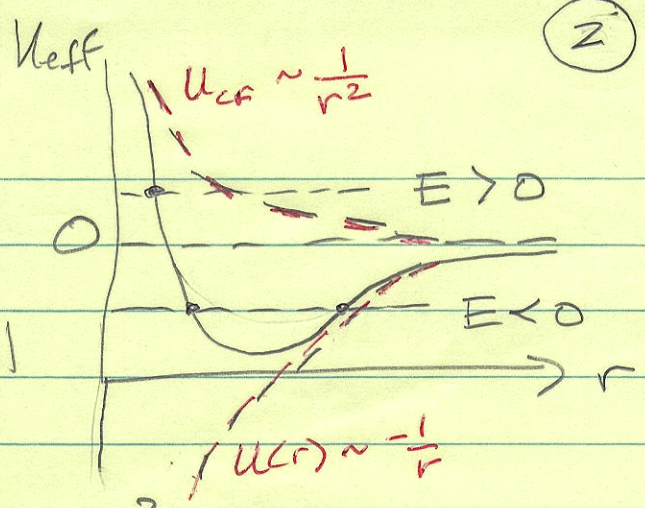
Not a new physical force, but shows up
in effective radial eqn. - "centrifugal force"
Sometimes convenient to write as gradient of its
own fictitious potential $F_{cf} = -\frac{dU_{cf}}{dr}$

$$U_{cf} = \frac{l^2}{2\mu r^2}$$

$$U_{eff} = U(r) + \frac{l^2}{2\mu r^2}$$

$$\Rightarrow \mu \ddot{r} = -\frac{dU_{eff}}{dr}$$

Plot $U_{eff}(r)$
for $U(r) = -\frac{GM_1 M_2}{r}$



NB zero of potential
at $r = \infty$

Energy $T + U = \frac{1}{2} \mu \dot{r}^2 + U_{eff}(r) = \text{const.} \equiv E$

$$E = \frac{1}{2} \mu \dot{r}^2 + U(r) + \frac{l^2}{2\mu r^2}$$

$E > 0$ or $E < 0$ determines class of
soln. to differential eqn.

$E > 0$ one crossing pt. \Rightarrow unbound orbit
 $E < 0$ two " " " bound orbit

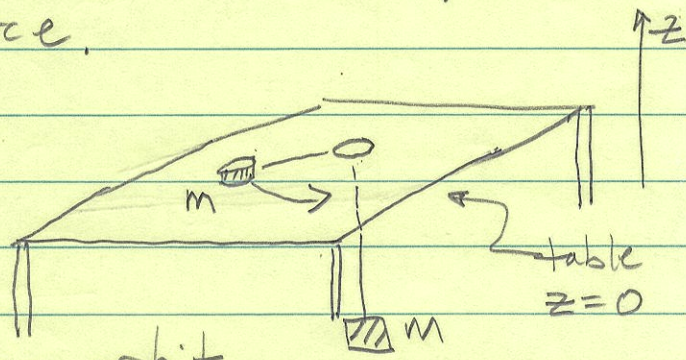
NB Book does only Kepler problem
with $U \sim \frac{1}{r}$, quite special in some
ways. But above discussion is general
for central force.

Ex. 1

Physics 1: $T = Mg$

$$T = \frac{mv^2}{r} \Rightarrow \text{circular orbit}$$

$$w/ \sqrt{r} = g \Rightarrow \omega = \dot{\theta} = \sqrt{g/r}$$



Gravity at earth's surface:

$$U = mgz = mg(r-a)$$

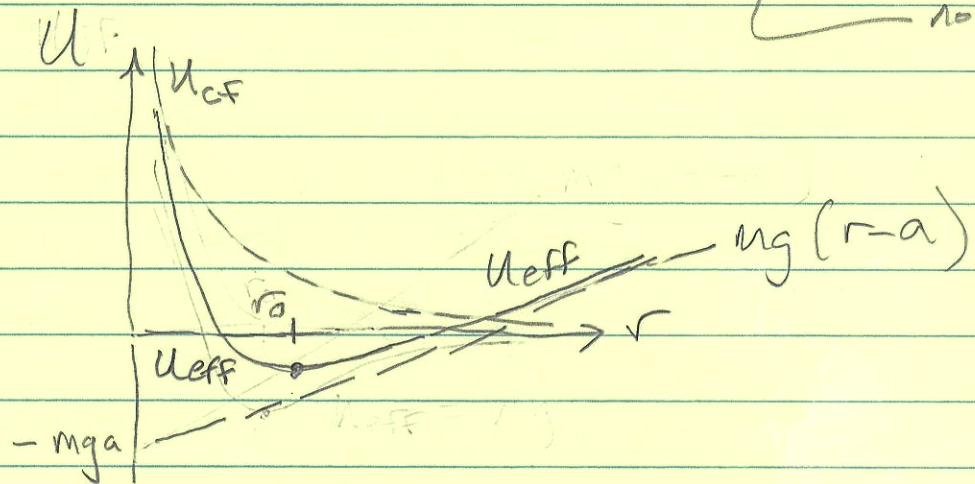
where a is length of string ($r-a < 0$)

Force is central, a.m. conserved

$$\mu = \frac{m}{2}$$

$$\Rightarrow U_{\text{eff}} = mg(r-a) + \frac{l^2}{2mr^2}$$

not $\mu \nabla$



We get our Physics I circular soln by solving for r_0 : (r where U_{eff} is minimum)

$$l = mr_0^2 \omega$$

$$\frac{\partial U_{\text{eff}}}{\partial r} = 0 = mg - \frac{l^2}{mr_0^3} = m \left(g - \frac{\omega^2}{r_0} \right)$$

$$\Rightarrow \omega = \sqrt{g/r_0} \quad \text{again}$$

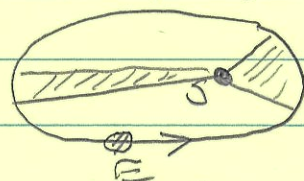
But now we see there are other solutions, other types of orbits with $E > E_0$!

These will not be conic sections since $U(r) \neq \frac{1}{r}$

"Kepler problem" ("1/r² problem")

Johannes Kepler 1571 - 1630

- Sought God in perfection of mathematics
- Obsessed w/ problem of planetary motion
- Math teacher Graz, Austria -
Planetary orbits' radii as radii of nested platonic solids
- Looked for better data - joined Tycho Brahe in Prague, Oranienborg
- Discovered 3 laws of planetary motion
 - orbits are conic sections (ellipses)
 - equal areas in equal times
 - $T^2 \sim R^3$
- 1st to ask why planets moved as they did. His theory: magnetism!
- His work essential to Newton's discovery of gravity 1/r² law.



$$U(r) = -\frac{GM_1M_2}{r}$$

so
$$U_{\text{eff}} = -\frac{GM_1M_2}{r} + \frac{l^2}{2\mu r^2}$$

