

1. Expand
$$x/(e^x - 1)$$
 to order x^2 for $x \ll 1$.

$$\frac{x}{1+x+x^2/2!+x^3/3!+\dots-1}$$
(1)

To order x^2 ,

$$\frac{1}{(1+x/2!+x^2/3!+\dots)} \simeq \frac{1}{1+(x/2!+x^2/3!)},$$
(2)

which is an alternating geometric series in $(x/2! + x^2/3!)$, so

$$= 1 - (x/2! + x^2/3!) + (x/2! + x^2/3!)^2 \simeq 1 - x/2 + x^2/12$$
(3)

2. The equation of state for a van der Waals gas is

$$\left(p + \frac{a}{V^2}\right)(V - b) = RT,\tag{4}$$

where a, b and R are constants. Consider two experiments on such a gas confined to a cylinder where you may control p, V and/or T.

(a) Hold T constant and find dV/dp.

$$d\left[\left(p+\frac{a}{V^2}\right)(V-b)\right] = d(RT) = 0 \tag{5}$$

 \mathbf{SO}

$$\frac{dV}{dp} = \frac{b - V}{\frac{a}{V^2} + \frac{2(b - V)a}{V^3} + p} = \frac{(b - V)V^3}{pV^3 - aV + 2ab}$$
(6)

(b) Hold p constant and find dV/dT. Similarly if dp = 0,

$$\frac{dV}{dT} = \frac{R}{\frac{a}{V^2} + \frac{2(b-V)a}{V^3} + p} = \frac{RV^3}{pV^3 - aV + 2ab}$$
(7)

3. Change variables x = u + v, y = u - v, to rewrite the differential equation

$$\frac{\partial^2 w}{\partial x^2} - \frac{\partial^2 w}{\partial y^2} = 1 \tag{8}$$

Sketch solution. First invert u = (x + y)/2, v = (x - y)/2. calculate partial derivatives:

$$\frac{\partial w}{\partial x} = \frac{\partial w}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial v} \frac{\partial v}{\partial x} = \frac{1}{2} \left[\frac{\partial w}{\partial u} + \frac{\partial w}{\partial v} \right]$$
$$\Rightarrow \frac{\partial}{\partial x} = \frac{1}{2} \left(\frac{\partial}{\partial u} + \frac{\partial}{\partial v} \right)$$
(9)

and similarly for y

$$\frac{\partial}{\partial y} = \frac{1}{2} \left(\frac{\partial}{\partial u} - \frac{\partial}{\partial v} \right) \tag{10}$$

The 2nd partials are e.g.

$$\frac{\partial^2 w}{\partial x^2} = \frac{1}{4} \left(\frac{\partial}{\partial u} + \frac{\partial}{\partial v} \right) \left(\frac{\partial}{\partial u} + \frac{\partial}{\partial v} \right) w$$
$$= \frac{1}{4} \left[\frac{\partial^2 w}{\partial u^2} + \frac{\partial^2 w}{\partial v^2} + 2 \frac{\partial^2 w}{\partial u \partial v} \right]$$
(11)

and similarly for y except the coefficient of the mixed partial derivative is negative. Constructing $\frac{\partial^2 w}{\partial x^2} - \frac{\partial^2 w}{\partial y^2} = 1$, we find

$$\frac{\partial^2 w}{\partial u \partial v} = 1. \tag{12}$$

4. Evaluate the integral

$$\int_{y=0}^{\pi} dy \int_{x=y}^{\pi} dx \frac{\sin x}{x}.$$
 (13)

Reverse order of integrations:

$$\int_0^\pi dx \frac{\sin x}{x} \int_0^x dy = \int_0^\pi dx \sin x = -\cos x|_0^\pi = 2.$$
 (14)

5. If $\vec{\nabla} \cdot \vec{A} = 0$ and $\vec{\nabla} \cdot \vec{B} = 0$, show that

$$\vec{\nabla} \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \vec{\nabla})\vec{A} - (\vec{A} \cdot \vec{\nabla})\vec{B}.$$
(15)

[Hint: $\epsilon_{ijk}\epsilon_{i\ell m} = \delta_{j\ell}\delta_{km} - \delta_{jm}\delta_{k\ell}$]

$$\begin{split} [\vec{\nabla} \times (\vec{A} \times \vec{B})]_i &= \epsilon_{ijk} \nabla_j (\vec{A} \times \vec{B})_k = \epsilon_{ijk} \epsilon_{kmn} A_m B_n = \epsilon_{kij} \epsilon_{kmn} \nabla_j A_m B_n \\ &= (\delta_{im} \delta_{jn} - \delta_{in} \delta_{jm}) \nabla_j A_m B_n = \nabla_j A_i B_j - \nabla_j A_j B_i \\ &= A_i (\vec{\nabla} \cdot B) + (\vec{B} \cdot \vec{\nabla}) A_i - B_i (\vec{\nabla} \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla}) B_i = (\vec{B} \cdot \vec{\nabla}) A_i - (\vec{A} \cdot \vec{\nabla}) B_i, \end{split}$$

where in the last step I used the info given that both vectors had zero divergence, and the product rule of differentiation.

6. Look for a minimum of the function 1/x + 4/y + 9/z for x, y, z > 0 and x + y + z = 12.

Lagrange multipliers:

$$F = 1/x + 4/y + 9/z + \lambda(x + y + z - 12),$$
(16)

so minimize:

$$\frac{\partial F}{\partial x} = -\frac{1}{x^2} + \lambda = 0 \quad ; \quad \frac{\partial F}{\partial y} = -\frac{4}{y^2} + \lambda = 0 \quad ; \quad \frac{\partial F}{\partial z} = -\frac{9}{z^2} + \lambda = 0. \tag{17}$$

Together with the constraint equation x + y + z = 12 this system can be easily solved by noting that the solutions should be positive. Therefore by eliminating λ we find x = y/2 = z/3. The constraint equation is then x + 2x + 3x = 6, so x = 2, y = 4, z = 6 is a solution. Function takes minimum value of 3 here.

7. (Extra credit) Consider the vector $\vec{V} = 4y\hat{i} + x\hat{j} + 2z\hat{k}$ and the scalar field $\psi(x, y, z) = 1/\sqrt{x^2 + y^2 + z^2}$.

(a) show
$$\vec{\nabla} \times \vec{V} = -3\hat{k}$$

$$\epsilon_{ijk} \nabla_j v_k$$
 For $i = 1$, $\epsilon_{1jk} \nabla_j v_k = \nabla_2 v_3 - \nabla_3 v_2 = 0$; for $i = 2$, $\epsilon_{2jk} \nabla_j v_k = \nabla_3 v_1 - \nabla_1 v_3 = 0$; for $i = 3$, $\epsilon_{3jk} \nabla_j v_k = \nabla_1 v_2 - \nabla_2 v_1 = 1 - 4 = -3$. So answer is $-3\hat{z}$.

(b) evaluate $\int \vec{V} \cdot d\vec{r}$ from the origin (0,0,0) to (1,1,1) along the line $x = t, y = t^2, z = t^3$.

Since curl $\vec{v} \neq 0$, integral depends on path in general.

$$\int \int \int_{0,0,0}^{1,1,1} (4y\hat{i} + x\hat{j} + 2z\hat{k}) \cdot (dx\hat{i} + dy\hat{j} + dz\hat{k}) = \int_{0}^{1} (4t^{2}dt + t \cdot 2tdt + 2t^{3} \cdot 3t^{2}dt)$$
$$= 6 \left[\frac{1}{3}t^{3} + \frac{1}{6}t^{6}\right]_{0}^{1} = 3$$
(18)

$$\vec{\nabla}\psi = -(x, y, z)/(x^2 + y^2 + z^2)^{3/2} = -\frac{\vec{r}}{r^3}$$
 (19)

and

$$\vec{\nabla} \times \vec{\nabla} \psi = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \partial_x & \partial_y & \partial_z \\ \partial_x \psi & \partial_y \psi & \partial_z \psi \end{vmatrix},$$
(20)

which vanishes by equality of mixed partial derivatives. You can also do this problem with ϵ_{ijk} notation if you like.

8. (Extra credit.) Calculate the radii of convergence of the following series:

(a)

$$\sum_{n=1}^{\infty} \frac{(nx)^n}{n!} \tag{21}$$

Use ratio test:

$$\rho_n = \left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{(n+1)^{n+1} x^{n+1}}{(n+1)!} \frac{n!}{n^n x^n} \right|$$
(22)

$$= \frac{|x|(n+1)^n}{n^n} = |x| \left(1 + \frac{1}{n}\right)^n$$
(23)

$$\rho = \lim_{n \to \infty} \rho_n = |x| \lim_{n \to \infty} \left(1 + \frac{1}{n} \right)^n = |x|e$$
(24)

(b)

$$\sum_{n=1}^{\infty} \frac{x^n}{n^2 + 1} \tag{25}$$

Use ratio test:

$$\rho_n = \left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{x^{n+1}}{n^2 + 2n + 2} \frac{n^2 + 1}{x^2} \right| = |x| \frac{n^2 + 1}{n^2 + 2n + 2}$$
(26)

$$\rho = \lim_{n \to \infty} \rho_n = |x| < 1 \tag{27}$$