

PHZ3113– to Theoretical Physics

Fall 2008

Test 2 – 55 minutes

Oct. 29, 2008

Solutions

Useful formulae:

$$\vec{\nabla}\psi = \frac{\partial\psi}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial\psi}{\partial\theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial\psi}{\partial\phi} \hat{\phi}. \quad (1)$$

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial\theta} (\sin\theta A_\theta) + \frac{1}{r \sin\theta} \frac{\partial A_\phi}{\partial\phi} \quad (2)$$

$$\begin{aligned} \hat{i} &= \sin\theta \cos\phi \hat{r} + \cos\theta \cos\phi \hat{\theta} - \sin\phi \hat{\phi} & x &= r \sin\theta \cos\phi \\ \hat{j} &= \sin\theta \sin\phi \hat{r} + \cos\theta \sin\phi \hat{\theta} + \cos\phi \hat{\phi} & y &= r \sin\theta \sin\phi \\ \hat{k} &= \cos\theta \hat{r} - \sin\theta \hat{\theta} & z &= r \cos\theta. \end{aligned} \quad (3)$$

$$\vec{\nabla} \left(\frac{1}{|\vec{r} - \vec{r}'|} \right) = -\vec{\nabla}' \left(\frac{1}{|\vec{r} - \vec{r}'|} \right) = -\frac{\widehat{\vec{r} - \vec{r}'}}{|\vec{r} - \vec{r}'|^2}, \quad (4)$$

where

$$\widehat{\vec{r} - \vec{r}'} = \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|}. \quad (5)$$

$$\vec{\nabla}\psi = \sum_i \hat{q}_i \frac{1}{h_i} \frac{\partial\psi}{\partial q_i}. \quad (6)$$

1. Consider a vector field $\vec{v} = 2x\hat{x} - z\hat{y} + y\hat{z}$. Verify Stokes' theorem using the circle of radius a in the xy plane, bounding the surface A of the hemisphere above the (x, y) plane given by $x^2 + y^2 + z^2 = a^2$.

(a) (5 pts) Calculate $\int_A \vec{\nabla} \times \vec{v} \cdot d\vec{a}$

$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ 2x & -z & y \end{vmatrix} = 2\hat{i} \quad (7)$$

$$= 2(\sin\theta \cos\phi \hat{r} + \cos\theta \cos\phi \hat{\theta} - \sin\phi \hat{\phi}), \quad (8)$$

where in the last step I expressed the answer in spherical coordinates because we need the integral over a hemisphere, which has normal \hat{r} . The magnitude of the area element on the surface is $da = a^2 \sin \theta d\theta d\phi$. Therefore

$$\vec{\nabla} \times \vec{v} \cdot d\vec{a} = 2 \sin \theta \cos \phi da = 2a^2 \sin^2 \theta \cos \phi d\theta d\phi, \quad (9)$$

and the integral is

$$\int \vec{\nabla} \times \vec{v} \cdot d\vec{a} = \int_0^{\pi/2} a^2 \sin^2 \theta d\theta \int_0^{2\pi} d\phi \cos \phi = 0 \quad (10)$$

because the $\cos \phi$ is integrated over a period.

(b) (5 pts) Calculate $\oint_{\partial A} \vec{v} \cdot d\vec{r}$.

Method 1): For the circular path in the xy plane, $d\vec{r} = a d\phi \hat{\phi}$, so we need to express \vec{v} in terms of spherical coordinates:

$$\begin{aligned} \vec{v} = & (2a \sin \theta \cos \phi)(\sin \theta \cos \phi \hat{r} + \cos \theta \cos \phi \hat{\theta} - \sin \phi \hat{\phi}) \\ & - a \cos \theta (\sin \theta \sin \phi \hat{r} + \cos \theta \sin \phi \hat{\theta} + \cos \phi \hat{\phi}) \\ & + a \sin \theta \sin \phi (\cos \theta \hat{r} - \sin \theta \hat{\theta}). \end{aligned} \quad (11)$$

For the circle in the xy plane, $\theta = \pi/2$ is fixed. The $\hat{\phi}$ component of \vec{v} is then $-2a \cos \phi \sin \phi - 0 + 0 = -2a \cos \phi \sin \phi$. So

$$\oint_{\partial A} \vec{v} \cdot d\vec{r} = \int_0^{2\pi} a d\phi (-2a \cos \phi \sin \phi) = 0 \quad (12)$$

Method 2): in Cartesian coordinates, $\vec{v} \cdot d\vec{r} = 2x dx - z dy + y dz$. Over the circle $dz = 0$, $z = 0$, and $dx = d(a \cos \phi) = -a \sin \phi d\phi$. So again

$$\oint_{\partial A} \vec{v} \cdot d\vec{r} = \int_0^{2\pi} a d\phi (-2a \cos \phi \sin \phi) = 0 \quad (13)$$

2. Given the matrices

$$A = \begin{bmatrix} 1 & -1 \\ 0 & i \end{bmatrix}; \quad B = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & -3 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & -2 \end{bmatrix} \quad (14)$$

(a) (2 pts) calculate $[A, B]$

$$[A, B] \equiv AB - BA = \begin{bmatrix} 1 & 1-i \\ 1-i & -1 \end{bmatrix} \quad (15)$$

(b) (2 pts) calculate $A^\dagger BA$

$$\begin{pmatrix} 0 & i \\ i & -2i \end{pmatrix} \quad (16)$$

(c) (3 pts) solve the equation $C\vec{r} = \vec{k}$, where $\vec{r} = (x, y, z)$ and $\vec{k} = (-2, 1, 0)$, for x, y, z by matrix methods.

$$C^{-1} = \begin{bmatrix} \frac{2}{5} & 1 & \frac{1}{5} \\ 0 & 1 & 0 \\ \frac{1}{5} & 1 & -\frac{2}{5} \end{bmatrix}, \quad (17)$$

so

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \frac{2}{5} & 1 & \frac{1}{5} \\ 0 & 1 & 0 \\ \frac{1}{5} & 1 & -\frac{2}{5} \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{5} \\ 1 \\ \frac{3}{5} \end{bmatrix} \quad (18)$$

(d) (3 pts) which of the matrices is orthogonal? Why?

$$B^T = B^{-1}.$$

3. (a) (5 pts) Give an example of a family of functions δ_n which satisfy the conditions for their limit as $n \rightarrow \infty$ to be the Dirac δ -function, and state what these conditions are. If you can't define the functions mathematically, sketch them.

We want functions normalized to 1 whose width gets narrower as $n \rightarrow \infty$. We did a couple of examples in class, and there are many of them, but the simplest is the sequence of "step" or "window" functions:

$$\delta_n(x) = \begin{cases} 0 & |x| > \frac{1}{2n} \\ n & |x| < \frac{1}{2n} \end{cases} \quad (19)$$

(b) (5 pts) Evaluate $\int_0^\infty \delta(x^2 - 4)e^x dx$

$$\delta(x^2 - 4) = \frac{1}{|2x|_{x=2}} \delta(x - 2) + \frac{1}{|2x|_{x=-2}} \delta(x + 2), \quad (20)$$

but only the 1st root is contained in the integration range, so

$$\int_0^\infty \delta(x^2 - 4)e^x dx = \frac{1}{4} \int_0^\infty \delta(x - 2)e^x dx = e^2/4 \quad (21)$$

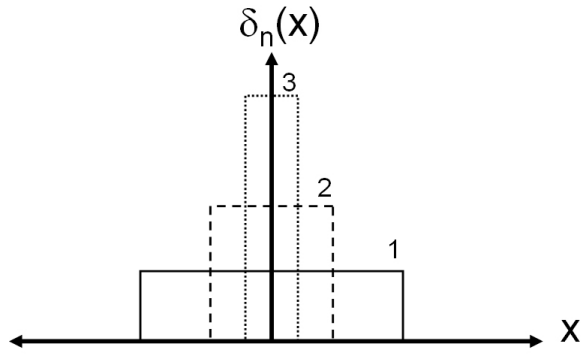


FIG. 1: Family $\delta_n(x)$.

4. Consider the transformations from coordinates (x, y) to (x', y') and from (x'', y'') to (x', y') given by

$$\begin{aligned} x' &= (\sqrt{3}x + y)/2 ; & y' &= (\sqrt{3}y - x)/2 ; \\ x' &= (x'' + y'')/\sqrt{2} ; & y' &= (y'' - x'')/\sqrt{2} \end{aligned} \quad (22)$$

Find the transformation from (x, y) to (x'', y'') . [Hint: write the transformation matrices carefully and make sure they correspond to the given equations. They must all be orthogonal matrices.]

$$\begin{aligned} \begin{bmatrix} x' \\ y' \end{bmatrix} &= \begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} ; & \begin{bmatrix} x' \\ y' \end{bmatrix} &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} x'' \\ y'' \end{bmatrix} \\ \Rightarrow \begin{bmatrix} x'' \\ y'' \end{bmatrix} &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}^{-1} \begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \frac{1+\sqrt{3}}{2\sqrt{2}} & \frac{1-\sqrt{3}}{2\sqrt{2}} \\ \frac{-1+\sqrt{3}}{2\sqrt{2}} & \frac{1+\sqrt{3}}{2\sqrt{2}} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \end{aligned} \quad (23)$$

5. (a) (5 pts) Calculate the arc length in the plane ds^2 for the coordinate system, u, v such that

$$x = u(1 - v) ; \quad y = u\sqrt{2v - v^2} \quad (24)$$

$$\begin{aligned} ds^2 &= dx^2 + dy^2 = \left(\frac{\partial x}{\partial u} du + \frac{\partial x}{\partial v} dv \right)^2 + \left(\frac{\partial y}{\partial u} du + \frac{\partial y}{\partial v} dv \right)^2 \\ &= ((1 - v)du - u dv)^2 + \left((\sqrt{2v - v^2})du + \frac{u(1 - v)}{\sqrt{2v - v^2}} dv \right)^2 \\ &= du^2 + dv^2 \left(\frac{u^2}{v(2 - v)} \right) \equiv h_u^2 du^2 + h_v^2 dv^2 \end{aligned} \quad (25)$$

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- (b) (5 pts) Determine the scale factors h_u and h_v , and use them to give an expression for the gradient of a scalar field ψ in these coordinates.
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$$h_u = 1 \quad ; \quad h_v = u(2v - v^2)^{-1/2} \quad (26)$$

so

$$\vec{\nabla}\psi = \hat{u} \frac{\partial\psi}{\partial u} + \hat{v} \frac{\sqrt{2v - v^2}}{u} \frac{\partial\psi}{\partial v} \quad (27)$$

6. (a) (4 pts) Given an arbitrary charge distribution $\rho(\vec{r})$, the electrostatic potential Φ is

$$\Phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} d\tau'. \quad (28)$$

Find the electrostatic field $\vec{E} = -\vec{\nabla}\Phi$.

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int d\tau' \frac{\rho(\vec{r}') \widehat{\vec{r} - \vec{r}'}}{(\vec{r} - \vec{r}')^2} \quad (29)$$

- (b) (3 pts) The charge density of a charge Q spread uniformly over a ring of radius R (centered at the origin, lying in the $x - y$ plane) can be expressed in terms of δ -functions in cylindrical coordinates, $\rho(\vec{r}) = A\delta(r - R)\delta(z)$, where A is a constant. Find A .
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Total charge must equal

$$\begin{aligned} Q &= \int d\tau \rho(\vec{r}) = \int_0^\infty r dr \int_0^{2\pi} d\theta \int_{-\infty}^\infty dz A\delta(r - R)\delta(z) \\ &= RA \cdot 2\pi \quad \Rightarrow \quad A = \frac{Q}{2\pi R} \end{aligned} \quad (30)$$

- (c) (3 pts) Using your result from parts a) and b), evaluate the electric field for the ring of charge at a point \vec{r} on the z axis a distance R above the plane of the ring. [Hint. Think before you calculate: in which direction will \vec{E} point?]
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\vec{E} must point in z direction by symmetry. Therefore we are only interested in the z component. For the geometry given $\vec{r} = R\hat{z}$, and $\vec{r}' = R\hat{r}$ (cylindrical). Therefore

$$\begin{aligned} \vec{E}(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \int d\tau' \frac{\rho(\vec{r}') \widehat{\vec{r} - \vec{r}'}}{(\vec{r} - \vec{r}')^2} = \frac{1}{4\pi\epsilon_0} \int d\tau' \frac{\rho(\vec{r}')(\vec{r} - \vec{r}')}{(\vec{r} - \vec{r}')^3} \\ &= \frac{A}{4\pi\epsilon_0} \int_0^\infty r' dr' \int_0^{2\pi} d\theta' \int_{-\infty}^\infty dz' \delta(r - R)\delta(z) \frac{R\hat{z} - R\hat{r}}{(R^2 + R^2)^{3/2}} \end{aligned} \quad (31)$$

where the denominator has the form shown because $\vec{r} \cdot \vec{r}' = 0$ and $|\vec{r}'| = |\vec{r}| = R$. The \hat{r} term will vanish due to the θ integration, so we keep just the z component as the hint suggests, and perform the integrals over the δ functions, as well as the θ integration, which is trivial:

$$\vec{E}(\vec{r} = R\hat{z}) = \frac{A}{4\pi\epsilon_0 R} \hat{z} = \frac{Q}{8\pi^2\epsilon_0 R^2} \hat{z} \quad (32)$$
