

PHY4324–Electromagnetism II

Fall 2011

Test 1 – 55 minutes

Sept. 26, 2011

No other materials except calculators allowed. If you can't do one part of a problem, solve subsequent parts in terms of unknown answer—define clearly. Do 3 of the 4 problems, CLEARLY indicating which you want graded by circling the problem number!. Each problem is worth 10 pts., for maximum of 30 points.

1. Consider a superposition of two linear polarized waves traveling in the z direction with electric field

$$\mathbf{E}(z, t) = \text{Re} \left[\hat{x} E_{10} e^{i(kz - \omega t)} + \hat{y} E_{20} e^{i(kz - \omega t)} \right], \quad (1)$$

where $E_{10} = E_1$ is real but $E_{20} = E_2 e^{i\phi}$, where E_1 and E_2 are real and positive, and the real number ϕ is the *phase difference* between the two components.

(a) (2 pts.) For $\phi = 0$, the resulting wave is still linearly polarized. What is the amplitude of the total electric field, and what is the direction of the polarization vector?

(b) (4 pts.) For $\phi = \pi/2$ and $E_1 = E_2$, the resulting wave is *circularly polarized*. What is the magnitude of the electric field as a function of time t at the point $z = 0$? In which direction does the electric field rotate (clock- or counterclockwise) as one views the wave coming towards the observer along the z -axis (i.e., you are sitting way down the positive z axis looking in the $-z$ direction).

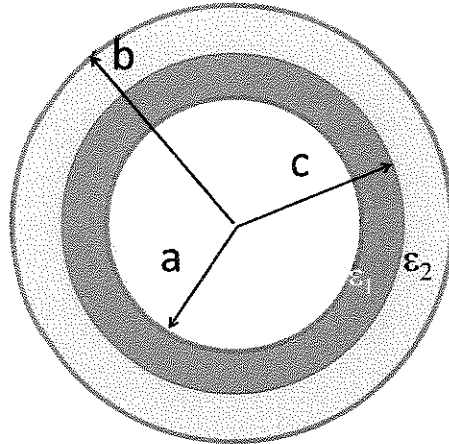
- (c) (4 pts.) For $\phi = \pi/2$ and $E_1 \neq E_2$, the wave is *elliptically polarized*. Determine the electric field at $z = 0$ as a function of time.

2. A long solenoid of height X is made of thin wire (diameter d) wrapped tightly around a cylinder of radius a . The density of conduction electrons in the wire is n , and the mean free time between collisions is τ_i .
- (a) (4 pts.) In terms of the quantities given, the electron charge and mass e and m , respectively, find the conductivity σ and the resistance R of the coil (Hint: find the total length of the wire).

(b) (4 pts.) In terms of the conductivity σ and/or R (no need to substitute from part (a)), what is the self-inductance of the coil?

(c) (2 pts.) At $t = 0$, the solenoid is connected to a battery. Find the characteristic delay time after which the current in the solenoid approaches its steady-state value.

3. A t -dependent voltage $V(t) = V_0 \cos(\omega t)$ is applied to a capacitor, which consists of two concentric conducting spheres of radii a and b ($a < b$). The space in



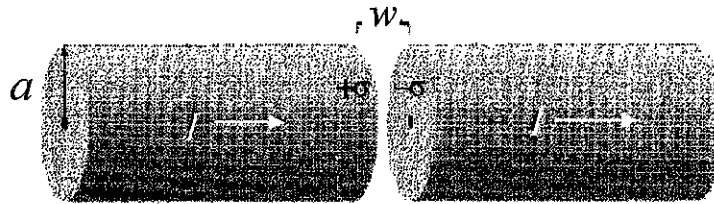
between the spheres is filled with two spherical shells made of *different* insulators, so that

$$\epsilon = \begin{cases} \epsilon_1 & \text{for } a < r < c \\ \epsilon_2 & \text{for } c < r < b. \end{cases}$$

(a) (4 pts.) Find the capacitance C .

(b) (4 pts.) Find the displacement current (direction and magnitude) in terms of C .

(c) (2 pts.) Find the magnetic field produced by the displacement current.



4. A fat wire, radius a , carries a constant current I , uniformly distributed over its cross section. A narrow gap in the wire of width $w \ll a$, forms a parallel plate capacitor.
- (a) (4 pts.) Find \mathbf{E} and \mathbf{B} in the gap as functions of the distance s from the axis and of the time t (assume charge density σ is zero at $t = 0$).

- (b) (4 pts.) Find the energy density u_{em} and the Poynting vector \mathbf{S} in the gap. What are the direction and magnitude of \mathbf{S} ?

- (c) (2 pts.) Verify the conservation of energy in the gap locally. (Hint: you may need $\nabla \cdot \mathbf{v} = \frac{1}{s} \frac{\partial}{\partial s}(sv_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$.)

Solns test 1
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(1)

1) wave $\vec{E} = \text{Re} \left[\hat{x} E_1 e^{i(kz - \omega t)} + \hat{y} E_2 e^{i(kz - \omega t)} \right]$

$\vec{E}_2 = E_2 e^{i\phi}$

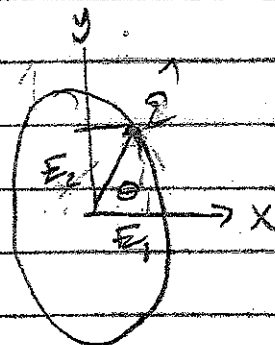
a) For $\phi = 0$ $\vec{E} = (E_1 \hat{x} + E_2 \hat{y}) \cos(kz - \omega t)$

Amplitude $|\vec{E}| = \sqrt{E_1^2 + E_2^2}$

polarization $\hat{\Sigma} = \frac{E_1 \hat{x} + E_2 \hat{y}}{\sqrt{E_1^2 + E_2^2}}$

$\theta = \tan^{-1} \frac{E_2}{E_1}$

independent of t

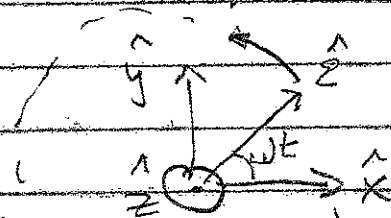


b) $z=0, \phi = \pi/2, E_1 = E_2$

$\vec{E} = \text{Re} \left[(E_1 \hat{x} + i E_1 \hat{y}) e^{i(kz - \omega t)} \right]$

$= E_1 (\hat{x} \cos \omega t - \hat{y} \sin \omega t)$

Amplitude $= \sqrt{E_1^2 \cos^2 \omega t + E_1^2 \sin^2 \omega t}$
 $= E_1$



For $t \geq 0$

$\hat{\Sigma}$ rotates counterclockwise

(left circularly polarized)

c) $\epsilon = 0 \quad \phi = \pi/2$

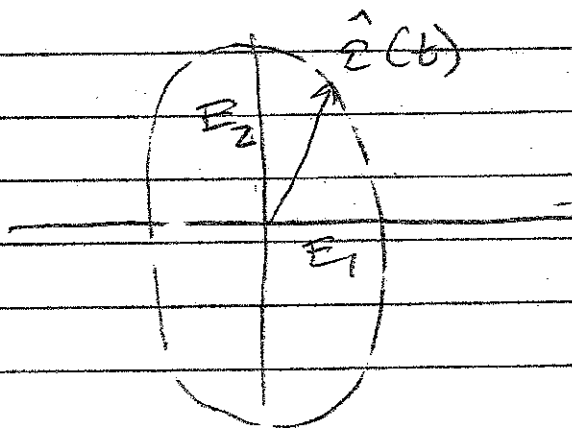
$$\vec{E} = \text{Re} \left[(E_1 \hat{x} + i E_2 \hat{y}) e^{i(\dots)} \right]$$

$$= E_1 \hat{x} \cos \omega t + E_2 \hat{y} \sin \omega t$$

Amplitude = $\sqrt{E_1^2 \cos^2 \omega t + E_2^2 \sin^2 \omega t}$

not a constant!

angle $\tan^{-1} \frac{E_2 \sin \omega t}{E_1 \cos \omega t}$



2) Solenoid

(a)

③

Tightly packed solenoid

\Rightarrow length of wire

$$= l = 2\pi a X / d$$

resistance

$$R = \rho \frac{l}{A} = \frac{1}{\sigma} \frac{(2\pi a X)}{\pi d^2 / 4}$$

$$R = \frac{8aX}{\sigma d^3} = \frac{8aXm}{ne^2 \tau_i d^3}$$

Drude conductivity

$$\sigma = \frac{ne^2 \tau_i}{m}$$

(b) $B = \mu_0 N I$ where $N = \frac{1}{d}$ turns/length

Energy stored is

$$W = \frac{1}{2\mu_0} \int B^2 dz = \frac{\mu_0}{2} N^2 (\pi a^2 X) I^2 = \frac{1}{2} L I^2$$

$$\Rightarrow L = \mu_0 N^2 (\pi a^2 X) = \mu_0 \frac{\pi a^2 X}{d^2}$$

(c) Delay time for an inductor

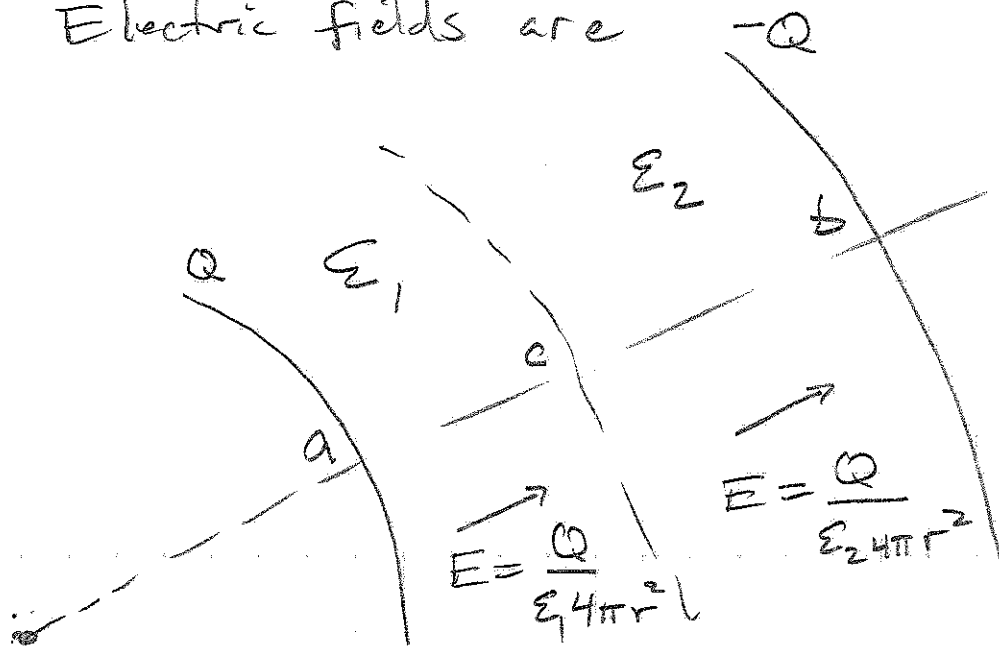
$$\tau = L/R = \frac{\mu_0 \pi a^2 X / d^2}{8aX / (\sigma d^3)}$$

$$\tau = \frac{\pi}{8} \mu_0 \sigma a d = \frac{\pi}{8m} \mu_0 n e^2 \tau_i a d$$

3) (a) Capacitance: put Q on inner conductor

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Electric fields are



$$V = V(a) - V(b) = - \int_b^a \vec{E} \cdot d\vec{r} = \int_a^b E dr$$

$$= \frac{Q}{4\pi\epsilon_1} \left(\frac{1}{a} - \frac{1}{c} \right) + \frac{Q}{4\pi\epsilon_2} \left(\frac{1}{c} - \frac{1}{b} \right)$$

$$Q = CV$$

\Rightarrow

$$C = \frac{1}{\frac{1}{4\pi\epsilon_1} \left(\frac{1}{a} - \frac{1}{c} \right) + \frac{1}{4\pi\epsilon_2} \left(\frac{1}{c} - \frac{1}{b} \right)}$$

(b) Displacement current density $\vec{J}_d = \frac{\partial \vec{D}}{\partial t}$

$$\text{Displacement current } I_d = \int \vec{J}_d \cdot d\vec{a} = J_d 4\pi r^2$$

\vec{D} is displacement field due to free charges!

$$\vec{D} = \frac{Q}{4\pi r^2} \hat{r} \Rightarrow J_d = \frac{\dot{Q}}{4\pi r^2} = \frac{C}{4\pi r^2} \dot{V}$$

$$\Rightarrow \vec{J}_d = -\frac{C}{4\pi r^2} V_0 \omega \sin \omega t$$

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$$\boxed{I_d = -C V_0 \omega \sin \omega t}$$

(c) Magnetic field due to displacement current

$$= \underline{\underline{0}} \quad \text{by symmetry}$$

since \vec{J}_d is radial $\propto \hat{r}$

4) Wire gap

(a) Wire "fat" \Rightarrow surface large

$$\Rightarrow \vec{E} = \frac{\sigma}{\epsilon_0} \hat{z}; \quad \sigma = \frac{Q}{\pi a^2}; \quad Q = It$$

\downarrow it's constant

$$\text{so } \boxed{\vec{E} = \frac{It}{\pi \epsilon_0 a^2} \hat{z}}$$

Ampereian loop radius s in gap:



$$\oint \vec{B} \cdot d\vec{\ell} = \oint (\vec{J}_f + \vec{J}_d) \cdot d\vec{a}$$

$$B 2\pi s = \mu_0 \epsilon_0 \frac{\partial E}{\partial t} \pi s^2$$

$$\Rightarrow \boxed{\vec{B}(s,t) = \frac{\mu_0 I s}{2\pi a^2} \hat{\phi}}$$

(6)

$$(b) \quad u_{em} = \frac{1}{2} \left(\epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right)$$

$$= \frac{1}{2} \left[\epsilon_0 \left(\frac{I t}{\pi \epsilon_0 a^2} \right)^2 + \frac{1}{\mu_0} \left(\frac{\mu_0 I S}{2 \pi a^2} \right)^2 \right]$$

$$= \frac{\mu_0 I^2}{2 \pi^2 a^4} \left[(c t)^2 + \frac{S^2}{4} \right]$$

used

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B}) = \frac{1}{\mu_0} \left(\frac{I t}{\pi \epsilon_0 a^2} \right) \left(\frac{\mu_0 I S}{2 \pi a^2} \right) (-\hat{s})$$

$$\vec{S} = -\frac{I^2 t S}{2 \pi^2 \epsilon_0 a^4} \hat{s}$$

used

$$\hat{z} \times \hat{\phi} = -\hat{s}$$

(c) Conservation of energy $\frac{\partial u_{em}}{\partial t} + \nabla \cdot \vec{S} = 0$

$$\frac{\partial u_{em}}{\partial t} = \frac{I^2 t}{\pi^2 \epsilon_0 a^4} \quad -\nabla \cdot \vec{S} = \frac{I^2 t}{2 \pi^2 \epsilon_0 a^4} \nabla \cdot (s \hat{s})$$

note $\nabla \cdot (s \hat{s}) = \frac{1}{s} \frac{\partial}{\partial s} (s^2) = 2$

$$\Rightarrow -\nabla \cdot \vec{S} = \frac{I^2 t}{\pi^2 \epsilon_0 a^4} \quad \checkmark$$