

2021 P3

$$1) \text{ BC: } f_{\text{left}}(x=0, t) = f_{\text{right}}(x=0, t) \quad (1)$$

$$\left. \frac{\partial f_{\text{left}}}{\partial x} \right|_{x=0} = \left. \frac{\partial f_{\text{right}}}{\partial x} \right|_{x=0} \quad (2)$$

$$(1) \Rightarrow f_I(0, t) + f_R(0, t) = f_T(0, t)$$

or

$$f_I(-v_1 t) + f_R(+v_1 t) = f_T(-v_2 t) \quad (3)$$

For all 3 waves  $\frac{\partial f}{\partial x} = -\frac{1}{v} \frac{\partial f}{\partial t}$ . So (2)  $\Rightarrow$

$$-\frac{1}{v_1} \frac{\partial f_I}{\partial t} + \frac{1}{v_1} \frac{\partial f_R}{\partial t} = -\frac{1}{v_2} \frac{\partial f_T}{\partial t} \quad \uparrow v < 0 \text{ for } f_R$$

Integrate  $\int dt [C]$

$$-\frac{1}{v_1} f_I(-v_1 t) + \frac{1}{v_1} f_R(+v_1 t) = -\frac{1}{v_2} f_T(-v_2 t) + C, \quad C: \text{constant}$$

or multiply  $(-v_1)$

$$\begin{aligned} f_I(-v_1 t) - f_R(+v_1 t) &= \frac{v_1}{v_2} f_T(-v_2 t) - v_1 C \\ &= \frac{v_1}{v_2} f_T(-v_2 t) - C' \quad (4) \quad C' = v_1 C \end{aligned}$$

Add (3) + (4)

$$2f_I = \left(1 + \frac{v_1}{v_2}\right) f_T - C'$$

$$f_I = \frac{1}{1 + \frac{v_1}{v_2}} (2f_T + C')$$

$$f_I = \frac{2v_2}{v_1 + v_2} f_T + \frac{v_2 C'}{v_1 + v_2}$$

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Subtract (3) - (4)

$$2f_R = \left(1 - \frac{v_1}{v_2}\right) f_T + c'$$

substitute for  $f_T$ 

$$2f_R = \left(1 - \frac{v_1}{v_2}\right) \frac{2v_2}{v_1 + v_2} f_I + \left(1 - \frac{v_1}{v_2}\right) \frac{v_2 c'}{v_1 + v_2} + c'$$

$$f_R = \frac{v_2 - v_1}{v_1 + v_2} f_I + \frac{v_2 - v_1}{2(v_1 + v_2)} c' + \frac{c'}{2}$$

$$= \frac{v_2 - v_1}{v_2 + v_1} f_I + \frac{v_2 - v_1 + v_1 + v_2}{2} \frac{c'}{v_1 + v_2}$$

$$= \frac{v_2 - v_1}{v_2 + v_1} f_I + \frac{v_2}{v_2 + v_1} c'$$

Let  $c'' = C = \frac{v_2}{v_2 + v_1} c'$  if you want

2. For any function  $f(x-ct)$  I'll have

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} \quad u = x-ct \quad \frac{\partial u}{\partial x} = 1$$

$$= \frac{\partial f}{\partial u} = f' \quad \text{also} \quad \frac{\partial f}{\partial y} = 0 = \frac{\partial f}{\partial z}$$

$$\nabla \cdot \vec{E} = 0 \Rightarrow \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} = \frac{\partial f}{\partial x} = \frac{\partial f}{\partial u} = 0 = \frac{\partial f}{\partial u}$$

$f' = 0 \Rightarrow f_x = \text{const}$   $f_x'' = 0$   $f_x$  is not a solution  
because  $f_x \neq f(x-ct)$

$\nabla \cdot \vec{B} = 0$  same  $\Rightarrow$   $g_x$  is not a solution.

So now I have

$$\vec{E} = \hat{y} f_y + \hat{z} f_z \quad \vec{B} = \hat{y} g_y + \hat{z} g_z$$

Moreover  $\nabla \times \vec{E} = -\hat{x} f_z' + \hat{y} f_z'$  (only terms with  $\frac{\partial}{\partial x}$ )

$$\nabla \times \vec{B} = -\hat{z} g_z' \hat{y} + \hat{z} g_y' \hat{x}$$

For any  $f(x-ct)$  I'll have

$$\frac{\partial f}{\partial t} = -c \frac{\partial f}{\partial u} = -c f' \quad \text{because} \quad \frac{\partial u}{\partial t} = -c$$

Thus  $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$  becomes

$$-\hat{y} f_z' + \hat{z} f_y' = -\frac{\partial}{\partial t} (-\hat{z} g_z' \hat{y} + \hat{z} g_y' \hat{x}) = \frac{c}{c} (\hat{y} g_z' + \hat{z} g_y')$$

$$\text{So } -\hat{y} f_z' = \frac{c}{c} \hat{y} g_z' \quad f_y' = \frac{c}{c} g_y'$$

$$\nabla \times \vec{B} = \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$-\hat{z} g_z' = -\frac{c}{c} \hat{z} f_z' + \frac{1}{c} \hat{z} g_y' = -\frac{c}{c} \hat{z} f_z'$$

substitute  $f_y'$

$$-\frac{1}{c} \hat{z} g_z' = -\frac{c}{c} \hat{z} f_z' \quad \text{or} \quad 1 = \frac{c^2}{c^2} \Rightarrow c = c$$

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$$g_y' = -f_z' \quad g_z' = f_y'$$

Integrate  
with c

$$g_y = -f_z$$

$$g_z = f_y$$

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3 Maxwell's eqns are

$$\nabla \cdot \vec{E} = \frac{1}{\epsilon_0} \rho \quad \nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Let's do  $\nabla \times (\nabla \times \vec{E})$  first,  $\epsilon_0 \mu_0 = \frac{1}{c^2}$ 

identity  $\left( \begin{array}{l} \nabla \times (\nabla \times \vec{E}) = -\frac{\partial}{\partial t} \nabla \times \vec{B} \\ \nabla (\nabla \cdot \vec{E}) - \nabla^2 \vec{E} = -\frac{\partial}{\partial t} (\mu_0 \vec{J}) - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} \end{array} \right)$  Maxwell

but  $\nabla \cdot \vec{E} = \frac{1}{\epsilon_0} \rho$

so  $\boxed{\frac{1}{\epsilon_0} \nabla \rho + \mu_0 \frac{\partial \vec{J}}{\partial t} = \nabla^2 \vec{E} - \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2}}$

similarly  $\nabla \times (\nabla \times \vec{B})$  becomes

$\left( \begin{array}{l} \nabla \times (\nabla \times \vec{B}) = \mu_0 \nabla \times \vec{J} + \mu_0 \epsilon_0 \frac{\partial}{\partial t} \nabla \times \vec{E} \\ \nabla (\nabla \cdot \vec{B}) - \nabla^2 \vec{B} = \mu_0 \nabla \times \vec{J} + \mu_0 \epsilon_0 \left( -\frac{\partial^2 \vec{B}}{\partial t^2} \right) \end{array} \right)$  Maxwell

but  $\nabla \cdot \vec{B} = 0$

so  $\boxed{-\mu_0 \nabla \times \vec{J} = \nabla^2 \vec{B} - \frac{1}{c^2} \frac{\partial^2 \vec{B}}{\partial t^2}}$

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$$4) \langle E \cdot D \rangle = \frac{1}{T} \int_0^T dt \cos(-\omega t + \delta_e) \cos(-\omega t + \delta_d) \quad x=0$$

You can use identities but you can also write  
 $\cos \phi = \frac{1}{2}(e^{i\phi} + e^{-i\phi})$

$$\begin{aligned} \langle E \cdot D \rangle &= \frac{1}{T} \int_0^T dt (e^{i(\delta_e - \omega t)} + e^{i(\omega t - \delta_e)}) (e^{i(\delta_d - \omega t)} + e^{i(\omega t - \delta_d)}) \\ &= \frac{1}{4T} \int_0^T dt (e^{i(\delta_e + \delta_d - 2\omega t)} + e^{i(2\omega t - \delta_e - \delta_d)} + e^{i(\delta_e - \delta_d)} \\ &\quad + e^{i(\delta_d - \delta_e)}) \\ &= \frac{1}{4T} \int_0^T dt [2 \cos(\delta_e + \delta_d - 2\omega t) + 2 \cos(\delta_e - \delta_d)] \end{aligned}$$

$$\frac{1}{T} \int_0^T \cos(A + t + \phi) dt = 0$$

$$\begin{aligned} \langle E \cdot D \rangle &= \frac{1}{2T} \cos(\delta_e - \delta_d) \int_0^T dt \\ &= \frac{1}{2} \cos(\delta_e - \delta_d) \end{aligned}$$

$$\begin{aligned} b) \frac{1}{2} \operatorname{Re}(E \cdot D^*) &= \frac{1}{2} k e^{i(kx - \omega t + \delta_e)} e^{-i(kx - \omega t + \delta_d)} \\ &= \frac{1}{2} k e^{i(\delta_e - \delta_d)} \\ &= \frac{1}{2} \cos(\delta_e - \delta_d) \end{aligned}$$

$$\begin{aligned} c) \frac{1}{2} \operatorname{Re} E^* D &= \frac{1}{2} \operatorname{Re} e^{-i(kx - \omega t + \delta_e)} e^{i(kx - \omega t + \delta_d)} \\ &= \frac{1}{2} \cos(\delta_d - \delta_e) \\ &= \frac{1}{2} \cos(\delta_e - \delta_d) \end{aligned}$$

$$d) \langle u \rangle = \frac{1}{4} \operatorname{Re} (\epsilon_0 \vec{E} \cdot \vec{E}^* + \frac{1}{\mu_0} \vec{B} \cdot \vec{B}^*) \quad \langle \vec{S} \rangle = \frac{1}{2\mu_0} (\vec{E} \times \vec{B}^*)$$