


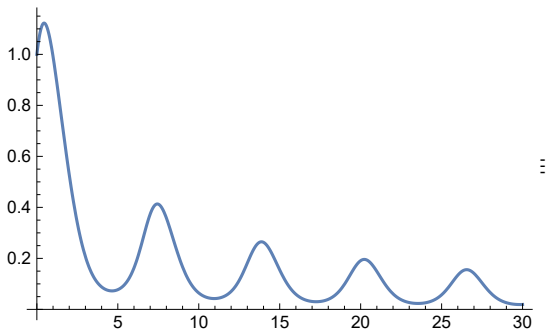
Example of how to use NDSolve

```
In[1]:= s = NDSolve[{y'[x] == y[x] Cos[x + y[x]], y[0] == 1}, y, {x, 0, 30}]
```

```
Out[1]= {{y -> InterpolatingFunction[ Domain: {{0., 30.}}  
Output: scalar ]}}
```

Note initial condition $y[0]=1$. Now use the solution s in a plot:

```
In[2]:= Plot[Evaluate[y[x] /. s], {x, 0, 30}, PlotRange -> All]
```



Try with driven damped pendulum

Our equation: $\frac{d^2}{dt^2} \phi + 2\beta \frac{d}{dt} \phi + \omega_0^2 \sin \phi - \gamma \omega_0^2 \cos \omega t = 0$

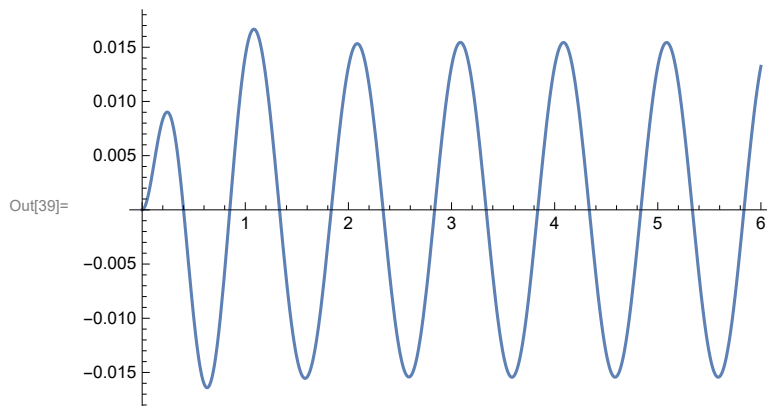
Parameters and initial conditions:

```
In[37]:=  $\omega = 2 \text{ Pi}; \omega_0 = 1.5 * \omega; \beta = \omega_0 / 4.; \gamma = 0.01;$ 
```

```
In[38]:= ddp1 = NDSolve[{ $\phi''[t] + 2 \beta \phi'[t] + \omega_0^2 \text{ Sin}[\phi[t]] - \gamma \omega_0^2 \text{ Cos}[\omega t] == 0,$   
 $\phi[0.] == 0., \phi'[0.] == 0.$ },  $\phi$ , {t, 0, 6}]
```


```
Out[38]= {{ $\phi$  -> InterpolatingFunction[ Domain: {{0., 6.}}  
Output: scalar ]}}
```

In[39]:= `Plot[Evaluate[$\phi[t]$ /. ddp1], {t, 0, 6}, PlotRange -> All]`

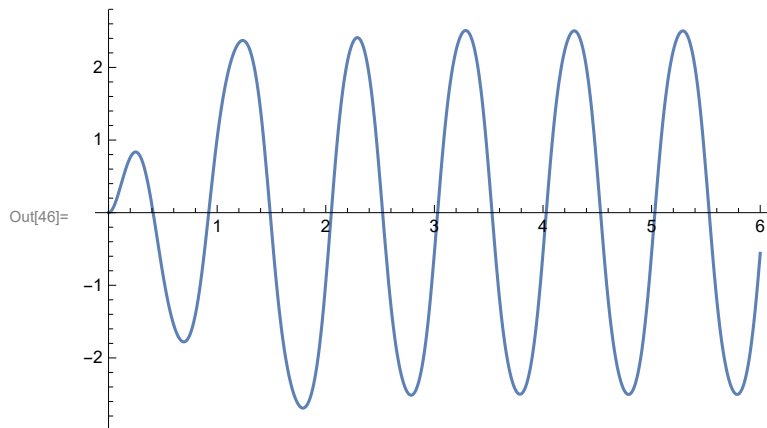


In[44]:= `$\omega = 2 \text{ Pi}$; $\omega_0 = 1.5 * \omega$; $\beta = \omega_0 / 4.$; $\gamma = .9$;`

In[45]:= `ddp1 = NDSolve[{ $\phi''[t] + 2 \beta \phi'[t] + \omega_0^2 \text{Sin}[\phi[t]] - \gamma \omega_0^2 \text{Cos}[\omega t] == 0$,
 $\phi[0.] == 0.$, $\phi'[0.] == 0.$ }, ϕ , {t, 0, 6}]`


Out[45]= `{ $\phi \rightarrow$ InterpolatingFunction[ Domain: {{0., 6.}}
Output: scalar]]}`

In[46]:= `Plot[Evaluate[$\phi[t]$ /. ddp1], {t, 0, 6}, PlotRange -> All]`

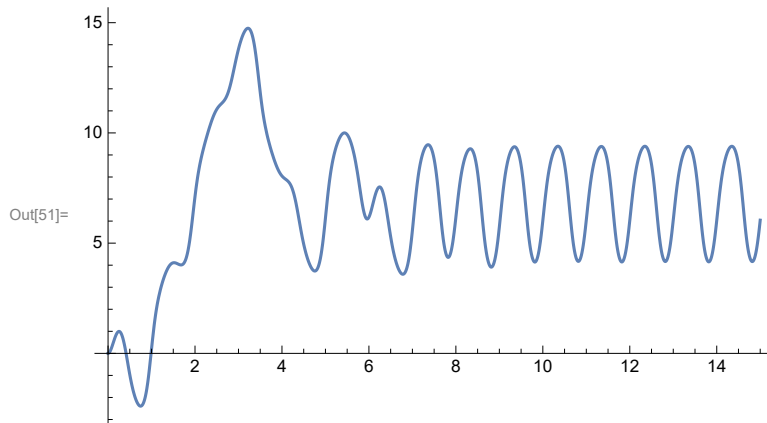


In[47]:= `$\omega = 2 \text{ Pi}$; $\omega_0 = 1.5 * \omega$; $\beta = \omega_0 / 4.$; $\gamma = 1.06$;`

In[50]:= `ddp1 = NDSolve[{ $\phi''[t] + 2 \beta \phi'[t] + \omega_0^2 \text{Sin}[\phi[t]] - \gamma \omega_0^2 \text{Cos}[\omega t] == 0$,
 $\phi[0.] == 0.$, $\phi'[0.] == 0.$ }, ϕ , {t, 0, 15}]`



Out[50]= `{ $\phi \rightarrow$ InterpolatingFunction[ Domain: {{0., 15.}}
Output: scalar]]}`

In[51]:= `Plot[Evaluate[$\phi[t]$ /. ddp1], {t, 0, 15}, PlotRange -> All]`

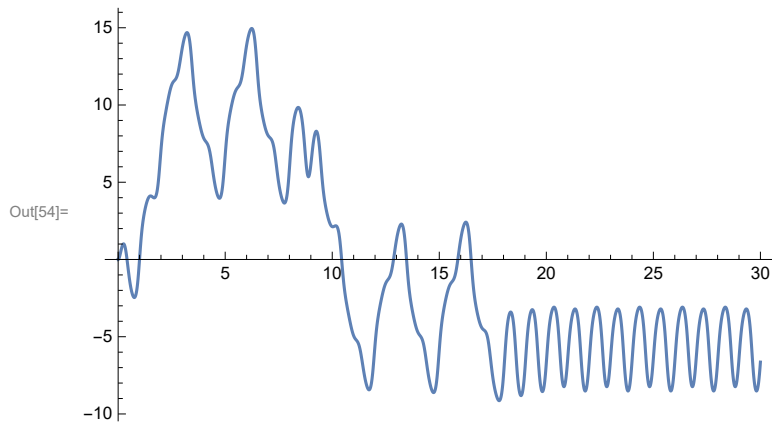


In[52]:= `$\omega = 2 \text{ Pi}$; $\omega_0 = 1.5 * \omega$; $\beta = \omega_0 / 4.$; $\gamma = 1.073$;`

In[53]:= `ddp1 = NDSolve[{ $\phi''[t] + 2 \beta \phi'[t] + \omega_0^2 \text{Sin}[\phi[t]] - \gamma \omega_0^2 \text{Cos}[\omega t] == 0$,
 $\phi[0.] == 0.$, $\phi'[0.] == 0.$ }, ϕ , {t, 0, 30}]`

Out[53]= `{ { $\phi \rightarrow \text{InterpolatingFunction}$ [  Domain: {{0., 30.}}
Output: scalar]] }`

In[54]:= `Plot[Evaluate[$\phi[t]$ /. ddp1], {t, 0, 30}, PlotRange -> All]`



In[55]:= `Plot[Evaluate[$\phi[t]$ /. ddp1], {t, 20, 30}, PlotRange \rightarrow {-9., -7.5}]`

